MODEL UNCERTAINTY AND THE EFFECT OF SHALL-ISSUE RIGHT-TO-CARRY
LAWS ON CRIME

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ABSTRACT

This paper explores the role of model uncertainty in explaining the different findings in the literature regarding the effect of shall-issue right-to-carry concealed weapons laws on crime. In particular, we systematically examine how different modeling assumptions affect the results. We find little support for some widely used assumptions in the literature (e.g., population weights), but find that allowing for the effect of the law to be heterogeneous across both counties and over time is important for explaining the observed patterns of crime. In terms of model uncertainty, we find that there is substantial variation in the estimated effects for each model across all dimensions of the model space. This suggests that one should be cautious in using the results from any particular model to inform policy decisions.

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1. Introduction

Over the last two decades, there has been a dramatic expansion in the ability of US citizens to carry concealed weapons. The US Supreme Court's 2008 District of Columbia vs. Heller decision established a personal right to carry arms. This decision made inevitable that all US states establish "may-issue" laws: laws which defined criteria under which a permit to issue concealed weapons may be obtained. A form of these laws, "shall-issue," which require permits to be issued unless the applicant falls into certain narrow categories, has been adopted by 41 states. 38 of the shall-issue states adopted the law prior to the Supreme Court decision. Shall-issue laws essentially legalize concealed carry for the vast majority of a state's population.

A key part of the policy debates preceding the adoption of shall-issue laws has been the claim that legalization reduces certain crime rates. The theoretical argument is that potential criminals considering crimes such as a street robbery will be deterred based on beliefs about the likelihood that a potential victim is carrying a weapon. Studies of the effects of shall-issue laws have also examined other violent crimes, such as murder and rape. This has been done both because the deterrence logic of concealed carry is generally felt not to hold for these types of crimes, and also because of arguments that concealed carry may increase violent crimes by creating opportunities, e.g., during a disagreement between people who are intoxicated.

Empirical evidence for these claims was initiated in work by Lott and Mustard (1997); other prominent examples of work arguing in favor of a deterrent effect include Lott (2010). This body of work in turn generated a set of studies which concluded that claims of a deterrence effect were wrong and an artifice of special modeling assumptions; e.g., Black and Nagin (1998), Ludwig (1998), and Ayres and Donohue (2003). While the various participants in this literature have subsequently argued in favor of their assumptions and criticized those of others, these further arguments have not produced any resolution of the conflicting empirical conclusions, nor is there good reason to think that they can. The different assumptions are not grounded in principled behavioral arguments, i.e., substantive assumptions about economic theory; nor do they

involve statistical distinctions for which there is a logical basis for preferring one approach to another.

This paper attempts to understand the conflicting claims in the concealed carry literature. We do this by systematically exploring how different modeling assumptions are linked to different findings on shall-issue's effect on crime. In contrast to the standard practice in the literature, we do not, ex ante, privilege any particular model. We are concerned with the relative evidentiary support for a given model, as well as the crime effect found through model averaging, but our primary objective is to explore the evidentiary support across a set of models and to understand which assumptions do and do not matter. Our analysis identifies a set of categories which span much of the existing concealed carry literature. These assumptions range from specification of the nature of the policy effect, to choices of control variables, to heteroskedasticity corrections, to formulations of potential parameter heterogeneity, to choices of instrumental variables. A major goal is to understand how these assumptions determine the disparate findings in the literature.

Methodologically, the closest antecedents to this paper are Cohen-Cole, Durlauf, Fagan, and Nagin (2009), Durlauf, Fu, and Navarro (2013), Durlauf, Navarro, and Rivers (2010), which each explore the model space generating conflicting claims about the deterrent effect of capital punishment. This work finds that affirmative claims of deterrence required certain sets of modeling assumptions, which do not have strong evidentiary support in comparison to other models.[1] Bartley and Cohen (1998) also explore robustness and fragility for concealed carry using Leamer's (1983) extreme bounds analysis to adjudicate differences between Lott and Mustard (1997) and Black and Nagin (1998) with respect to choices of control variables. Our analysis considers a much more systematic set of papers and assumptions and focuses on the nature of the heterogeneity in deterrence estimates rather than a robustness analysis per se. Furthermore, we employ Bayesian model averaging rather than extreme bounds

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[1]See Strnad (2007) for a general argument for the importance of accounting for model uncertainty in empirical legal studies.

analysis as the basis for aggregating information across models.[2] Our work attempts to follow the spirit of Leamer (1978), who initiated systematic efforts to account for model uncertainty in evaluating empirical claims, although we do not focus on extreme bounds analysis per se.[3]

The modern literature on model uncertainty has focused on the development of model averaging methods to facilitate statistical inferences which are not model-specific.[4] Eduardo Ley played a foundational role in this work both in helping to develop a statistical framework for Bayesian model averaging (Fernandez, Ley, and Steel (2001a)), as well as early applications (Fernandez, Ley, and Steel (2001b), Fernandez, Ley, and Steel (2002)), which initially focused on the identification of the determinants of heterogeneity in growth rates across countries. Ley's work, in combination with Sala-i-Martin, Doppelhofer, and Miller (2004), provided a constructive way to address model uncertainty which has seen wide application, and hence the dedication. We will employ model averaging methods to summarize our exploration of the model space. However, our main goal is to understand how assumptions determine conclusions on the effects of concealed carry laws.

As the concealed carry literature is based on observational data, the research may be subjected to the standard critiques that are made by advocates of randomized controlled trials and natural experiments as the gold standard for empirical social science. A National Academy of Sciences report, *Firearms and Violence* (Wellford,

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[2]Brock, Durlauf, and West (2003) discuss why model averaging has better decision-theoretic foundations.

[3]Lott (2010) includes a broader set of control variables than we do, but eschews any formal methods for incorporating model uncertainty in deterrence estimates (pg. 186). Lott's discussion conflates extreme bounds analysis with model uncertainty assessment. While we concur with his concerns about informal sensitivity analysis, we disagree with the rejection of systematic evaluation of deterrence effect variation across a well-defined model space. In fairness to Lott, there is much informal robustness analysis, in the sense of consideration of multiple specifications. Further, he is willing to argue the merits of assumptions in a way that, in our language, corresponds to dogmatic priors on the model space. Our approach complements his as we can show which assumptions drive certain findings and which do not.

[4]Draper (1995) and Raftery, Madigan, and Hoeting (1997) are seminal contributions from statistics; see Doppelhofer (2008) for a concise overview of applications in economics.

Pepper, and Petrie (2004)), expressed deep pessimism about the possibility that observational data would be able to resolve the effect of shall-issue laws

"…with the current evidence it is not possible to determine that there is a causal link between the right to carry laws and crime rates…It is also the committee's view that additional analysis along the lines of the current literature is unlikely to yield results that will persuasively demonstrate a causal link between right-to-carry laws and crime rates (unless substantial numbers of states were to adopt or repeal right-to-carry laws), because of the sensitivity of the results to model specification." (pg. 150-151)

This claim led one of the members of the panel, the eminent criminologist James Q. Wilson, to dissent from the report, which is extremely rare. Wilson's decision to dissent is primarily based on his objections to the report's claims that the concealed carry literature was uninformative. Specifically, he criticizes the report for making this conclusion based on the conflicting results on the effects of legalization generated by models with and without controls. Wilson argues that models without controls, even if they contradict other models, are intrinsically uninteresting.

"Suppose Professor Jones wrote a paper saying that increasing the number of police in a city reduced the crime rate and Professor Smith wrote a rival paper saying that cities with few police officers have low crime rates. Suppose that neither Smith nor Jones used any control variables, such as income, unemployment, population density, or the frequency with which offenders are sent to prison in reaching their conclusions. *If* such papers were published, they would be rejected by the committee out of hand for the obvious reason they failed to produce a complete account of the factors that affect the crime rate." (pg. 270)

Wilson's dissent, in turn, invoked the rejoinder

"…Everyone (including Wilson and the rest of the committee) agrees that control variables matter, but there is disagreement on the correct set. Thus the fact that there is no way to statistically test for the correct specification and that researchers using reasonable specifications find different answers are highly relevant. Given the existing data and methods, the rest of the committee sees little hope in resolving this fundamental statistical problem." (pg. 273-274)

As discussed in Durlauf, Navarro, and Rivers (2008), Wilson has the stronger side of the argument. With reference to model uncertainty, model averaging and related methods can constructively address the issues raised by the majority in the report. And of course, one can just as easily criticize assumptions implicit in randomized trials. Our position, which follows the spirit of Heckman (2005), is that there is no single privileged type of empirical strategy in economics, which does not mean that methodological arguments are vacuous, but rather that judgments need to be exercised with respect to assumptions.

Our empirical findings may be summarized as follows. One assumption in the literature, the use of population weights to control for heteroskedasticity in crime rates, has so little evidentiary support that it is reasonably excluded from the analysis. For the remaining assumptions, the effects of the law on crime range across positive and negative values. With partial exceptions involving the specification of the way that shall-issue law effects are measured and whether the laws are treated as endogenous, there is no simple one-to-one mapping between any one assumption and uniformly positive or negative set of estimates conditional on the assumption. Together, the full range of assumption disagreements matter for the disagreements in conclusions.

We also employ model averaging to provide a summary evaluation of the model-specific estimates that we study. Bayesian model averaging combines priors over the model space, with a measure of data fit, to generate posterior probabilities for each model, which are used to weight models in computing effects averaged across models.

Interestingly, conditional on a uniform prior on the model space, the posterior model probabilities are almost entirely concentrated on a single model for both property and violent crimes, although the models turn out to differ.[5] For property crime, the model-averaged point estimates imply a negative (deterrent) effect on crime in the short run, but a positive and increasing effect on crime in the long run. For violent crime, the results indicate positive effects on crime in both the short- and long-run.

Model averaging can help summarize, or in this case essentially eliminate, the large degree of uncertainty associated with the choice of a model. However, this

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[5]But see Section 9, where we discuss sensitivity to the choice of priors and how this affects which models receive non-negligible weights.

approach judges models based on the measure of fit implicit in the calculation of posterior model probabilities, a decision rule that not all researchers/policymaker will agree with. There is also likely to be disagreement over the selection of priors.

Absent other formal rules for either aggregating information over models, or for selecting a particular model, the large degree of variation in estimated effects across models implies that one should be cautious in using the results from any one particular model to guide policy decisions. Put differently, a researcher/policymaker needs to be very convinced that there is a strong basis for the particular model (or models) selected, and for their associated assumptions. By the standard of Leamer's extreme bounds analysis, in which changes of sign across a model space are equated to fragility, there is no assumption that can avoid fragility per se, although one assumption gives most effect estimates the same sign.

2. Model uncertainty and policy effects: basic ideas

Our objective in this analysis is to explicitly incorporate model uncertainty into descriptions of the evidentiary support for a given empirical claim. The standard approach to policy evaluation, abstractly, is simply the construction of the posterior probability for outcome o conditional on policy p, data D, and a model m,

$$\Pr\left(o|D,p,m\right) \tag{1}$$

This distribution can be used to compute first and second moments $E\left(o|D,p,m\right)$ and $\mathrm{var}\left(o|D,p,m\right)$, as well as the posterior probability of the data, which provides a measure of goodness of fit:

$$\Pr\left(D|p,m\right). \tag{2}$$

Models may be understood as collections of assumptions which together provide a statistical specification (see Brock and Durlauf (2014) for elaboration). The new model uncertainty literature can be understood as relaxing the conditioning in equations (1) and (2) on a single model and providing new ways to report evidence on policy effects. Instead of a single model, one employs a set of candidate models, M; elements m of this set are differentiated by the assumptions from which they are constituted. From this perspective, the identity of the "true" model is one of the unobservables for which an analyst must account in drawing inferences. Further, the true model is itself of no intrinsic interest. The objective of a policy analysis is solely to evaluate the effect of the law on criminal behavior.

When assumptions are justified by economic or econometric theory, then it is of course appropriate to condition empirical conclusions on them. If such *a priori* information exists, then a researcher is justified in employing a dogmatic prior on the model space, i.e., assigning $\Pr(m) = 1$ to some model. Similarly if some assumptions warrant a prior probability 1, then those models which contradict these assumptions should receive prior probability 0. However, for a context such as concealed carry and crime, the differences in modeling assumptions which have been used in competing analyses do not, as we argue below, admit resolution on an *a priori* basis. While arguments can be made in favor of or against particular assumptions, the models in the literature are all plausible candidates for the crime process.

This general critique of the use of a single model applies to the concealed carry literature at several levels. First, it means that there is no principled basis for functional form assumptions or for the choice of control variables that are found in a given model. Becker's (1968) deterrence model involves the marginal costs and benefits of a potential crime, but is mute on the forms of the cost and benefit functions, nor does the theory say anything about their determinants. Choices of functional forms and control variables involve judgments. Second, uncertainty exists with respect to the validity of instruments. Unsurprisingly, a number of crime determinants are endogenous and so instruments are used to account for correlation between them and the unobserved heterogeneity in crime rates across localities. However, the absence of a principled

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basis for constructing the crime model means that the literature has relied on ad hoc informal arguments for the validity of particular instruments.

A third problem is that there is no reason to think that the parameters of a crime regression should be invariant to other characteristics (either measured or unmeasured) of the polities, i.e., it is not clear whether data taken across localities obeys the needed exchangeability assumptions which underlie analyses based on common coefficients.[6] It is easy to identify reasons for parameter heterogeneity. For example, Southern states where people are taught at early ages how to handle weapons, and where guns are very much a part of the culture; and Northeastern states where guns are not common among regular citizens, can be expected to exhibit different coefficients in a crime regression that includes variables such as the conditional probability of arrest given crime commission, gun prevalence, or the presence of a concealed weapons carry law. The Lucas (1976) critique, further, can be argued to imply that the parameters in a regression of the type employed in the concealed carry literature will depend on the polity's criminal sanction regime.

All of these issues suggest that model uncertainty is likely to play a key role in crime regressions. In this respect, the literature on shall-issue carry laws is more of a demonstration of sensitivity of policy effect calculations to model assumptions than a body of work from which conclusions may be drawn. In fact, if the deterrent effects are estimated because of their use in policy evaluation, decision theory requires that model uncertainty be part of the appropriate loss function calculation.

Model averaging, when the loss function does not depend on the "true" model, can provide a sufficient characterization of policy effects for policy comparisons if the policymaker is solving a standard statistical decision problem with uncertainty; see

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[6]A collection of random variables $\{x_1,...,x_n\}$ is exchangeable if the "labels" associated with each variable (i.e., the subscripts) are irrelevant to describe their dependence. That is, if $\Pr(x_1,...,x_n) = \Pr(x_{\pi(1)},...,x_{\pi(1)})$ for all permutations π defined on the set $\{1,..,n\}$. Hence, if the collection is i.i.d., it is exchangeable; but the converse need not be true. We emphasize exchangeability since we believe that it captures the idea that the social science commitments of a researcher, by choice of modeling assumptions, reduce unobserved heterogeneity to random variables on which one is willing to assume some form of symmetry in their joint density; see Brock and Durlauf (2001).

Brock, Durlauf, and West (2003) for a formal argument and elaboration. Averaging across models takes place by first calculating the posterior probability of the data:

$$\Pr(D|p,m) = \int \Pr(D|p,m,\theta_m)\Pr(\theta_m|p,m)d(\theta_m). \tag{3}$$

Equation (3) is often referred to as the integrated likelihood or as the marginal likelihood. The right hand side of equation (3) makes it clear that the marginal likelihood's measure of fit consists of two parts: the fit of the model to the data as described by the data likelihood conditional on the parameters ($\Pr(D|p,m,\theta_m)$), and the prior probability that the parameters actually takes this value ($\Pr(\theta_m|p,m)$). Notice that, while increasing the number of parameters will increase the posterior probability of the data by increasing the likelihood, it will decrease it by increasing the number of terms in the prior. For this reason, we refer to the fit measured by the marginal likelihood as "complexity-penalized fit".

The posterior probability for each model can then be computed as

$$\Pr(m|D,p) = \frac{\Pr(D|p,m)\Pr(m)}{\sum\limits_{j\in M}\Pr(D|p,j)\Pr(j)}, \tag{4}$$

for some model priors $\Pr(m)$. The model-averaged policy effect is then obtained by weighting the estimated policy effects for each model (i.e., the outcome o) by the posterior probability for each model,

$$E(o|D,p) = \sum\limits_{m\in M} E(o|D,p,m)\Pr(m|D,p). \tag{5}$$

Its variance follows from

$$Var(o \mid D, p) =$$

$$\sum_{m \in M} \left[Var(o \mid D, p, m) + E(o \mid D, p, m)^2 \right] Pr(m \mid D, p) - E(o \mid D, p)^2. \tag{6}$$

There are good reasons, however, why averaging using the posterior probabilities in (4) across models may not be sufficient for an analysis whose objective is to communicate evidence on policy effects. One reason concerns the specification of the priors on the model space. We regard this as a qualitatively different problem from the specification of priors for model-specific parameters. Why? While we have argued that there are not good reasons to possess dogmatic priors based on economic or statistical theory, at least for the context we study, this claim does not speak to the issue of how to construct priors for the model space.

Consider the case in which there is model uncertainty depending on whether one assumes rational or adaptive expectations in an environment. Different economists would have very different priors based on the totality of social science knowledge each possesses, or because each evaluates a common knowledge set differently in terms of its implications for which model is correct. While the concealed carry literature does not contain such stark disagreements on economic principles, authors have made principled arguments in favor of various assumptions, which means that priors over the model space would range widely. The judgments which underlie an element of a model space reflect different views on assumptions, so while it may be reasonable to ask a policymaker to relax a dogmatic model space prior, it is not reasonable to expect him to only be interested in results in which assumptions or their negation receive equal *a priori* weight.

Second, the literature on model robustness (Hansen and Sargent (2007)) has given reasons to believe that preferences can exhibit ambiguity aversion with respect to model uncertainty. In such cases, the worst case scenario for a policy will depend on the identity of the true model, which in turn cannot be determined independently from the policymaker's preferences.

Both the classical Bayesian and modern ambiguity-based decision-theoretic approaches differ from the way in which economists typically make policy

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recommendations. By this, we mean that policy implications of alternative models are most often advocated on the basis that one analysis is better than another, which in our language, amounts to a claim that one set of assumptions is preferred to another. Relative to a decision-theoretic approach, these disagreements do not involve formal rules for comparing or aggregating claims across models. Policymakers are unlikely to possess such rules either, let alone the training to compare the merits of different empirical analyses.

These considerations imply that it is valuable to report information about the (unweighted) distribution of policy effects associated with (1) and (2). As first argued in Brock, Durlauf, and West (2007), policy dispersion plots, which visually represent the set of values of a policy effect across a model space, are useful in helping a policymaker to understand policy-effect/model dependence. Durlauf, Fu, and Navarro (2013) extend this idea by creating dispersion plots in which they organize models by classes of assumptions, allowing a reader to identify which assumptions do and do not matter for heterogeneity in model-specific policy effects. For example, a researcher may have dogmatic priors with respect to some assumptions (e.g., use of instrumental variables to address endogeneity of regressors) and so only wish to consider subsets of the model space. The organization of the variety of estimates by broad assumption classes illustrates that different researchers choosing particular models may find (and in our case will find), different answers, even conditional on a subset of assumptions. Hence, while model averaging is a useful way to provide scalar statistics (e.g., moments) for a policy effect, we believe policy dispersion plots are valuable as well.

3. Model space

As we have emphasized, the lack of scholarly consensus over the effect of concealed carry laws on crime has centered on differences in the modeling choices employed by various researchers. Since there is essentially an infinite number of modeling choices available to a researcher, we employ the notion of exchangeability as a guiding principle. The basic idea is to consider whether the model selected by the

researcher eliminates enough differences between (sets) of observations, e.g., Alameda county in California and Jackson county in Mississippi, that one can assume that the residuals are no longer a function of the identity of the particular observation. This is not to say that violating exchangeability invalidates a model. Instead, one should consider whether the sources of non-exchangeability invalidate the purpose for which the model was built. Hence, when choosing a model space, we consider aspects like control variable choice, specification of the effect of the law, heterogeneity in the effect of the law both in the cross-section and over time, etc., that may lead to violations in exchangeability that are likely to affect our estimates of the effect of the law on crime.

The model space we consider in this paper takes into account some of the key sources of debate in the literature including modeling how the effect of the law varies over time, controlling for demographics, modeling time trends in crime rates, and dealing with the potential endogeneity of the laws. In addition, we also include some dimensions to the model space that we feel are particularly relevant to the issue, but that have received little or no attention in the literature. This includes the introduction of additional relevant control variables, allowing the parameters of interest to be heterogeneous, dealing with the potential endogeneity of arrest rates, and the use of population weights. Below we discuss each dimension of the model space in detail. In addition to identifying assumptions which differentiate existing papers, we also note some cases in which the literature seems to have ignored some natural variations of those specifications which have appeared so far.

i.   formulation of shall-issue laws as a crime determinant

Perhaps surprisingly, there has been disagreement in the literature as to the formulation of the impact of shall-issue laws in the statistical crime model. These disagreements depend on how one characterizes the dynamic effects of legalization. The first part of the literature identified concealed carry effects using a dummy variable to indicate whether the law is in place or not in a given location-time pair. This specification has a substantive implication, as it entails that the introduction of the law generates a permanent shift up or down in the crime rate. However, suppose that crime

rates were increasing in a location prior to the implementation of the law. Suppose further that the effect of the law was to reverse this trend, generating a subsequent decreasing rate of crime. If one just measured crime before and after the introduction of the law, average crime rates would be similar, leading to the incorrect conclusion that the law had little or no effect on crime.

An alternative to the dummy variable model that seeks to account for this possibility is to allow for different time trends in crime before and after the law. This approach has been used in John Lott's work (Lott and Mustard (1997), Lott (2010)), and has been referred to in the literature as the "spline" model (Ayres and Donohue (2003)). If we let $Y_{i,t}$ denote the log of the crime rate in county i at time t, and let t_0 denote the time at which the law is implemented, a (very basic) spline model can be written as

$$Y_{i,t} = (t - t_0)\left[1(t_0 > t)\pi_b + 1(t_0 < t)\pi_a\right] + \epsilon_{i,t}. \tag{7}$$

Here π_b and π_a measure the trends before and after the law is implemented.

The spline model of equation (7) allows for pre- and post-law trends. However, it does not allow for the law to have any immediate impact on crime. As a response, a "hybrid" specification proposed by Ayres and Donohue (2003) incorporates both the trends of the spline model as well as the discrete shift allowed by the dummy model.

These two models are an attempt to account for differing temporal effects of the law in order to improve on the pure dummy model. However, they both have the feature that, as time elapses, the trend will keep pushing crime either up or down indefinitely. As we illustrate next, this feature can lead to paradoxical results.

Take the example in Figure 1 which shows a case in which crime rates are decreasing, then the law is implemented, the trend flattens and after a few years the trend flattens even more. The real effect of the law is that it worsens crime (since it was decreasing at a higher rate before the law was implemented) in the short run, and makes it even worse in the long run.

How will a hybrid trend specification behave relative to this hypothetical pattern? The pre-law trend will match exactly the real trend, but the post-law trend will

overestimate the effect in the short run and underestimate it in the long run. More importantly, the dummy will show an immediate shift to a lower crime rate, i.e., it will show that the law decreased crime immediately, even though the only effect of the law is to worsen crime both in the short run and in the long run. The point we want to illustrate is that one should be very careful when interpreting estimates from these models, a task that gets even harder once the effect of the law is allowed to depend on other variables as well (as we do in the section on parameter heterogeneity below).

ii. control variables

Another important source of disagreement surrounds the selection of control variables to include in the empirical model.[7] These disagreements involve different types of variables.

It is common to include control variables for socio-economic status, age, and gender, in aggregated empirical analyses of crime. While their inclusion is, abstractly, justified by choice-theoretic models of criminal behavior such as Becker (1968), there are many potential measures of these underlying characteristics which are available for use, and theory does not provide guidance on how to proceed. For example, Lott includes a set of variables measuring the proportion of people in each county-year pair that fall into different bins defined by race (white, black, and other), gender, and age (divided into six groups).[8] In contrast, Ayres and Donohue (2003) argue that the number of such variables is excessive due to these variables being highly collinear and suggest including only the subset pertaining to black and white males, since these groups contribute to the vast majority of crime. They find that limiting the set of demographic controls causes significant changes in the estimated effect of gun laws on crime, and in some instances leads to a change in the sign of the effect.

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[7]For a discussion of these issues related to measuring the effect of the death penalty on murder see Cohen-Cole, Durlauf, Fagan, and Nagin (2009), and Durlauf, Fu, and Navarro (2013).

[8]For example, one such bin would be "black, female, and between the ages of 20 and 29", and the value would be between 0 and 1.

In addition to differences in demographics across localities, there may be other factors related to location that are relevant for explaining crime rates. For example, attitudes towards gun safety, violence, or even gun usage in general may differ across various parts of the country. County-level fixed effects are one way to control for these differences, and are commonly included in empirical models. However, fixed effects do not capture any time-varying differences across counties. In order to address this, we consider two additional variables that vary across both county and time and are potentially related to both crime rates and gun control laws: gun prevalence and the level of urbanization.

If one believes that the legalization of concealed weapons has an effect on crime rates, then the same logic justifying this makes it plausible that the prevalence of guns in the population directly affects crime. Since the presence of shall-issue laws and the degree of gun prevalence might be correlated, one may want to include a measure of gun prevalence in the regression equation.

While gun prevalence is not a standard control variable in the literature, there are a few papers that include it. However, as is the case with demographic controls, there is no consensus on the effect of inclusion. Duggan (2001) estimates a positive correlation between gun prevalence and crime rates, but finds that controlling for gun prevalence does not affect the relationship between gun laws and crime. Moody and Marvel (2005) look only at the correlation between gun prevalence and crime, but find no systematic relationship. They attribute the difference between their results and Duggan's to the choice of proxy variable for gun prevalence and differences in the number of control variables for age included in the regressions.

In addition to controlling for gun prevalence, we also expand the model space by introducing a measure of the level of urbanization in a county as a control variable. As is the case with gun prevalence, the degree to which a county is urban or rural may be related to both crime rates and the probability that a concealed carry law is in place.

iii.   time trends

Aggregate crime data often contain low frequency movements which are unexplained relative to the substantive theoretical commitments involved in a crime regression. As a result, there is controversy over how to model this type of unobserved heterogeneity, which involves the specification of time trends.[9] One option is to include time-specific dummy variables that control for changes in crimes rates that affect all localities equally. This allows for full flexibility in how crime rates evolve over time, but does not allow these effects to vary by location. An alternative option is to include region-time trends, which allow for differences across region, at the expense of less flexibility in the time dimension.

iv.   parameter heterogeneity

A fourth source of model uncertainty is parameter heterogeneity. While parameter heterogeneity has not been systematically explored in the concealed carry literature, it has been shown to matter in other crime contexts, e.g., Shepherd (2005). One exception is Black and Nagin (1998) who argue that affirmative evidence that concealed carry reduces crime is sensitive to whether or not data from Florida are included in the analysis. Black and Nagin argue that this sensitivity reflects the effects of the Mariel boatlift on crime rates. Concealed carry legalization in Florida occurs during the post-boatlift crime increase. Black and Nagin attribute the subsequent decrease in crime to the absorption of this population into Florida society and the identification of criminals who came in the boatlift, not concealed carry per se.

Black and Nagin's argument should be understood in the context of whether crime observations from different US counties can be thought of as draws from a common model with fixed parameters.[10] Essentially, the issue is whether, after controlling for a large set of variables, one should assume that the effect of concealed carry on crime is independent of the identity of the observation. For example, should one assume that the effect of the law is the same for county-time pairs where gun

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[9]See Durlauf, Navarro, and Rivers (2008) for further discussion.
[10]Brock and Durlauf (2001) provide an analysis of parameter heterogeneity as an example of an exchangeability violation and discuss how such violations can, if not accounted for, create spurious policy conclusions.

prevalence is very large as for county-time pairs in which there are few guns amongst the population?

The vast majority of the literature implicitly assumes that the effects of a policy, in this case shall-issue laws, are the same for all states and counties, in all time periods.[11,12] However, the response of crime rates to these laws may depend on a number of factors. We consider three factors that we believe could create heterogeneity in the effects of gun laws.

First, we allow for the laws to have differing effects depending on the level of urbanization in a county. Response to the laws may be very different in rural versus urban areas. For example, in rural areas, since people are more spread out, there may be fewer confrontations involving weapons. It may also be the case that in rural areas people know each other better, and therefore are more informed about who has a weapon and who does not, potentially altering the benefit of having a concealed weapon.

We also include a specification that allows for the effects of the laws to vary by region. Some regions may have differing attitudes regarding the use and safety of firearms, which could lead to different effects of the law.

Finally, we allow for the effects of the laws to depend on the prevalence of guns in a county. Since shall-issue laws allow individuals to carry concealed weapons, these laws could have a very different effect in areas with very few guns to begin with, compared to areas with many guns. For example, allowing people to carry concealed weapons in a place where gun prevalence is very low might have a small effect on crime as very few people have guns. From the perspective of a criminal, the probability of ending up in a confrontation with an armed victim is minimal, even if they are allowed to carry concealed weapons in principle.

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[11]Examples of papers which allow for parameter heterogeneity in a crime context are Black and Nagin (1998), Shepherd (2005), Durlauf, Navarro, and Rivers (2010), and Durlauf, Fu, and Navarro (2013).

[12]The spline and hybrid models discussed above allow for the law to affect the linear trend in crime rates, but do not allow the effect to depend on calendar time, nor do they allow for non-linear trends.

v.   instrumental variables

The concealed carry literature has attempted to address the endogeneity of the timing of legalization. Intuitively, relatively high (or low) crime rates may have determined which laws are passed, and not the other way around. We follow the convention in the literature and use the Republican vote share in the most recent presidential election to instrument for the laws.[13]

An additional concern that has received less attention in the literature is that the arrest rates for various crimes may also be endogenously determined. For example, if a county experiences an increase in the rate of a given crime, it may find it more difficult to find and arrest the perpetrators of those crimes with a given set of police resources. Alternatively, a county may respond to an increase in crime by allocating additional resources towards catching criminals. In either case, arrest rates would be endogenous.

In order to control for the endogeneity of arrest rates, we employ an instrumental variable strategy that is common in other literatures, particularly industrial organization, but to our knowledge has not been applied in crime contexts. We use the so-called Hausman-Nevo instruments (see Hausman (1995) and Nevo (2001)). These instruments exploit the panel structure of the data, and are constructed as a function (often the average) of the endogenous variable in other locations. In our context, we implement this in the following way. For each county-time pair, we compute the average arrest rate in all regions of the US in that period, excluding the region in which that county is located.

The identifying assumption behind this instrumental variable strategy is that arrest rates for a given type of crime are correlated across different counties (for instance, it may be easier to catch perpetrators of certain types of crimes), but the arrest rates in other regions of the US do not endogenously respond to variation in the local crime rate.

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[13]The Republican vote share is used extensively in the literature as an instrument for shall-issue laws, e.g., Lott and Mustard (1997), Ayres and Donohue (2003), among many others.

vi. population weights

Our final form of model uncertainty centers on population weights. The use of population weights has become standard practice in empirical crime studies. There are various reasons for why one may want to include weights,[14] but the usual argument is based on concern regarding heteroskedasticity of the residuals. The intuition for wanting to weight aggregate observations (typically at the state or county level) is the following. Consider a simple linear probability model for the probability an individual j in county i in period t commits a crime $\rho_{j,i,t}$:

$$\rho_{j,i,t} = X'_{j,i,t}\beta + \eta_{j,i,t}, \tag{8}$$

where $X_{j,i,t}$ is a vector of observable characteristics, and $\eta_{j,i,t}$ is a mean-zero error term with variance σ^2. If we average this equation over individuals within each county and period, we obtain the following model for the county-time-specific crime rate:

$$P_{i,t} = \frac{\sum_{j=1}^{N_{i,t}} \rho_{j,i,t}}{N_{i,t}} = \overline{X}'_{i,t}\gamma + \varepsilon_{i,t}, \tag{9}$$

where $\overline{X}'_{i,t} = \dfrac{\sum_{j=1}^{N_{i,t}} X'_{j,i,t}}{N_{i,t}}$ and $N_{i,t}$ is the number of individuals in county c in period t.

Since the residual in this new equation is given by $\varepsilon_{i,t} = \dfrac{\sum_{j=1}^{N_{i,t}} \eta_{j,i,t}}{N_{i,t}}$, its variance will be given by $\dfrac{\sigma^2}{N_{i,t}}$. The aggregate residual, the one obtained by running county-level panel data

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[14]See Solon, Haider, and Wooldridge (2013) for a useful discussion of the various justifications for using weights and the misapplication of weights in empirical work.

regressions, is therefore heteroskedastic in proportion to the county population. Weighting by population makes the residual homoskedastic and generates the correct standard errors in a regression.

There are two problems with this argument. First, it ignores the possibility that location-time-specific unobservables are present, which we denote as $\Lambda_{i,t}$. With individual-level data, we could directly control for this form of heterogeneity using distinct location-specific, time-specific, and location-time-specific fixed effects. However, since we only observe county-level aggregate data, unobserved determinants of the crime rate that vary by location and over time, such as unmeasured demographic and socio-economic factors, as well as any other crime-related policy changes will enter the error term via $\Lambda_{i,t}$. Adding them to equation (9) gives us the following equation for the county-level crime rate:

$$P_{i,t} = \overline{X}'_{i,t}\, \gamma + v_{i,t}, \qquad\qquad (10)$$

where $v_{i,t} = \Lambda_{i,t} + \varepsilon_{i,t}$. Since the average population in a county is over 100,000, and the variance of ε is equal to $\dfrac{\sigma^2}{N_{i,t}}$, the variance of ε will tend to be quite small. Therefore, unless the variation in county-level unobservables is extremely small in relation to variation in individual unobservable determinants of crime, the variance of error term in equation (10) will be dominated by the variance of $\Lambda_{i,t}$. Consequently, the use of population weights will overweight observations from more populous counties, leading to invalid confidence intervals, and potentially misleading point estimates.

The second problem is that in the majority of the literature on the effects of shall-issue right-to-carry laws (and in the models we consider in this paper), the crime rate is measured in logs, not in levels. Therefore the intuition described above no longer applies because the error in the aggregate crime equation is no longer a simple average of the underlying individual errors. For these two reasons we also consider models that do not use population weights.

Our model space consists of all possible combinations of the model elements described above. The size of the model space is then the product of the dimensions of each element: formulation of the law's effect on crime (3), demographic controls (2), additional covariates (3), time effects (2), parameter heterogeneity—none, gun prevalence (GP), urban, region, GP and urban, GP and region (6), IV/non-IV (2), and population weights (2), for a total of 864 models.

When we include interactions between the effect of shall-issue laws with gun prevalence, urbanization, and region we also separately include these variables as controls. As a result some models already contain the additional covariates (gun prevalence and urban dummies).[15] This leaves us with 624 distinct models, for each property and violent crime. In order to organize our discussion of the model space, we first define a baseline model and then fill out the model space by considering deviations from this baseline in each possible dimension. See Figure 2 for a characterization of the model space.

All models employ the log of the crime rate per 100,000 people as the dependent variable. Covariates which always appear are a measure of the shall-issue law, the arrest rate, socio-economic controls, age and race controls, time effects, and county fixed effects. All of the models under consideration are variations of this baseline specification:[16]

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[15]Region dummies are already implicit in every model given the presence of county-level fixed effects.

[16]For the instrumental variables models, we also have equations corresponding to the endogenous regressors:

$$EndogenousVariable_{i,t} =$$
$$\alpha' InstrumentVector_{i,t} +$$
$$\gamma_1 PovertyRate_{i,t} + \gamma_2 UnemploymentRate_{i,t} +$$
$$\gamma_3 Population_{i,t} + \gamma_4 RealPerCapitaPersonalIncome_{i,t} +$$
$$\gamma_5 RealPerCapitaUnemploymentInsurance_{i,t} +$$
$$\gamma_6 RealPerCapitaIncomeMaintenance_{i,t} +$$
$$\gamma_7 RealPerCapitaRetirementPayments_{i,t} +$$
$$\gamma_8 Age/RaceControls_{i,t} + \sum_t TimeEffects +$$
$$\sum_i CountyEffects_i + v_{i,t}.$$

$$\ln\left(\frac{\#Crimes_{i,t}}{Population_{i,t}\,/\,100{,}000}\right)=$$

$$\beta_1 LawDummy_{i,t} + \beta_2 ArrestRate_{i,t} +$$

$$\gamma_1 PovertyRate_{i,t} + \gamma_2 UnemploymentRate_{i,t} +$$

$$\gamma_3 Population_{i,t} + \gamma_4 RealPerCapitaPersonalIncome_{i,t} +$$

$$\gamma_5 RealPerCapitaUnemploymentInsurance_{i,t} + \qquad (11)$$

$$\gamma_6 RealPerCapitaIncomeMaintenance_{i,t} +$$

$$\gamma_7 RealPerCapitaRetirementPayments_{i,t} +$$

$$\gamma_8 Age\,/\,RaceControls_{i,t} + \sum_t TimeEffects +$$

$$\sum_i CountyEffects_i + \varepsilon_{i,t}.$$

In the baseline model, both the shall-issue laws and the arrest rate are treated as endogenous. As we discussed above, we use the share of people who voted Republican in the most recent presidential election and the average arrest rate in the other regions of the county to instrument for each variable respectively.

4. Implementation

In this section we discuss issues related to estimating all the models contained in the model space described above. Estimation is performed via a MCMC Gibbs sampler. The most general version of the class of models we estimate is an instrumental variables model with county fixed effects and population weights. Since all of the models we consider are special cases of this, we only discuss how to implement the general version that includes all of these features.

Let $i = 1,...,I$ index counties and $t = 1,...,T$ index time. The general version of the model can be written as

$$Y_{i,t} = X'_{i,t}\,\beta + W'_{i,t}\,\alpha + \psi_i + \epsilon_{i,t}, \qquad (12)$$

where the $j = 1,...,J$ elements of $X_{i,t}$ are potentially correlated with $\epsilon_{i,t}$ (i.e., endogenous) while the $h = 1,...,H$ elements of $W_{i,t}$ are assumed exogenous. When we estimate models where the law and the arrest rate are assumed exogenous, we simply make $X_{i,t}$ a subset of $W_{i,t}$. We also assume access to a set of $k = 1,...,K$ instruments $Z_{i,t}$ such that

$$X_{i,t,j} = Z'_{i,t}\,\gamma_j + W'_{i,t}\,\lambda_j + \zeta_{i,j} + \upsilon_{i,t,j} \tag{13}$$

for all j, with both $Z_{i,t}$ and $W_{i,t}$ assumed to be independent of $\upsilon_{i,t,j}$.

Let $Q_{i,t}$ denote the population of county i at time t, and let $q_{i,t} = \sqrt{Q_{i,t}}$.[17] To allow for heteroskedastic errors, we assume that $\epsilon_{i,t} \sim N\left(0, \dfrac{\tau_\varepsilon}{Q_{i,t}}\right), \upsilon_{i,t,j} \sim N\left(0, \dfrac{\tau_{v,j}}{Q_{i,t}}\right)$, jointly independent from ψ, ζ. This allows us to define new random variables $\varepsilon_{i,t} = q_{i,t}\epsilon_{i,t} \sim N(0, \tau_\varepsilon)$ and $v_{i,t} = q_{i,t}\upsilon_{i,t} \sim N(0, \tau_v)$ such that

$$
\begin{aligned}
Y_{i,t} &= X'_{i,t}\,\beta + W'_{i,t}\,\alpha + \frac{\varepsilon_{i,t}}{q_{i,t}} \\
X_{i,t,j} &= Z'_{i,t}\,\gamma_j + W'_{i,t}\,\lambda_j + \frac{v_{i,t}}{q_{i,t}}.
\end{aligned}
\tag{14}
$$

We do not specify anything about the dependence of ψ, ζ on either X, W and/or Z.

To construct the Gibbs sampler, we employ an Empirical Bayes approach (see Casella (1985) for an introduction) in which we first estimate the parameters γ, λ and fix

---

[17]For models that do not include population weights, $Q_{i,t}$ may be set equal to 1 without loss of generality.

them throughout the rest of the analysis.[18] The full details of the algorithm we employ can be found in Durlauf, Navarro and Rivers (2014); here we sketch the basic ideas.

The first step in estimation of the model involves the county fixed effects. Traditional Bayesian approaches deal with fixed effects using a "mixed" effect strategy in which the distribution of the effect is parameterized, allowing it to depend on moments of the distribution of X, W, Z. This approach introduces many additional parameters to estimate, which increases the computational burden, and may lead to imprecision in estimates of the parameters of interest. Furthermore, there is no basis for imposing any particular dependence structure between X, W, Z and ψ, ζ, or making particular distributional assumptions on ψ, ζ. As we discuss below, adopting traditional methods to remove the fixed effects (i.e., within or first differencing), present both implementation and empirical challenges that make them unappealing in our context.

Instead, we introduce a new procedure, which we call "random first differencing", that eliminates the fixed effects by differencing the data with respect to a fixed, but randomly chosen period. To see how this procedure works, let r_i denote a random period in which county i is observed in the data and, for any random variable V, let $V_{i,t}^{\Delta} = V_{i,t} - V_{i,r_i}$. By taking differences with respect to the randomly chosen period r_i, we have

---

[18]An alternative approach is to include an additional block in the Gibbs sampler associated with γ, λ and sample these parameters as well. We chose not to take this approach for two reasons. First, sampling these parameters substantially increases the computation burden, as the dimension of Z and W can be quite large. Second, the marginal likelihood in equation (3) penalizes models with additional parameters. However, the goal of the analysis is to judge models from the perspective of how well they do regarding explaining the crime rate. Hence γ, λ are essentially "nuisance" parameters that should not be considered when judging the model. Our approach avoids the penalty associated with these extra parameters, hence improving the fit of models with many instrumented endogenous variables relative to models with less or none (i.e., OLS).

$$Y_{i,t}^{\Delta} = X_{i,t}^{'\Delta}\beta + W_{i,t}^{'\Delta}\alpha - \frac{\varepsilon_{i,r_i}}{q_{i,r_i}} + \frac{\varepsilon_{i,t}}{q_{i,t}}$$

$$X_{i,t,j}^{\Delta} = Z_{i,t}^{'\Delta}\gamma_j + W_{i,t}^{'\Delta}\lambda_j - \frac{v_{i,r_i}}{q_{i,r_i}} + \frac{v_{i,t}}{q_{i,t}}.$$

(15)

The main advantage of this "random first differencing" procedure is that, if we complete the data and condition on ε_{i,r_i} (and the observed q_i), then $\frac{\varepsilon_{i,t}}{q_{i,t}} - \frac{\varepsilon_{i,r_i}}{q_{i,r_i}}$ will be independent over time, and the same is true for v_j.

By comparison, using the traditional within differencing approach leads to a complicated joint distribution of the errors over time. This substantially increases the computational burden of the algorithm compared to the conditionally i.i.d. data generated by our procedure.

Random first differencing also solves the problem associated with just first-differencing the data when you have a dummy variable that switches only once per county (as we do for the case of the law). In this case, the only identifying power in the data is given by that one period switch in the dummy, causing the researcher to rely on a very small portion of the variation in the data. Our procedure also overcomes the difficulties associated with differencing with respect to a fixed period, in which case the results can be sensitive to the period that is chosen.[19]

In order to deal with the potential heteroskedasticity associated with population weights, we simply pre-multiply the random first differenced data by $q_{i,t}$. Letting $V_{i,t}^{\Delta,q} = q_{i,t}\left(V_{i,t} - V_{i,r_i}\right)$ for any random variable V, the model is given by

---

[19]By doing random first differencing, we are effectively integrating against the distribution of the data, which leads to something that resembles the within differences fixed effect type estimator.

$$Y_{i,t}^{\Delta,q} = X_{i,t}^{'\Delta,q}\beta + W_{i,t}^{'\Delta,q}\alpha - \frac{q_{i,t}}{q_{i,r_i}}\varepsilon_{i,r_i} + \varepsilon_{i,t}$$

$$X_{i,t,j}^{\Delta,q} = Z_{i,t}^{\Delta,q}\gamma_j + W_{i,t}^{'\Delta,q}\lambda_j - \frac{q_{i,t}}{q_{i,r_i}}v_{i,r_i} + v_{i,t}.$$

$$(16)$$

The remaining step for implementation is the specification of priors for the parameters. For the regression coefficients β,α we specify independent normal priors $N(0,\sigma^2)$, with $\sigma^2 = 10$ in our baseline estimates.[20] In order to specify priors for the distributions of the residuals, notice that one can rewrite the crime equation as

$$Y_{i,t}^{\Delta,q} =$$
$$Z_{i,t}^{'\Delta,q}\sum_{j=1}^{J}\gamma_j\beta_j + W_{i,t}^{'\Delta,q}\left(\sum_{j=1}^{J}\lambda_j\beta_j + \alpha\right) - \frac{q_{i,t}}{q_{i,r_i}}\left(\sum_{j=1}^{J}v_{i,r_i}\beta_j + \varepsilon_{i,r_i}\right) + \sum_{j=1}^{J}v_{i,t}\beta_j + \varepsilon_{i,t}.$$

$$(17)$$

Let $v_{i,t,J+1} = \sum_{j=1}^{J}v_{i,t}\beta_j + \varepsilon_{i,t}$ and define $v_{i,t} = \left(v_{i,t,1},\ldots,v_{i,t,J},v_{i,t,J+1}\right)'$ as the $(J+1)\times 1$ vector of SUR residuals for county i at time t. We assume $v_{i,t} \sim N(0,\Pi^{-1})$, where Π is the precision matrix of the SUR equations.[21] Finally, for Π we assume a proper Wishart prior, $\Pi \sim W(b,V)$, set $b = J+2$ and set V to be an identity matrix. The key to deriving our Gibbs sampling algorithm is that, conditional on the random variable pair $\varepsilon_{i,r_i},v_{i,r_i}$, equation (16) is a standard instrumental variables model. The only difference is that we then have to derive the posterior distribution for $\varepsilon_{i,r_i},v_{i,r_i}$. Details of the Gibbs sampling algorithm are given in Durlauf, Navarro and Rivers (2014).

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[20]We scale the data appropriately in order to ensure that the variance of the prior is not too "restrictive" relative to the size of the mean estimate. In Sections 7 and 9, we discuss the sensitivity of our results to the specification of the priors.
[21]Notice that the normality assumptions are in no way crucial since they can be replaced by more flexible distributions like mixtures of normals.

Finally, we discuss how we calculate the marginal likelihood of the data. Recall from equation (3) that the posterior probability of the data given the model (i.e., the marginal likelihood) has the form

$$\Pr(D|m) = \int \Pr(D|m,\theta_m)\Pr(\theta_m|m)\,d(\theta_m).$$

Integrals of this form, however, can be very hard to calculate numerically. To see why, consider a Monte Carlo estimator for (3). Unless the prior is very similar to the posterior, most of the values for θ_m that one would sample to calculate the integral will have very small likelihood (especially if the posterior is concentrated relative to the prior) and the variance of the estimated integral will be large. As a consequence one would need to take an enormous number of draws from the prior in order to obtain precise estimates of the integral in equation (3), otherwise the estimates will be numerically unstable.

Closed-form solutions and good approximations for some specific models with specific priors exist which avoid the explicit calculation of the right hand side of (3) (e.g., Eicher, Lenkoski and Raftery (2009)). These results, however, do not generalize to panel data models, mixed effects, and heteroskedasticity, and so cannot be applied to the statistical models which are used to evaluate concealed carry laws.

Instead, we apply the procedure of Chib (1995) to compute equation (3). The key insight of Chib (1995) is to recognize that, due to Bayes' Rule, the marginal likelihood can be expressed as the following:

$$\Pr(D|m) = \frac{\Pr(D|m,\theta_m)\Pr(\theta_m|m)}{\Pr(\theta_m|D,m)},$$

and that this relationship holds for any value of θ_m. Chib suggests selecting a value of θ_m that is a high density point in the posterior distribution, such as the mean. Calculating the posterior is accomplished by a Monte Carlo estimate based on the draws from the Gibb's sampler. For larger models like ours, in which θ_m is divided into blocks, additional Gibbs draws are required.

Calculating the marginal likelihood requires us to evaluate the conditional likelihoods for each model. Deriving the conditional likelihood for non-IV models is straightforward. Let $\epsilon_i^\Delta = \left(\epsilon_{i,1}^\Delta, ..., \epsilon_{i,T_i}^\Delta \right)'$. In this case,

$$
\begin{aligned}
\Pr\left(D \mid m, \theta_m\right) &= \Pr\left(Y_{i,t}^\Delta, W_{i,t}^\Delta, m, \theta_m\right) \\
&= \Pr\left(Y_{i,t}^\Delta \mid W_{i,t}^\Delta, m, \theta_m\right) = \prod_i f_{\epsilon_i^\Delta}\left(Y_i^\Delta - W_i^{'\Delta}\alpha\right),
\end{aligned}
\tag{18}
$$

where $f_{\epsilon_i^\Delta}$ is the T dimensional multivariate normal density defined by ϵ_i^Δ.

Since our focus is on comparing models based on how well they explain crime rates, for IV models we compute the conditional likelihood based only on the partial likelihood of the outcome equation (12), taking first random differences in order to eliminate the county fixed effects.

In the IV models, X is potentially endogenous due to the correlation between ϵ_i^Δ and the first stage residuals $\left(v_{i,1,j}^\Delta, ..., v_{i,T,j}^\Delta \right)$. Therefore, we cannot evaluate the likelihood using the unconditional distribution of ϵ_i^Δ, as we do above for the non-IV models. Instead we use the conditional distribution of ϵ_i^Δ, conditional on the first stage residuals in order to capture the dependence between ϵ_i^Δ and X.[22]

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[22]The validity of this approach follows directly from the fact that one can write the parameter posteriors as functions of the joint distribution of the endogenous Y^Δ, X^Δ:

$$
\Pr\left(\theta_m \mid m, Y^\Delta, X^\Delta, W^\Delta, Z^\Delta\right) = \frac{\Pr\left(Y^\Delta, X^\Delta \mid m, \theta_m, W^\Delta, Z^\Delta\right)\Pr\left(\theta_m \mid m\right)}{\Pr\left(Y^\Delta, X^\Delta \mid m, W^\Delta, Z^\Delta\right)}, \quad \text{or alternatively as}
$$

functions of the conditional distribution of Y^Δ on X^Δ:

$$
\Pr\left(\theta_m \mid m, Y^\Delta, X^\Delta, W^\Delta, Z^\Delta\right) = \frac{\Pr\left(Y^\Delta \mid m, \theta_m, X^\Delta, W^\Delta, Z^\Delta\right)\Pr\left(\theta_m \mid m\right)}{\Pr\left(Y^\Delta \mid m, X^\Delta, W^\Delta, Z^\Delta\right)}.
$$

Let $\omega_{i,j}^{\Delta} = \left(v_{i,1,j}^{\Delta}, \ldots, v_{i,T,j}^{\Delta} \right)'$, the T dimensional vector of residuals from the jth first stage regression, and let $\omega_{i}^{\Delta} = \left(\omega_{i,1}^{\Delta}, \ldots, \omega_{i,J}^{\Delta} \right)'$. The partial likelihood of Y given X is then given by:

$$\Pr\left(Y_{i,t}^{\Delta} \mid X_{i,t}^{\Delta}, W_{i,t}^{\Delta}, Z_{i,t}^{\Delta}, m, \theta_m \right) = \prod_i f_{\epsilon_i^{\Delta} \mid \omega_i^{\Delta}} \left(Y_i^{\Delta} - X_i^{'\Delta}\beta - W_i^{'\Delta}\alpha \right). \tag{19}$$

Notice that when ϵ_i^{Δ} is uncorrelated with ω_i^{Δ}, X is no longer endogenous and $f_{\epsilon_i^{\Delta} \mid \omega_i^{\Delta}}$ collapses to $f_{\epsilon_i^{\Delta}}$.[23]

5. Data

The main source of data for this paper is a county-level panel dataset covering 1979-2000. Various versions of this dataset have been used extensively in previous studies on the effect of shall-issue laws on crime.[24,25] The dataset consists of information on crime rates and arrest rates for various crime categories that comes from the FBI's Uniform Crime Reports. This is supplemented with data on the presence of shall-issue laws in each state. The dataset also contains information from the US Census Bureau on a wide set of socio-economic and demographic controls.

In order to expand the model space, we add some additional variables to the dataset. First, we introduce a measure of gun prevalence used previously by Moody

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[23]Note that for IV models, the full variance-covariance matrix of the errors $\left(v_{i,t,1}, \ldots, v_{i,t,J}, \varepsilon_{i,t} \right)'$ needs to be estimated and integrated into equation (19).

[24]Papers using this dataset include Lott and Mustard (1997), Bartley and Cohen (1998), Black and Nagin (1998), Dezhbakhsh and Rubin (1998), Lott (2010), Plassmann and Tideman (2001), Ayres and Donohue (2003, 2009a, 2009b), Moody and Marvell (2008, 2009), Aneja, Donohue, and Zhang (2011), among many others.

[25]The dataset we employ was downloaded from John Lott's website http://www.johnlott.org in January 2013.

and Marvell (2005). Moody and Marvell use the data collected by Duggan (2001) from the General Social Survey (GSS) of the National Opinion Research Center (NORC), which includes questions related to gun ownership. According to Moody and Marvell, this is the only direct measure of gun ownership at the state level.

One drawback of the survey is that it only covers 3000 people, and it is not asked in every state in every year. In order to deal with this, Moody and Marvell show that the percentage of suicides that were committed using guns is a good proxy for gun ownership as measured by the survey. Therefore, we collected data on the percentage of gun suicides from the Centers for Disease Control and Prevention (http://wonder.cdc.gov/).[26] We then scaled this percentage by the correlation between gun ownership and gun suicides found by Moody and Marvell, and use this as our measure of gun prevalence in our empirical analysis.

We also collected data from the US Census Bureau that measures the percentage of people living in urban areas. We define a county as urban if more than 70% of the population live in urban areas and define it as rural if less than 30% live in urban areas. Our results are robust to alternative choices of cutoffs and to the use of a continuous measure of urbanization.

The original dataset includes a measure of the percentage of the population that voted Republican in the most recent Presidential election. However, this variable only goes up to 1998, so we updated this series to 2000 using data collected from the Atlas of US Presidential Elections (http://www.uselectionatlas.org).

6. Defining effects

Since the dummy, spline, and hybrid specifications differ in how the law enters the model, and because we have some specifications in which the effects of the law vary across observations, there is no single parameter that can be used to compare

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[26]These data are available at both the county and state levels. However, due to confidentiality concerns, this data is not reported if the total number of suicides, or number of suicides by guns, is too low. As a result, data are missing for a large number of county-level observations. Therefore, we use the state-level data in our analysis.

the results of the different models. In order to compare the results across models, we compare the crime rates for each observation when we allow the law to be in effect versus when it is not. We call this the marginal effect of the law. We focus on average marginal effects (AME) of the law, where we average the effect over all states in 1998. This means that we are calculating the change in the crime rate which would have occurred if all states had legalized shall-issue in 1998. We compute the effect of the law at implementation, as well as one and two years afterwards. We also calculate the average across all three periods. The primary reason for this is that the spline and hybrid models allow the effect of the law to vary over time.[27] In order to capture this, we measure the effect of the law over this three-year window, allowing the values of controls to evolve over the same three-year window.

Other types of policy effects can be calculated. One alternative, which we call AME-Law measures the average effect of the law for *only* those states which had actually implemented shall-issue by 1998, using a three-year window for crime rates and controls.[28] As a complement to this, we also compute AME-No Law, which measures the effect for states that *did not* implement the law during our sample period. These two measures allow for the possibility that states which implemented the law and those who did not were aware of the heterogeneity in its effects. Our main measure of the effect of the law, AME, is a weighted average of AME-Law and AME-No Law.

In total this gives us twelve different average marginal effect estimates for each model.[29] We compute each of these marginal effect measures for all models in the model space. In order to focus our discussion, we primarily use the version that measures the effect for all states (AME), and we use the average of this measure

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[27]The average marginal effects also vary over time when we allow the effect of the law to depend on certain characteristics of the county (e.g., gun prevalence and the level of urbanization). While the levels of gun prevalence and urbanization do change over time, these changes are typically small.

[28]We also computed the average marginal effect for only states that implemented the law, evaluated when the law was implemented in each state, instead of in 1998. The results were very similar.

[29]We compute each of the three AME measures for each of the three years following the introduction of the law, as well as an average over these three years, for a total of four estimates per AME measure.

across all three years. We discuss the cases in which there are important differences between the various measures and their corresponding relevance for gun control policy.

7. Preliminary analysis and identification of a policy-relevant model space

A standard issue in exploring model spaces concerns the high dimension of the space. Madigan and Raftery (1994) propose a way of decreasing a set of candidate models by eliminating highly improbable ones via a procedure they call "Occam's Window". The basic idea of the procedure is to set a threshold for a model's posterior probability and to then eliminate models with lower probabilities than this threshold. For the context of understanding the role of assumptions in outcomes, we follow the spirit of the "Occam's Window" procedure by checking whether certain assumptions are associated with qualitatively lower likelihoods than their (contradictory) counterparts, and so resolve such cases based on complexity-penalized goodness of fit. We start with this evaluation in order to allow subsequent analyses to focus on assumptions which possess non-negligible posterior weights. Specifically, we identify assumptions such that the model with the highest likelihood from those maintaining the assumption still has a lower likelihood that the model with the lowest likelihood among models which do not maintain it. There is one assumption whose associated models are dominated by the posterior probabilities found in the rest of the model space.

The assumption that is associated with dominated models is the use of population weights to control for heteroskedasticity. This finding suggests that the common practice of adding population weights to regressions using county-level or state-level data is not supported by the data. As discussed in Section 3, when one considers the presence of location-time-specific unobservables in the model, the standard argument for using population weights is weakened, and may in fact introduce heteroskedasticity, instead of correcting for it. Further, models with weights tend to overstate the effect of the laws on the crime rate compared to the models without weights. In other words, the models with weights are more likely to find that the laws

lead to an increase in crime. As a result, the standard use of population weights in the literature may be leading to an upward bias in the estimate of the effect of the laws on crime in light of the lack of support for the assumption. The model space described in Figure 2 generates 624 models. Half of this set consists of models with population weights. After eliminating these dominated models, 312 models remain for analysis. This means that we now examine model uncertainty with respect to control variables for demographics and location-specific heterogeneity, parameter heterogeneity, specification of time trends, and instrumental variables.

In addition to our baseline set of priors discussed above, we also estimate versions of the model under two alternative specifications of the parameter priors: a high variance case in which we increase the variance in the priors for β, α to $\sigma^2 = 20$ instead of 10 and we set the Wishart prior to $\Pi \sim W(b, V)$, with $b = J + 1$ instead of $J + 2$; and a low variance case in which we set $\sigma^2 = 1$ and $b = J + 5$. While the choice of priors have an impact on the marginal likelihoods for each model (which we discuss below in Section 9), the estimated AME's are very similar across the different choices of priors. Therefore, we report the AME results from our baseline set of priors only.

Figures 3A and 3B present dispersion plots which graphically represent the heterogeneity in average marginal effects (AME) that appears as one moves across the model space.[30] The estimated AMEs are represented by the solid black line, and 95% confidence intervals around the estimates are represented by the dotted lines. Roughly one-half of the models produce a positive effect of the law on crime, i.e., shall-issue laws increase crime, whereas the remaining models suggest a negative effect. Magnitudes also vary considerably. For violent crime, the estimates range from the law implying a decrease in crime of 15% to an increase of 26%, and for property crime ranging from a decrease of 19% to an increase of 35%. Based on these results, it is easy to see how the concealed carry literature contains such disparate claims. Depending on the model chosen by the researcher, the results can vary from a large decrease to a large increase in the crime rate. We now examine the sources of this heterogeneity in estimated policy effects.

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[30]In Table A in the Appendix, we present the marginal likelihood values for the non-dominated models for both violent and property crime.

8. Assumptions and policy effects

In Figures 4A-4H we present the average marginal effects (three-year average of AME) for all models. These figures are the same as Figures 3A and 3B, except that the models are grouped according to each model dimension. In order to make the figures easier to read, we drop the confidence bands around the estimates. For example, Figures 4A and 4B group the models by the formulation of the law (i.e., dummy, spline, hybrid). These figures illustrate two important features of our estimates. First, there is a substantial degree of heterogeneity both across and within each dimension of the model space. Second, they show how moving within each dimension of the model space affects the estimated effect of the law.

i.   formulation of shall-issue laws as a crime determinant

For both violent and property crime, there is a clear difference in the estimated average marginal effects between the dummy, spline, and hybrid models. As can be seen in Figure 4A, for violent crime, the dummy specifications generate the largest (in absolute value) negative effects of the law, the hybrid generates the largest positive ones, and the spline is in between. However, there is a substantial amount of heterogeneity within each group, as all three contain both positive and negative estimates. With property crime the differences are more pronounced, and flipped compared to the violent crime results. As Figure 4B illustrates, the hybrid produces the largest (in absolute value) negative values, and the dummy model produces the largest positive values, again with the spline in between. The sign of the effect is more uniform within the dummy and spline categories, with the dummy producing mostly positive estimates, and the spline producing mostly negative estimates, although there is substantial variation in the magnitude of the dummy model estimates.

In most cases, the hybrid or spline specification is preferred to the dummy model (has a higher marginal likelihood value, see table A in the Appendix). In about half of the

cases for property crime, and about one-quarter of the cases for violent crime, the hybrid model has a higher marginal likelihood than the spline model. While the hybrid model is a more flexible version of the spline model, in many cases the contribution of this increased flexibility towards explaining the observed crime rates is offset by the penalty for the increased model complexity.[31]

Together these results suggest that the effect of legalization of concealed carry is heterogeneous over time, and that the use of a single dummy variable is insufficient to capture the effect of the law. The hybrid and spline are reduced form ways of allowing for this but, as illustrated in Figure 1 and its associated discussion, more work needs to be done to investigate the source and implications of this heterogeneity.[32]

ii.   control variables

We next examine the effects of alternative control variable choices. For violent crime, there is no systematic pattern in either the estimated marginal effects or the likelihoods between specifications with the full set of age and race variables (36 in total) and those with only the black/white subset (12 variables). The specifications with the full set of age and race variables are preferred in almost all cases for property crime. Similar to violent crime, however, there is no systematic pattern in the average marginal effects. For both types of crime, the difference in marginal effects is very small (less than 1% on average), and thus both versions (with and without full age and race variables) provide similar answers to the question of the effect of shall-issue laws on crime.

For the additional control variables, it appears that gun prevalence is useful for helping to explain violent crime patterns, as its inclusion leads to higher marginal

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[31]This is confirmed when we do sensitivity analysis in Section 9. As we increase the prior precision (i.e., decrease the variance), the implied penalty for complexity is reduced and the marginal likelihoods for more complex models (i.e., hybrid) increase relative to those for the simpler models (i.e., spline).

[32]Black and Nagin (1998) interact the law with a set of five lead and lag dummies, allowing the effect of the law to vary over the 11-year period centered around the enactment of the law, however they fail to find any statistically significant effects of the law on crime.

likelihood values for most specifications. However, urbanization leads to lower marginal likelihood values in all cases, suggesting that the contribution to the likelihood is undone by the implicit penalty in the marginal likelihood for the extra parameters. Neither set of additional control variables has a systematic pattern in the marginal likelihoods for property crime. As was the case with demographic variables, for both types of crimes, these additional variables generate only small changes in the average marginal effects. As we discuss below, the more important impact of these additional variables is through allowing the effect of the law to depend on gun prevalence and urbanization by interacting them with the law variables.

iii.   time trends

With only two exceptions (both for violent crime), the models with time dummies are preferred to their counterparts with region trends. This finding indicates that the time-series patterns in crime rates do not follow a linear trend and are better approximated by flexible time dummies, even at the expense of not allowing the time-series pattern to be region-specific. However, even though the models with time dummies are strongly preferred in terms of marginal likelihoods, the distribution of AME's illustrated in Figures 4C and 4D for both types of models is quite similar, with an average difference of 0.25% for violent crime and 0.04% for property crime. Hence, as was the case with additional covariates, the use of time dummies outperforms region trends, but has little effect on the estimated effects of the law.

iv.   parameter heterogeneity

Figures 4E and 4F plot the estimated AME's when one allows for the effects of the law to be heterogeneous. On average, the models that allow for interactions with urbanization generate the highest AME's, and those with region interactions generate the lowest AME's.

As shown in Table A in the Appendix, for violent crime there is a clear pattern in the marginal likelihoods, and the models that include interactions of the law and region

are strictly preferred to the other models. These specifications on average produce lower effects of the law compared to the other models (i.e., small negative effects versus effects close to zero). However, as Figure 4E illustrates, there is still a considerable amount of heterogeneity in the estimated effects within each group.

With property crime, the pattern is less clear. The models with interactions are generally preferred to the models without any parameter heterogeneity. Overall, the models that include interactions with urban dummies and the models that include interactions with urban dummies and gun prevalence have the highest marginal likelihood values. There is no systematic pattern in the AME's for the models with urban interactions, but on average they produce the largest positive effects of the law. As was the case with violent crime, there are large differences in the estimated effects within each group.

In general we find that the effect of shall-issue laws on both property and violent crime is increasing in gun prevalence. In other words, the more guns there are in the population, the more likely the law leads to an increase in overall crime. One potential explanation for this result is that as the number of guns in the population increases, any potential deterrent effect of individuals being able to carry concealed weapons is mitigated by the increase in the number of guns actively being carried in public (as opposed to just being owned).

When we allow for the effects of the law to vary with the degree of urbanization, we also find evidence of heterogeneous effects. For property crime, the effect of the law is monotonically decreasing in urbanization. The more urban (rural) a county is, the more likely the law will decrease (increase) crime. With violent crime there seems to be a similar pattern, although it is less pronounced, particularly with the spline and hybrid specifications.

The results with regional heterogeneity are harder to interpret. This is partially due to differences in the crime trends across regions, which we discussed earlier. For violent crime, the dummy model specification suggests that the effect of the law for the South is to increase crime (or decrease crime less) relative to the other regions. However, once we allow for the effect of the law to vary over time via the spline or hybrid models, the result flips, with the law associated with a decrease in crime (or a

smaller increase in crime) in the South relative to the other regions of the country. Moreover, when we also allow the law to interact with gun prevalence, the change is even stronger, due to the fact that gun prevalence is higher on average in the South.

For property crime there is also evidence of heterogeneous effects of the law across regions, but there is no consistent pattern across models. These results suggest that there is important heterogeneity in the effect of shall-issue laws across regions. While interacting the effect of the law helps to both isolate this heterogeneity and to better fit the observed patterns of crime, region differences alone do not inform us as to the ultimate source of this underlying heterogeneity, something we discuss more in the conclusion.

v.   instrumental variables

When we compare the models which treat the laws and the arrest rate as endogenous (IV models) to those in which they are assumed to be exogenous (non-IV models), we find that the IV models are almost exclusively preferred to their non-IV counterparts. However, the non-IV models are not dominated as a group, as was the case with population weights. This implies that although there is strong support for treating the laws and arrest rate as endogenous, there are other dimensions of the model space that are equally, if not more, important. On average the IV models generate higher average marginal effects (5.6 and 0.5 percentage points higher for violent and property crime, respectively). Figures 4G and 4H demonstrate the reasons for these differences. For violent crime, it is driven by the fact that almost all non-IV models generate negative effects of the law, but the IV models generate a majority of positive effects. With property crime, on the other hand, the difference is driven by the magnitude of the effects, as opposed to the sign.

vi.   differences across the average marginal effect measures

So far we have focused our discussion on the three-year average of AME, one of twelve measures we compute for each model. In many cases the average marginal

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effects vary little, if at all, across the three measures and across the different years in which the effect is measured. However, there are two situations for which this is not the case, and they are worth highlighting. The first case is when the models contain trends (spline/hybrid). The trend component of these specifications produces an effect of the law that builds over time, and unless the trend effect is equal to zero, the magnitude of the effect depends on how long the law has been in place. In some cases the trend is quite large, which makes it difficult to evaluate the effect of the law compared to other models. In addition, as the discussion surrounding Figure 1 shows, the linear trend specification has the unappealing feature that the magnitude of the effect grows without bound. We believe that while the results from these models suggest that there is important time-heterogeneity in the effects of the laws, the correct specification of these time-effects warrants further research. Furthermore, there may be short-run versus long-run trade-offs in terms of the effects of the laws that need to be considered.

The second situation in which there are important differences across the average marginal effects measures are when the models include interactions of the law with region. This result is presented graphically in Figure 5. When the average marginal effects are computed for states that implemented the law (AME-Law), compared to states that did not implement the law (AME-No Law), we see sizeable differences. (Recall that our main AME measure is just a weighted average of these two measures.) This is reflective of the fact that those regions that were more likely to adopt shall-issue laws experienced different effects of the law compared to regions that were less likely to adopt. This is an important result to note, particularly to policymakers trying to decide whether to enact such laws. The effects of the law vary across location, and the experiences of those that previously enacted the law are not necessarily going to be replicated in other locations.

This discussion is quite wide ranging. We summarize our findings on the model space as follows.

1. In terms of complexity-penalized fit (i.e., marginal likelihoods), models that a) allow for heterogeneity and b) correct for endogeneity, substantially outperform their counterparts.

2. The effect of the law seems to be very heterogeneous across many dimensions. Interacting the law with observables like gun prevalence, or urban or region dummies shows that a) having more guns seems to reduce the potential deterrent effect of the law, b) more urbanization increases the potential deterrent effect of the law and c) there seem to be important regional differences in the effect of the law on crime.

3. While the effects of the law are heterogeneous along many dimensions, some assumptions lead to specific patterns of results. For the case of violent crime, models that do not account for the endogeneity of the law almost surely lead to negative (i.e., deterrent) effects of the law, while models that use instrumental variables are very likely to find a positive effect of the law. For property crimes, the AME's are ordered according to the specification of the effect of the law. Models that use a dummy specification point to a positive effect of the law, spline models find (small) negative effects, while hybrid models find more mixed effects.

4. There is little support for the substitution hypothesis of Lott (Lott and Mustard (1997), Lott (2010)) in which criminals shift their activity from violent crimes towards less confrontational crimes like property crimes.

5. Finally, all results should be interpreted with caution, as there is enormous heterogeneity in the estimated effects across models, in terms of the signs, magnitudes, and their economic and statistical significance.

9. Posterior Probabilities and Model-Averaged Results

We have focused our discussion thus far on the distribution of AME's over the model space, documenting how the estimated effects of shall-issue laws vary across and within different modeling assumptions. However, as we have alluded to above,

models vary in their degree of evidentiary support, as summarized by their marginal likelihood values. In order to illustrate the relationship between the AME's and the support for each model in the data, in Figures 6A and 6B we plot the same AME's we plot in the previous figures, but now sorted by the value of the marginal likelihoods.

For the case of violent crimes, the models with the highest marginal likelihoods all point to small effects of the law on crime, the effect being positive for the top models. For property crime, the preferred models all point to much larger (mostly negative) effects of the law on crime. This is due to the fact that for property crime, the hybrid models receive the highest marginal likelihood values, and these models are the ones that generate the largest negative effects of the law. These models are all characterized by large negative (deterrent) effects initially, followed by a positive trend afterwards. Therefore, although the AME's in the first few years are negative, they are shrinking over time, and would eventually turn positive.

We now turn to the model-averaging exercise as described by equations (5) and (6) in Section 2. Since we have no strong *a priori* reason to prefer one model specification over another, we employ a uniform prior distribution over the model space. Given the large differences between the marginal likelihoods documented in Table A in the Appendix (even between the most likely models), changes in the model priors will have a negligible impact on the calculation of the posterior model probabilities. In order for the specification of the model priors to make a difference, one would have to prefer the second most likely model at least 9 times more *a priori* (even more so for property crime) than the most likely model for it to make a difference.

For violent crime, only two models receive posterior probabilities above 1%. We label these as model A and model B. The specifications for each are listed below, based on the characterization of the model space in Figure 2.

- Model A: Spline, collapsed demographic controls, add gun prevalence controls, time dummies, region interactions, IV, no population weights.

- Model B: Spline, collapsed demographic controls, no additional covariates, time dummies, region interactions, IV, no population weights.

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The difference between the two models is that model A also includes gun prevalence and gun prevalence-squared as control variables. The posterior probability weights for model A and model B are 90.1% and 9.9%, respectively.

As can be seen in Table 1, both models produce similar results in terms of the AME's. For both models, all three average marginal effect measures suggest a similar pattern. As a result of the law being introduced, violent crime increases in the first year and continues to increase afterwards.[33] In addition, the effect is the strongest for those states that had not introduced shall-issue laws as of 1998, suggesting that the increase in crime resulting from the law would be even larger if these states were to introduce such laws.

With property crime, the posterior model probabilities load essentially on one model, which we denote as model C.

- Model C: Hybrid, all demographic controls, no additional covariates, time dummies, gun prevalence and urban interactions, IV, no population weights.

For property crime there is initially an economically and statistically significant drop in crime of 12%. However, as was the case with violent crime, there is a positive trend in the effect of the law on crime. As a consequence the deterrent effects of the law get wiped out and would become increasingly positive if extended over the long run. However, as the discussion surrounding Figure 1 suggests, one should be careful about how to interpret the immediate effects of the hybrid model.

Beyond the estimated effects we just presented, the model averaging exercise illustrates a pattern that warrants further research. The fact that the data prefer models with interactions between time and the effect of the law, shows that the law has effects that are not only heterogeneous in the cross section (by region, prevalence of guns, etc.) but with strong time heterogeneity as well. However, the practice of introducing this time heterogeneity via simple trends is problematic. For our estimates, the effect on

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[33]Note that when the model includes interactions of variables with the law, the AME measures will not necessarily follow a simple linear trend over time. In fact, depending on how the interacted variables change over time, they need not even be monotone.

crime of introducing guns continues to grow over time. So it seems important to consider richer specifications of the policy effect than have appeared in the literature.

i.   robustness to parameter priors

As we discuss above, in order to analyze the sensitivity of our results to the choice of the priors over the parameters, we estimate the model under three different prior specifications: baseline, low variance, and high variance. While our estimated effects of shall-issues laws are very similar across all three prior specifications, the marginal likelihoods do change.

For the high variance set of priors, the marginal likelihoods for more complex models get reduced relative to simpler models (since the implied penalty for complexity increases). The ordering of models based on the marginal likelihood remains mostly unchanged, and in fact it is the same for the most likely models.

With the low variance case, the marginal likelihoods are relatively higher for more complex models as the implied penalty is reduced. For the case of property crime, the ordering is again mostly unchanged, especially for the most likely models. However, the ordering does change for the case of violent crimes. In this case the most likely models are more complex versions (e.g., hybrid, full set of demographic variables, and the addition of interactions of the law with gun prevalence) of the preferred models with the baseline priors. The AME's generated by these models all produce very small estimated AME's that are not statistically different from zero.

10. Conclusions

Relative to the strong claims made by particular papers in the literature, we find evidence that the estimated effects of shall-issue right-to-carry laws on crime are very sensitive to modeling assumptions. Furthermore, particular subsets of assumptions (e.g., dummy vs. hybrid) can mark the difference between getting a negative or a positive effect of the law. However, our model averaging exercise does lend some

support to the law having a negative (but with a positive trend) effect on property crimes, and a small but positive (and increasing) effect on violent crimes. Based on these results, we do not find evidence of these laws leading to substitution away from violent crime and into property crime. Overall, we conclude that the evidence that shall-issue right-to-carry laws generate either an increase or decrease in crime on average seems weak.

However, we do find some interesting results that we believe are revealing as to how shall-issue laws affect crime. For both types of crime, the degree of gun prevalence in a county is an important determinant of how the law affects crime. Interestingly, for violent crime, heterogeneity across regions is also important, whereas the level of urbanization is more important for property crime. While there are regional differences in urbanization, it appears that there are other differences across region that drive violent crime. With property crime, the level of urbanization seems to be an important difference that transcends regional boundaries.

Urban areas differ from rural areas in how closely people live to one another. Property crimes, by definition, do not involve confrontations with victims. Therefore, it seems natural that concealed carry laws could have different effects on crime in areas in which potential witnesses to property crimes (who may be carrying concealed weapons) are more dispersed compared to areas in which they are tightly clustered. Alternatively, it may be easier to carry a concealed weapon regularly in a rural area in which there may be fewer places in which weapons are not allowed, such as mass transit and state or federal facilities, resulting in differential usage of the law in rural versus urban locations.

For violent crimes, with the exception of murder, there is always at least one witness to the crime, the victim. Therefore, the fact that there might be other armed witnesses might be less relevant for these crimes. Of course, our finding that urbanization matters more for property crimes, and region matters more for violent crimes, does not mean that urbanization is not relevant. Rather, it reveals that there are other factors that vary across regions, which are more important. The use of region interactions helps to identify the level at which these differences exist, but does not

provide any direct evidence as to the underlying mechanism. Attitudes towards violence, gun safety, and gun usage in general are examples of potential differences.

We believe that, in particular, our results related to parameter heterogeneity highlight an area of research that is currently underdeveloped in the literature. The fact that interacting the effect of the law with time trends and region helps to better explain crime patterns in the data, suggests the presence of important sources of heterogeneity that are not captured by current models of crime.

One can speculate as to the underlying mechanisms at work here, and attempt to identify additional observable variables to include in the model. However, progress will, we believe, primarily depend on the introduction of a more structural approach to the analysis of shall-issue laws. The assumptions underlying both the theories that predict the law will lead to an increase in crime and those that predict a decrease all involve individuals making different decisions in the presence of concealed carry laws. Incorporating into the analysis mechanisms that generate both possible effects, in addition to allowing for counterfactual analysis, permits specification testing of the model's substantive behavioral commitments.

An example of where a more structured approach to modeling crime would help arises in our finding that a time-varying effect of the law is important to explain the patterns in the data. Without a model that explains why these temporal patterns arise, it is not clear how to interpret these changes or how useful it is to even estimate them as opposed to just recovering some "average" effect of the policy. Is this heterogeneity a consequence of restrictions on the "technology" of crime commission, and hence the policy fundamentally alters how criminals commit crimes? Are these patterns the consequence of changes in expectations by the agents, and what we see is simply a temporary effect while agents "figure out" how to identify gun-carrying individuals, for example? Do they arise because of interactions with other (potentially unmeasured) laws that also change over time, etc.? The answers to these questions have different implications for both policy evaluation (e.g., we may not be able to estimate the effect

independently of other policies) and implementation (e.g., packages of policies, either concurrently or in particular sequences, may be more effective).[34]

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[34]See for example Murphy (2003), Heckman and Navarro (2007), and Cooley, Navarro and Takahashi (2014) for a discussion of issues surrounding time-varying treatment effects.

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Figure 1: Hybrid Model Example

Figure 2: Model Space

Crime Category	Formulation of the Laws	Demographics	Additional Covariates	Time Effects	Parameter Heterogeneity	Instrumental Variables	Homoskedastic/ Heteroskedastic
1. Property	1. Dummy	1. All	1. None	1. Time Dummies	1. None	1. non-IV	1. No weights
2. Violent	2. Spline	2. Collapsed Demographics	2. Urban	2. Region Trends	2. GP and GP squared	2. IV	2. Population weights
	3. Hybrid		3. Gun Prevalence (GP) and GP Squared		3. Urban		
					4. Region		
					5. GP, GP Squared and Region		
					6. GP, GP Squared and Urban		

Figure 3A: Average Marginal Effects - Violent Crime
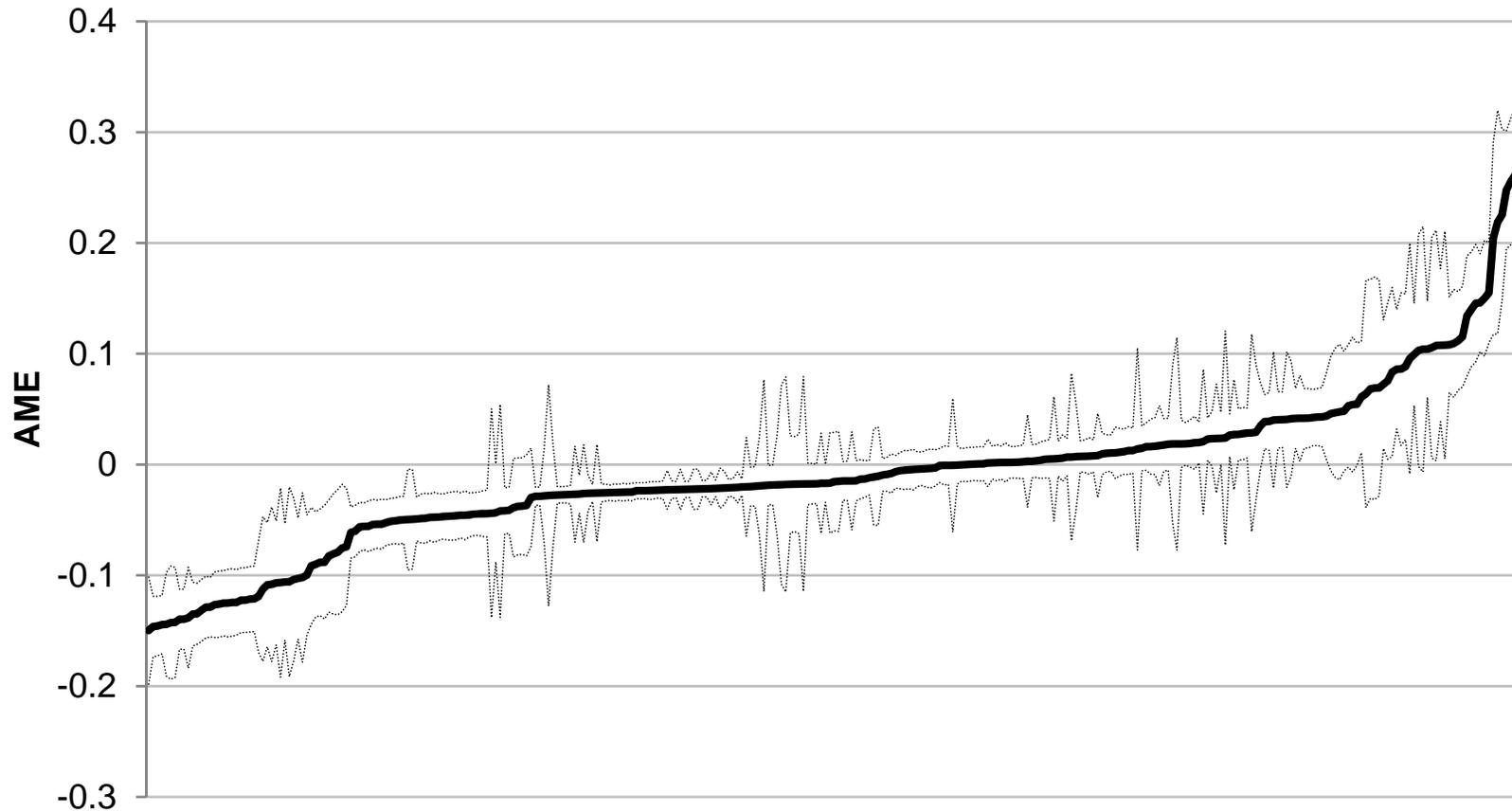
Note: Each dot on the solid black line represents a specific model's three-year average effect of introducing a shall-issue law, computed for all states using their characteristics in 1998-2000 (AME). The dashed lines show the corresponding 95% confidence interval.

Figure 3B: Average Marginal Effects - Property Crime
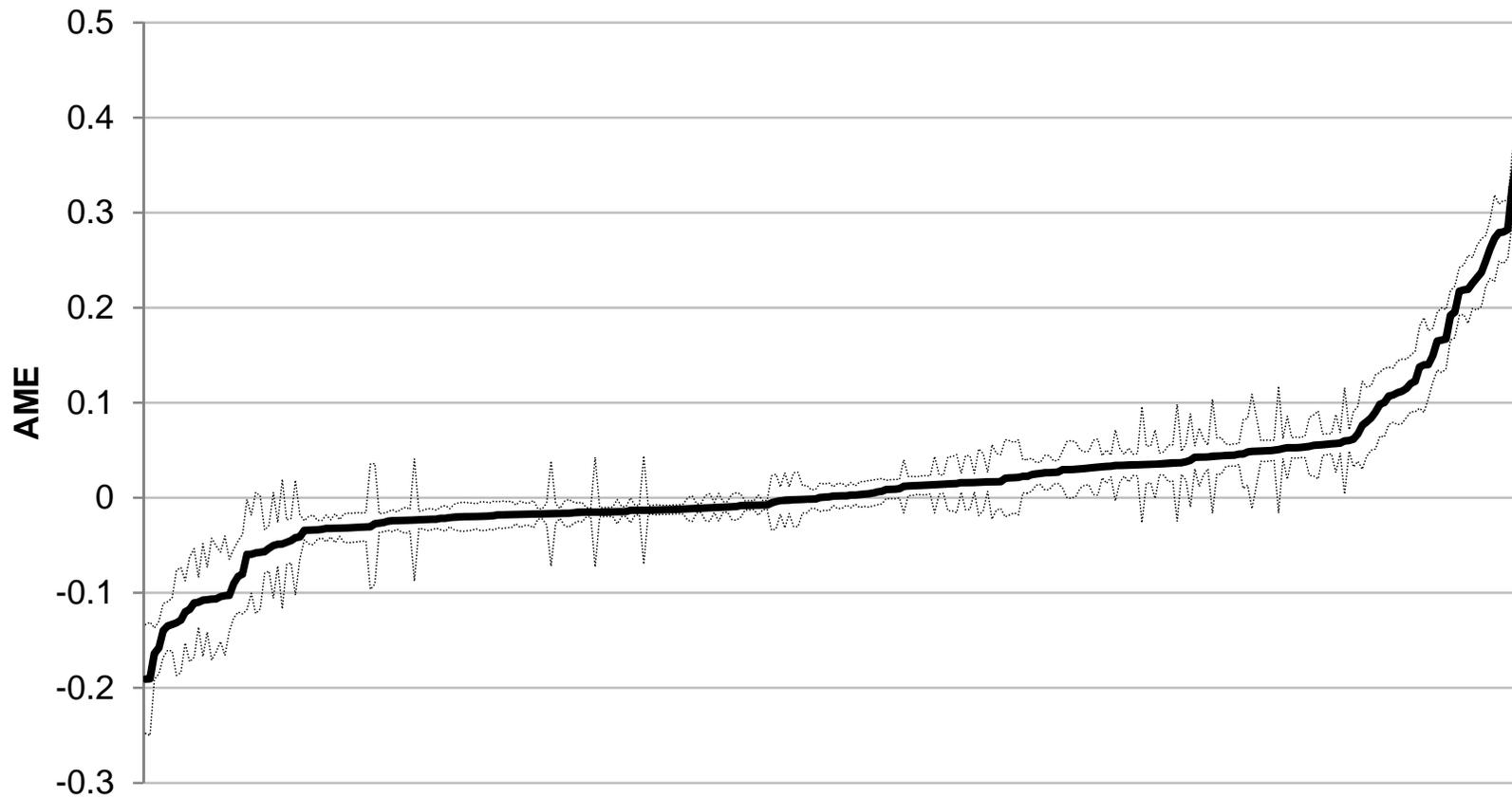
Note: Each dot on the solid black line represents a specific model's three-year average effect of introducing a shall-issue law, computed for all states using their characteristics in 1998-2000 (AME). The dashed lines show the corresponding 95% confidence interval.

Figure 4A: Average Marginal Effects - By Law Specification - Violent Crime
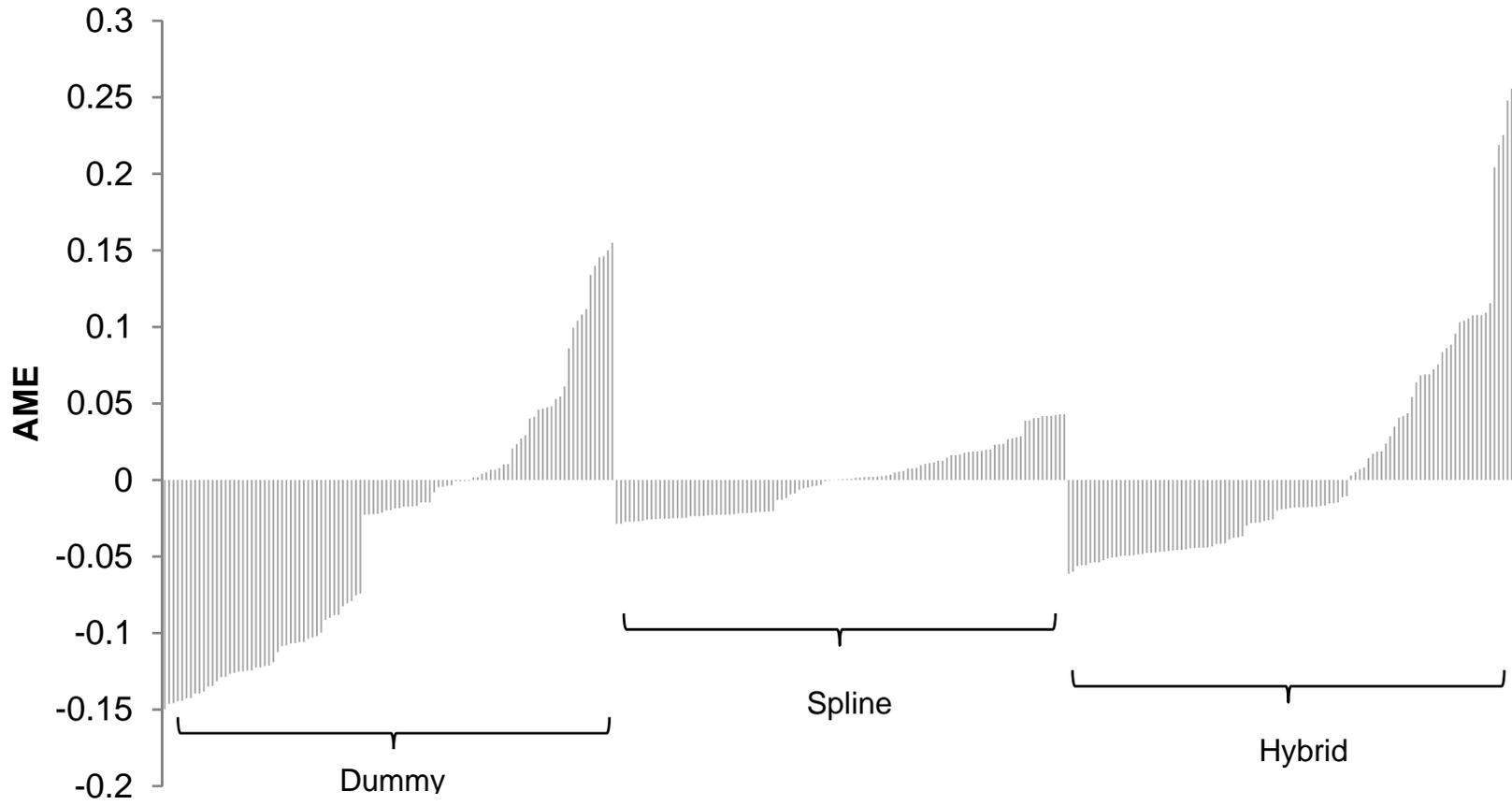
Note: Each bar represents a specific model's three-year average effect of introducing a shall-issue law, computed for all states using their characteristics in 1998-2000 (AME).

Figure 4B: Average Marginal Effects - By Law Specification - Property Crime
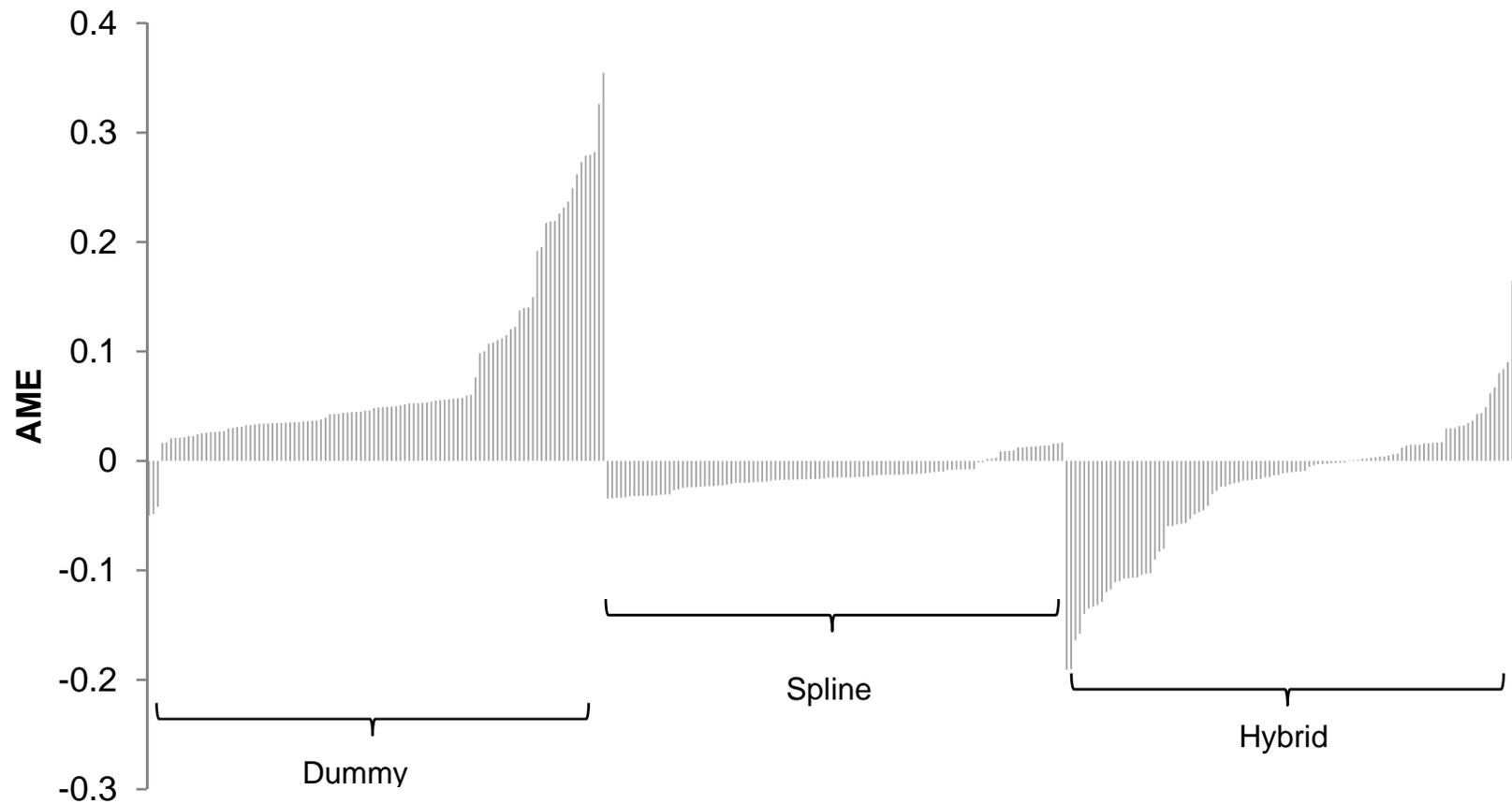
Note: Each bar represents a specific model's three-year average effect of introducing a shall-issue law, computed for all states using their characteristics in 1998-2000 (AME).

Figure 4C: Average Marginal Effects - Region Trends vs Time Dummies - Violent Crime
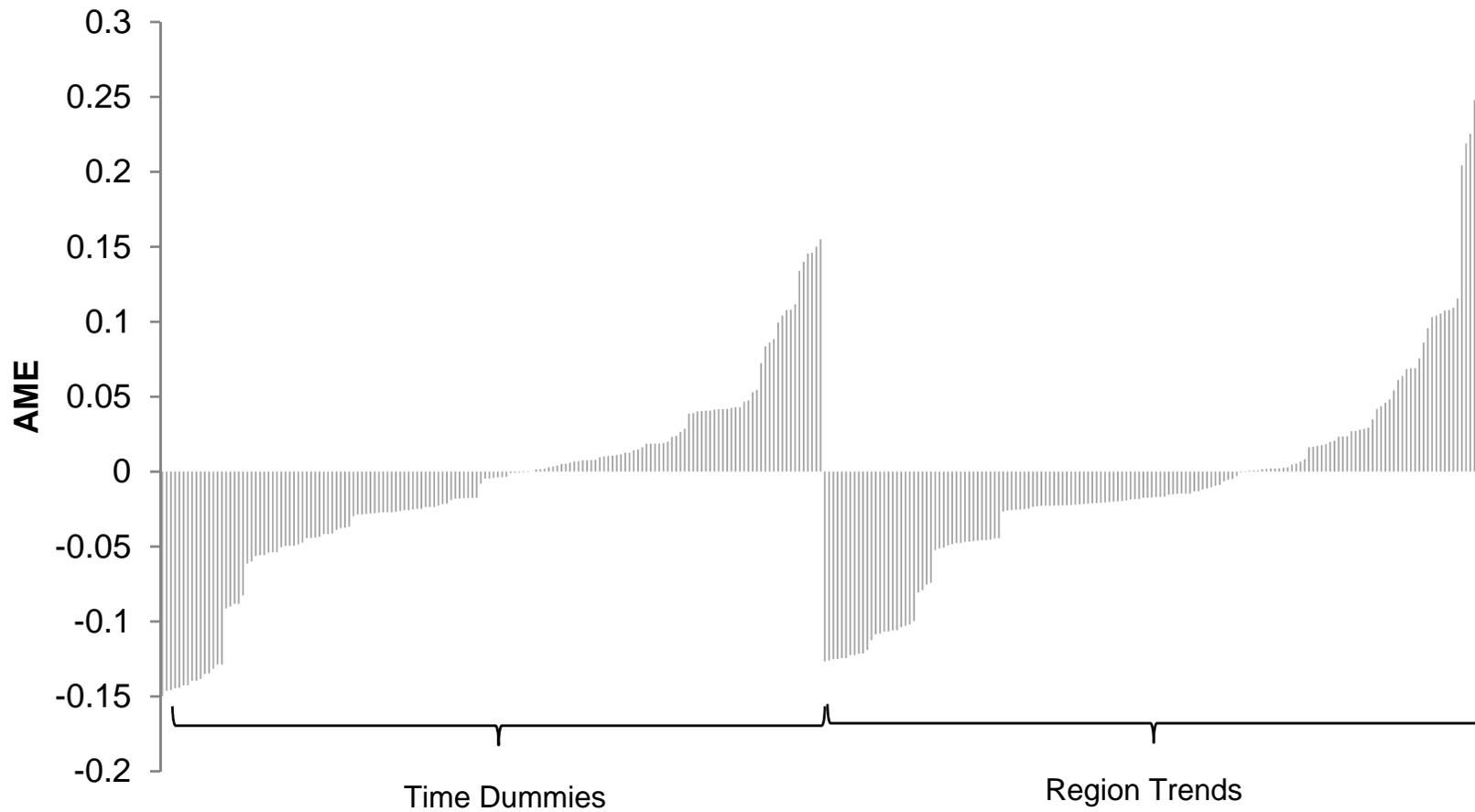
Note: Each bar represents a specific model's three-year average effect of introducing a shall-issue law, computed for all states using their characteristics in 1998-2000 (AME).

Figure 4D: Average Marginal Effects - Region Trends vs Time Dummies - Property Crime
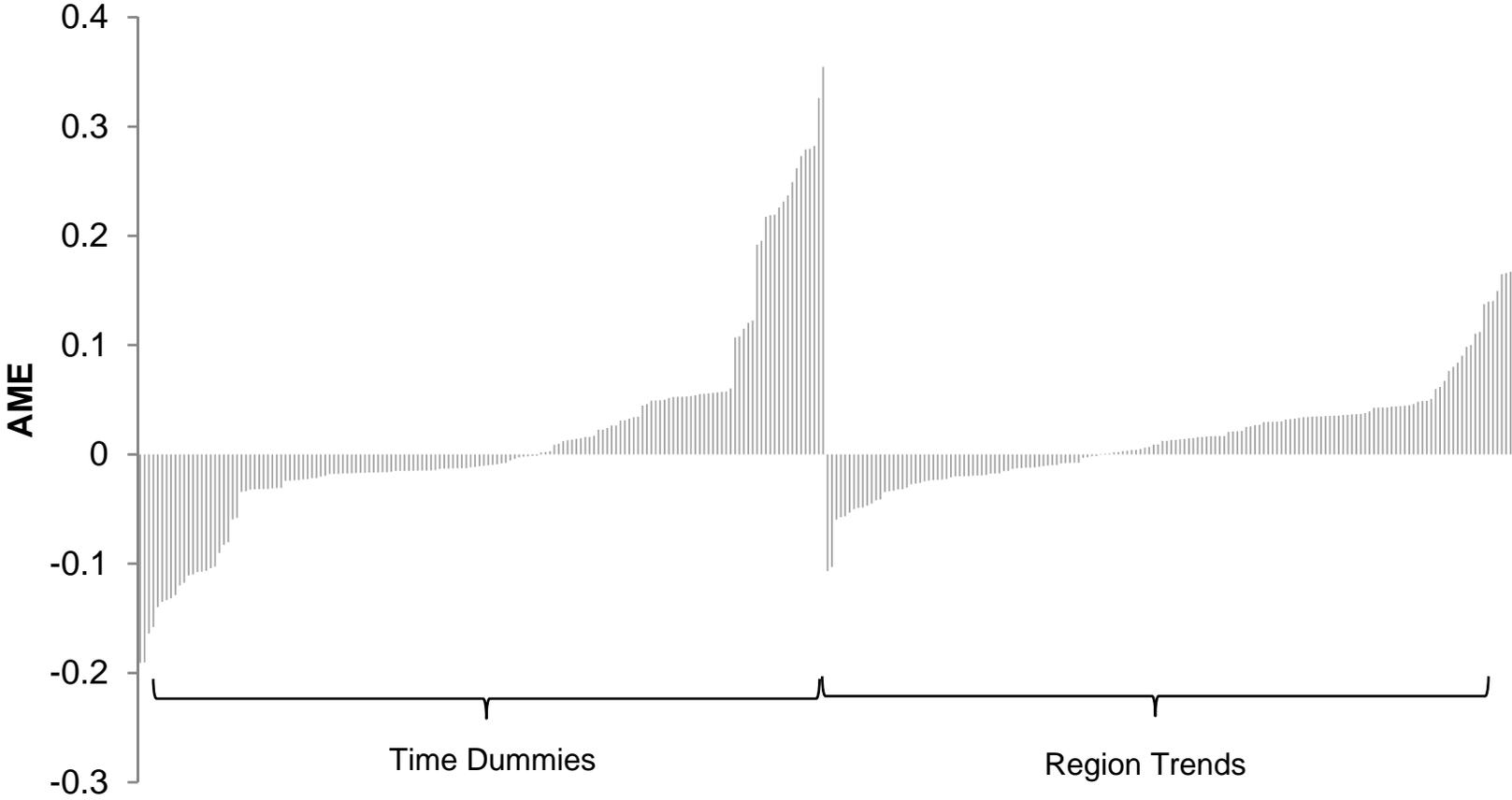
Note: Each bar represents a specific model's three-year average effect of introducing a shall-issue law, computed for all states using their characteristics in 1998-2000 (AME).

Figure 4E: Average Marginal Effects - Parameter Heterogeneity - Violent Crime
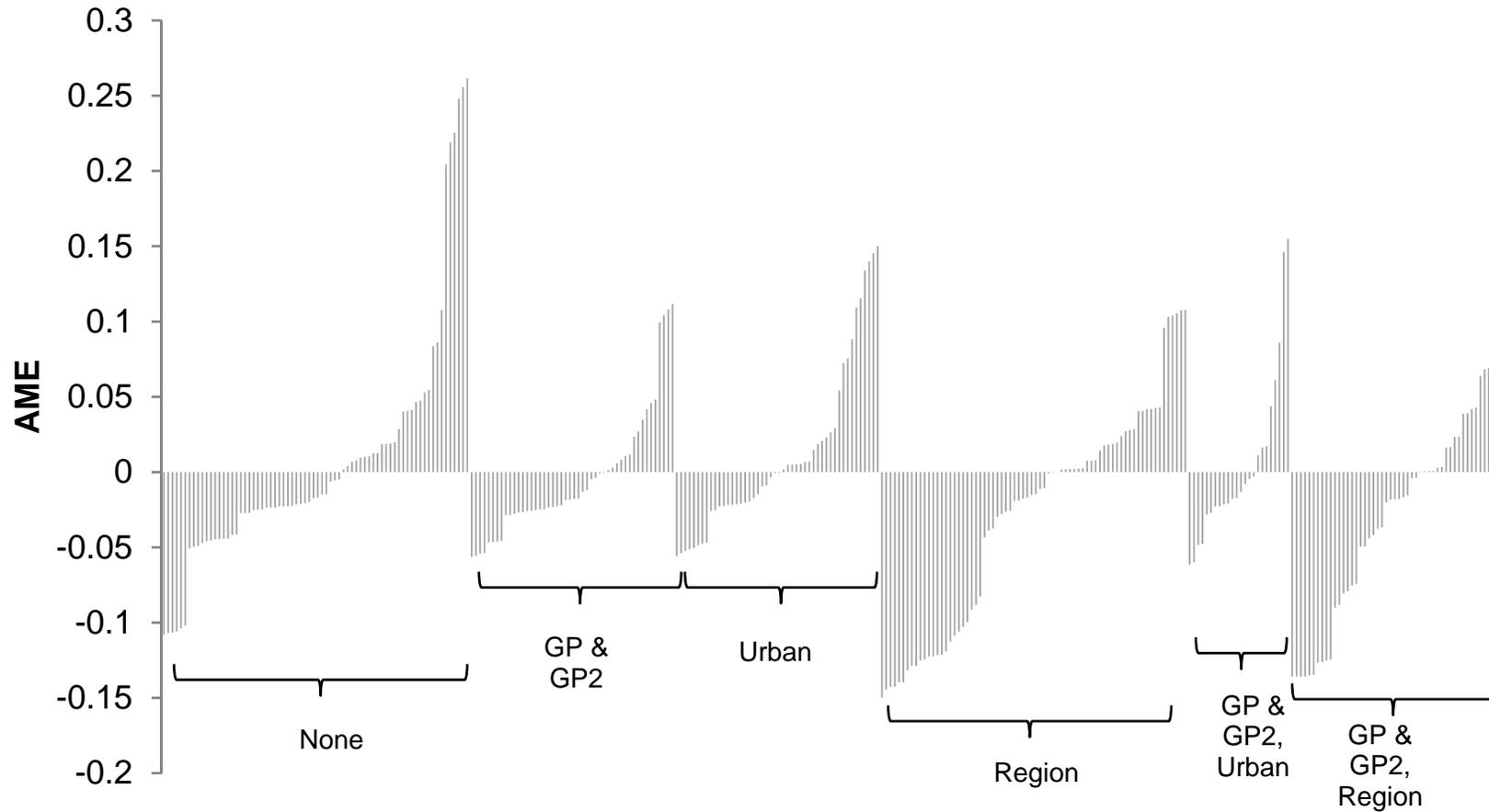
Note: Each bar represents a specific model's three-year average effect of introducing a shall-issue law, computed for all states using their characteristics in 1998-2000 (AME). GP and GP2 stand for gun prevalence and gun prevalence squared.

Figure 4F: Average Marginal Effects - Parameter Heterogeneity - Property Crime
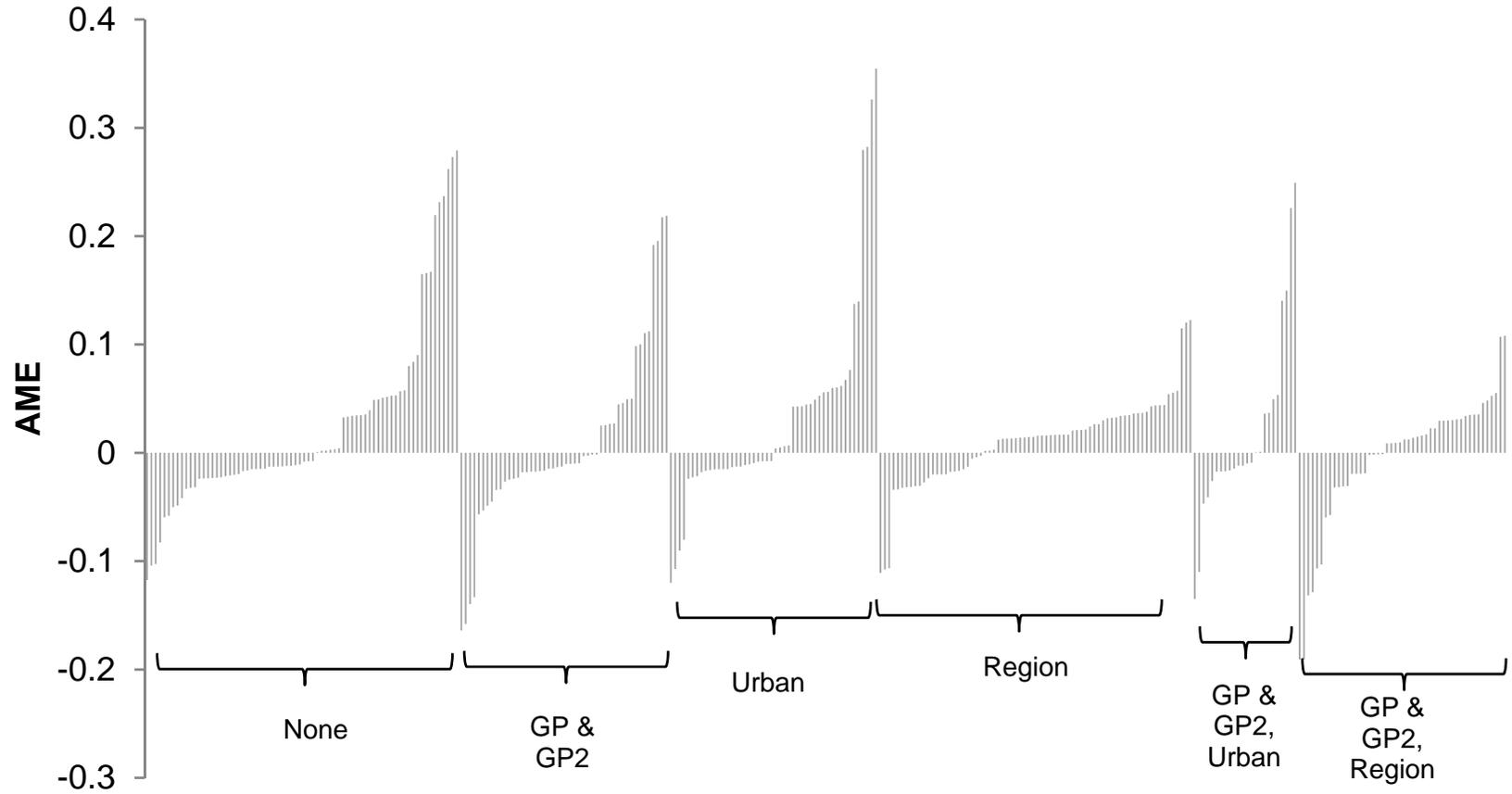
Note: Each bar represents a specific model's three-year average effect of introducing a shall-issue law, computed for all states using their characteristics in 1998-2000 (AME). GP and GP2 stand for gun prevalence and gun prevalence squared.

Figure 4G: Average Marginal Effects - IV versus Non-IV Specifications - Violent Crime
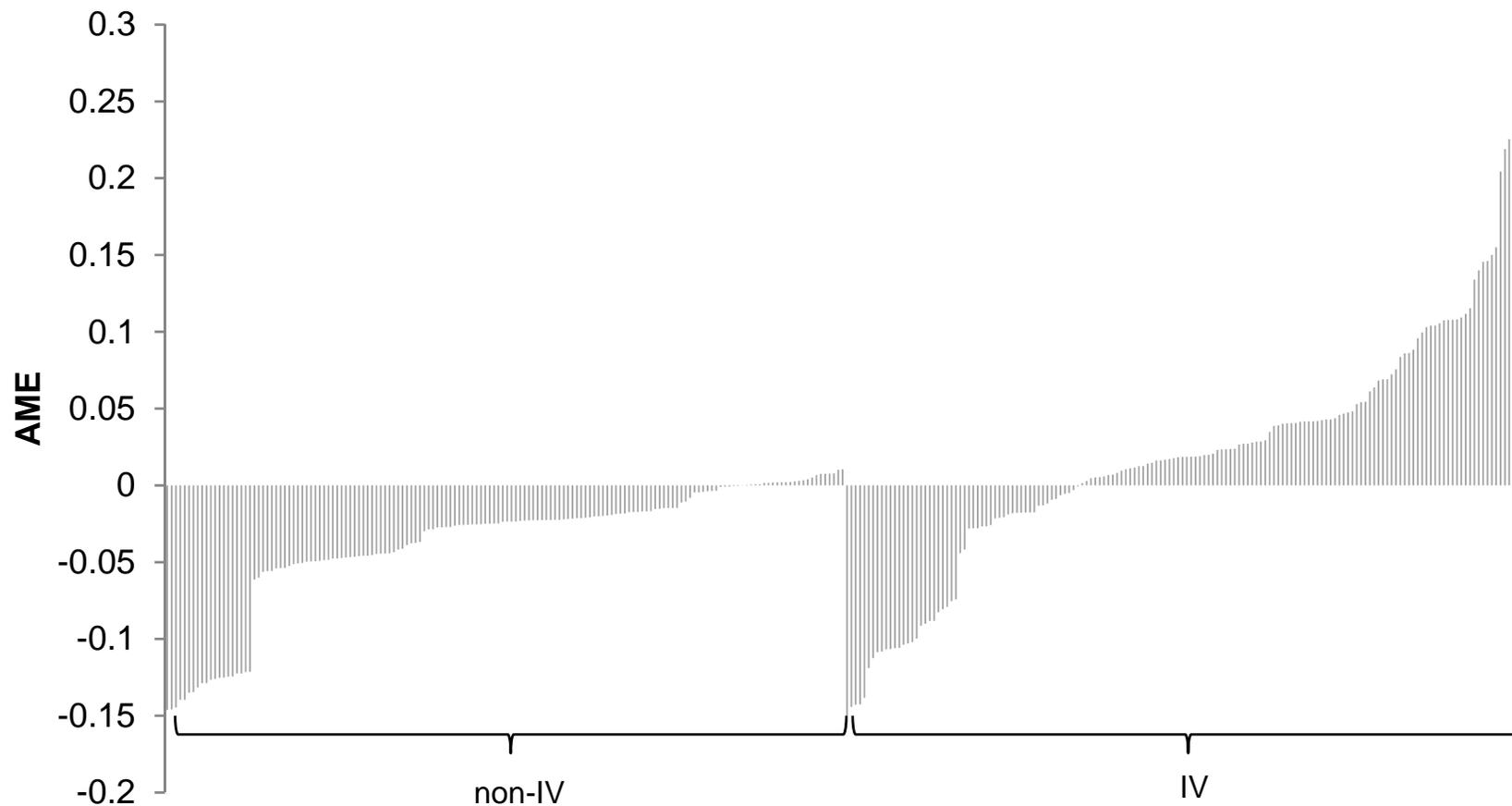
Note: Each bar represents a specific model's three-year average effect of introducing a shall-issue law, computed for all states using their characteristics in 1998-2000 (AME).

Figure 4H: Average Marginal Effects - IV versus Non-IV Specifications - Property Crime
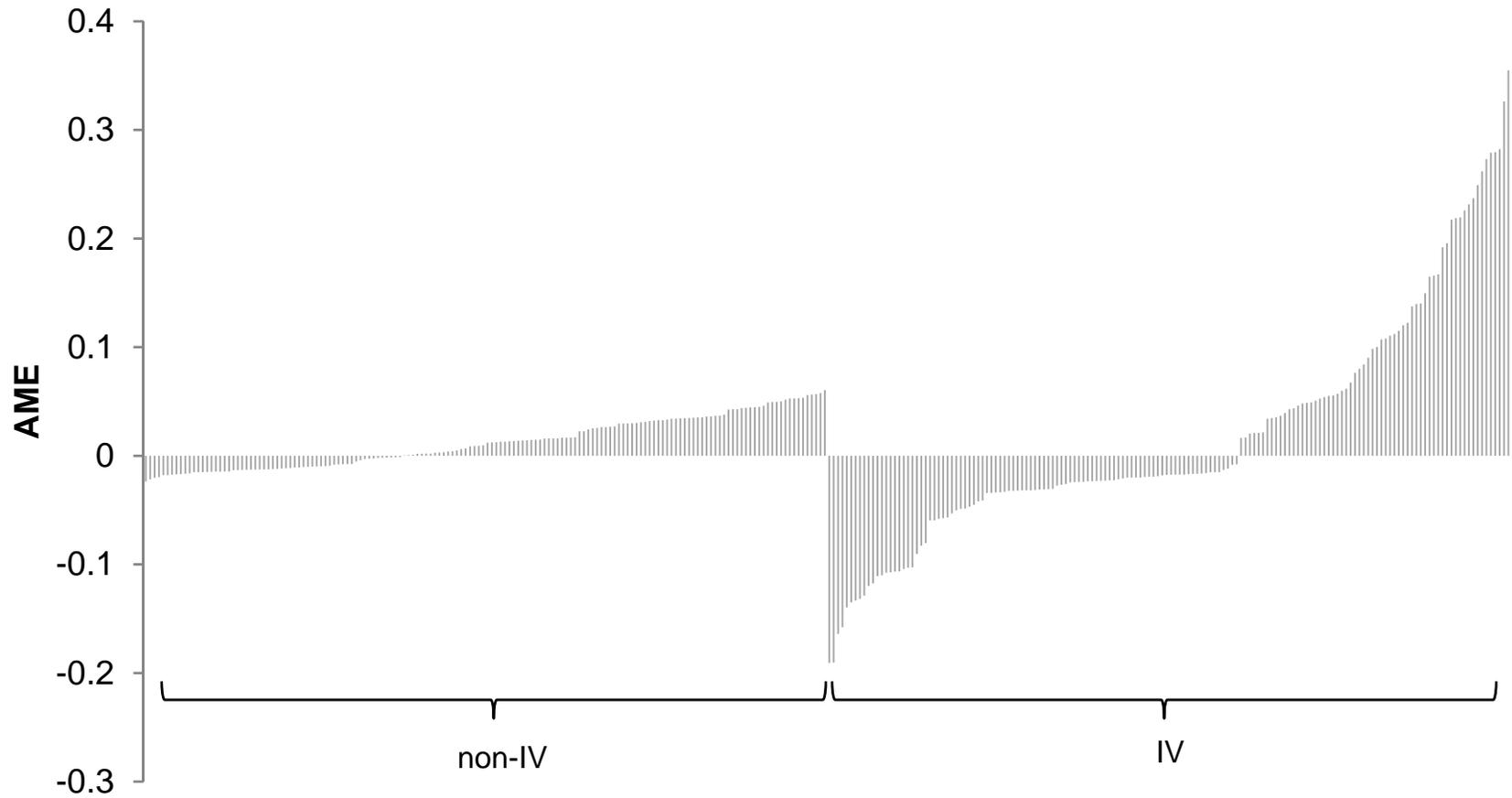
Note: Each bar represents a specific model's three-year average effect of introducing a shall-issue law, computed for all states using their characteristics in 1998-2000 (AME).

Figure 5A: Differences in the Average Marginal Effects: Models with Region Interactions - Violent Crime
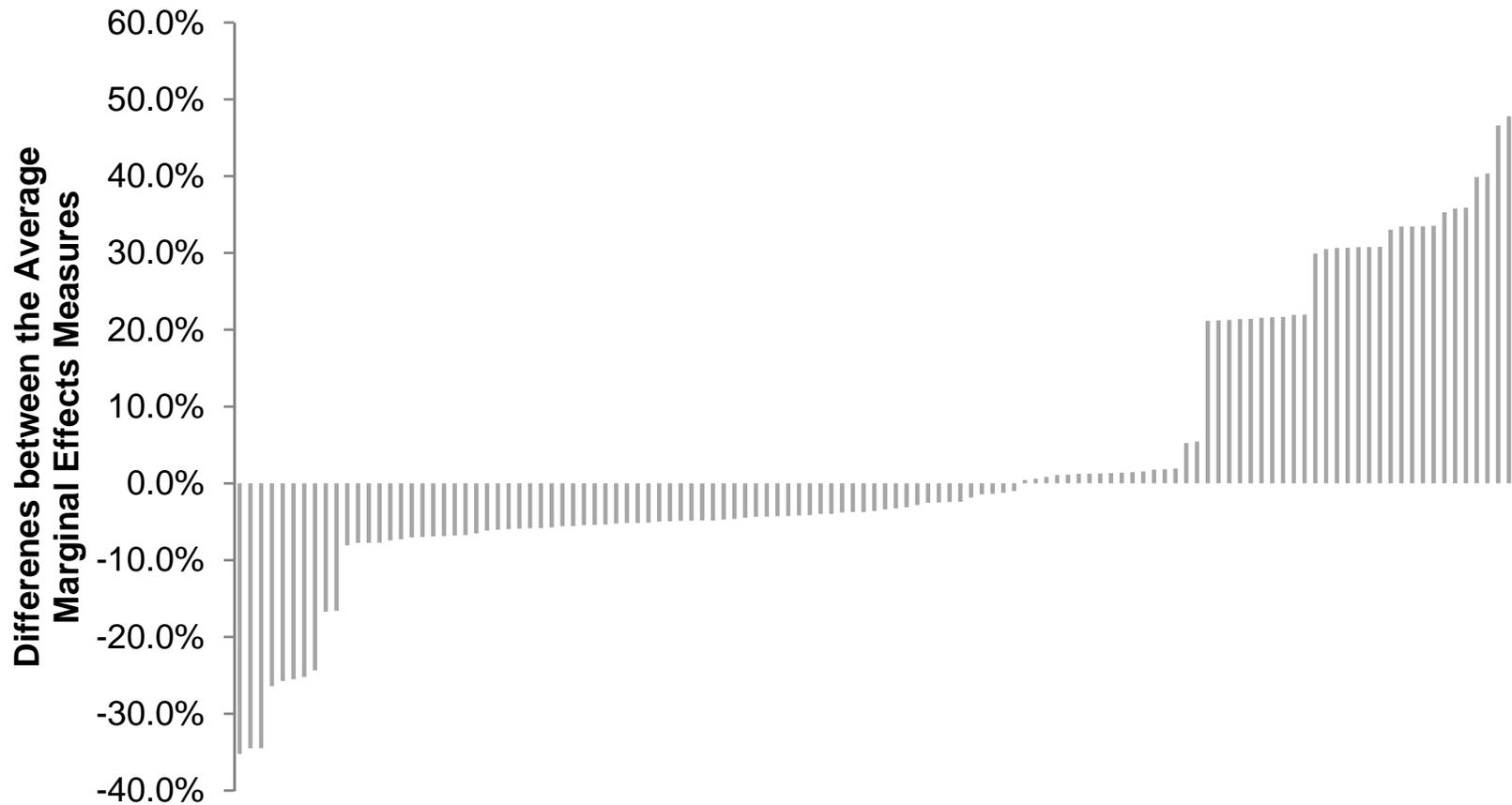
Note: Each bar represents the difference between AME-Law and AME-No Law, for each model that contains interactions of the law with region dummies. AME-Law is the three-year average marginal effect for those states that implemented the law, evaluated using the characteristics of those states that implemented the law. AME-No Law is the same, except that it is evaluated for those states that did not implement the law.

Figure 5B: Differences in the Average Marginal Effects: Models with Region Interactions - Property Crime
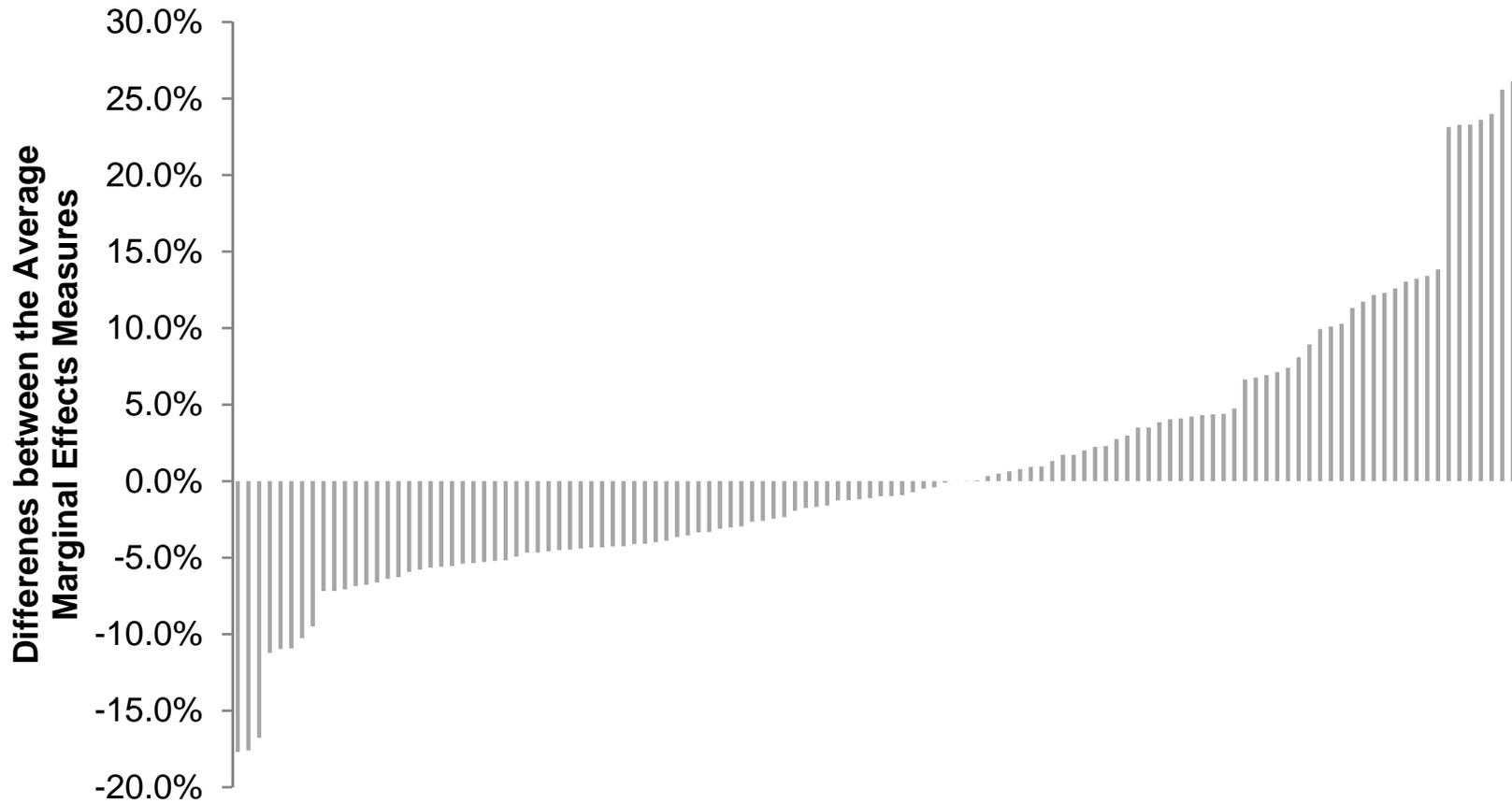
Note: Each bar represents the difference between AME-Law and AME-No Law, for each model that contains interactions of the law with region dummies. AME-Law is the three-year average marginal effect for those states that implemented the law, evaluated using the characteristics of those states that implemented the law. AME-No Law is the same, except that it is evaluated for those states that did not implement the law.

Figure 6A: Average Marginal Effects ordered by Marginal Likelihood - Violent Crime
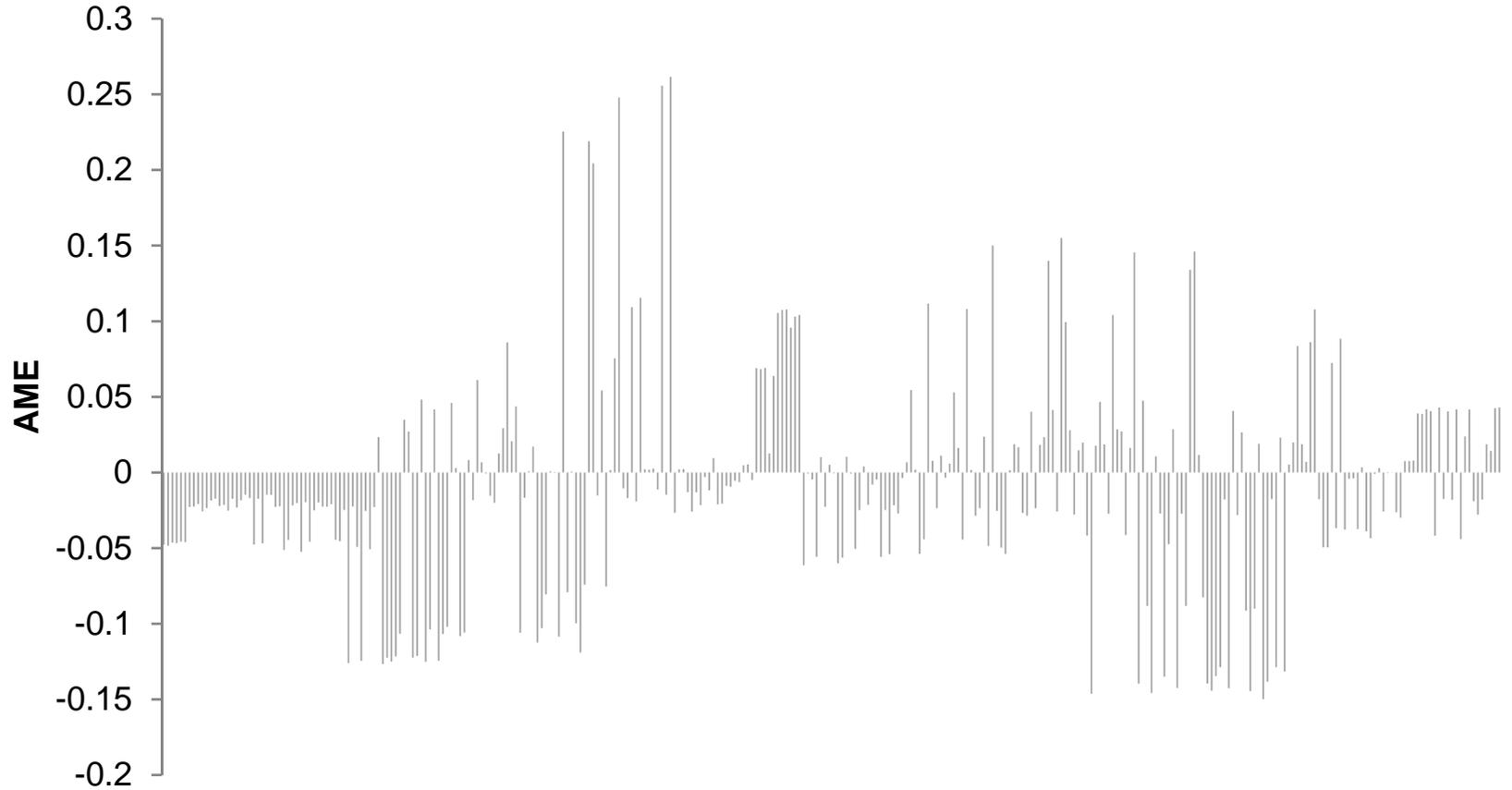
Note: Each bar represents a specific model's three-year average effect of introducing a shall-issue law, computed for all states using their characteristics in 1998-2000 (AME). The models are ordered by the value of the marginal likelihood from the lowest (on the left) to the highest (on the right).

Figure 6B: Average Marginal Effects ordered by Marginal Likelihood - Property Crime
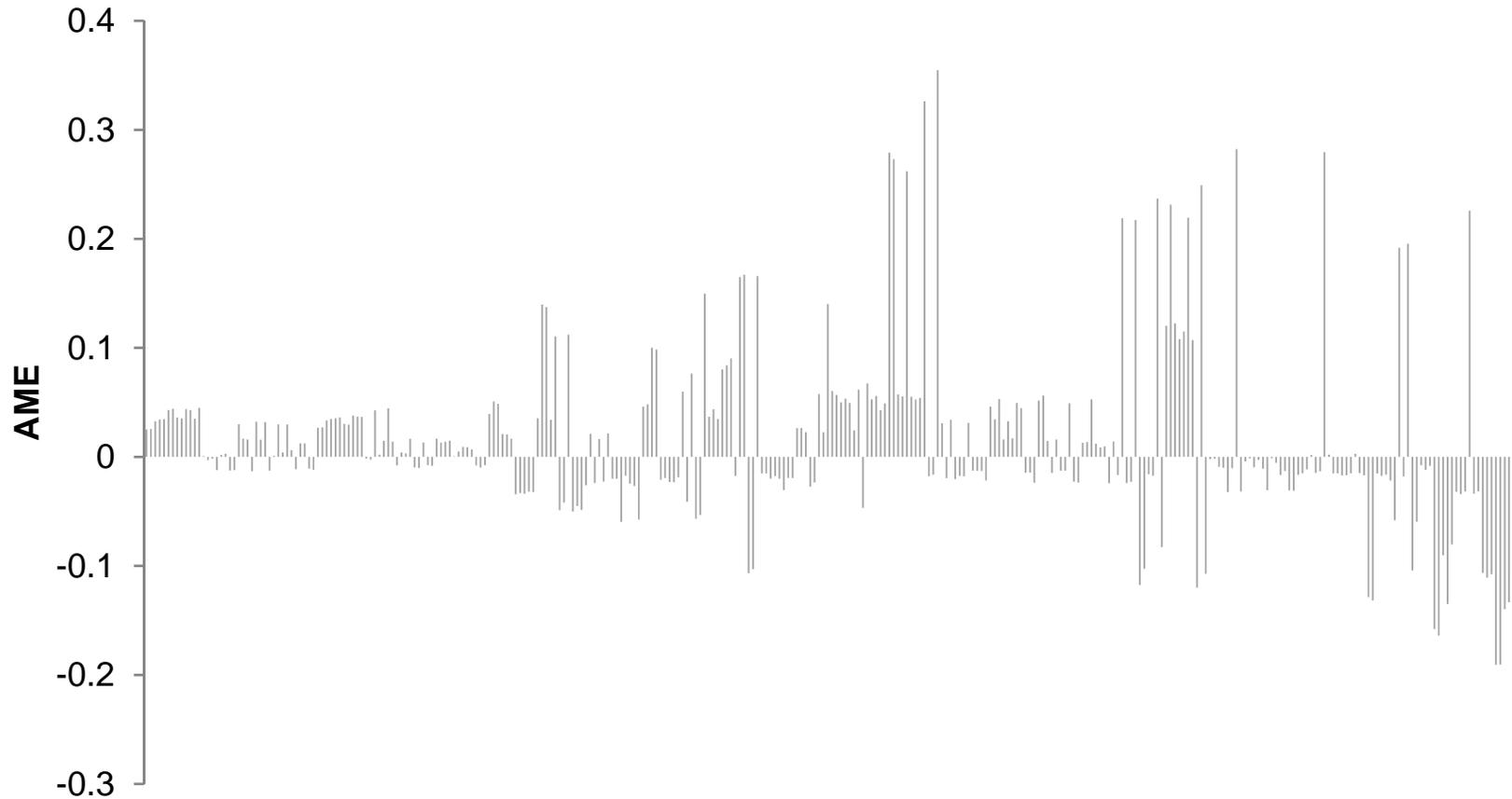
Note: Each bar represents a specific model's three-year average effect of introducing a shall-issue law, computed for all states using their characteristics in 1998-2000 (AME). The models are ordered by the value of the marginal likelihood from the lowest (on the left) to the highest (on the right).

Table 1: Model Averaging Results

Violent Crime

|	Posterior Probability	AME				AME-Law				AME-No Law			
		Year 1	Year 2	Year 3	Average	Year 1	Year 2	Year 3	Average	Year 1	Year 2	Year 3	Average
Model 1	90.1%	2.15%	4.30%	6.45%	4.30%	1.27%	2.54%	3.82%	2.54%	4.20%	8.39%	12.59%	8.39%
		(0.68%)	(1.36%)	(2.04%)	(1.36%)	(0.48%)	(0.96%)	(1.44%)	(0.96%)	(4.50%)	(8.99%)	(13.48%)	(8.99%)
Model 2	9.9%	2.13%	4.25%	6.38%	4.25%	1.26%	2.51%	3.77%	2.51%	4.16%	8.31%	12.46%	8.31%
		(0.65%)	(1.29%)	(1.94%)	(1.29%)	(0.44%)	(0.88%)	(1.31%)	(0.88%)	(4.44%)	(8.88%)	(13.32%)	(8.88%)
Model-Averaged Results		2.15%	4.29%	6.44%	4.29%	1.27%	2.54%	3.81%	2.54%	4.19%	8.39%	12.58%	8.39%
		(0.68%)	(1.35%)	(2.03%)	(1.35%)	(0.48%)	(0.95%)	(1.43%)	(0.95%)	(4.49%)	(8.98%)	(13.46%)	(8.98%)

Property Crime

	Posterior Probability	AME				AME-Law				AME-No Law			
		Year 1	Year 2	Year 3	Average	Year 1	Year 2	Year 3	Average	Year 1	Year 2	Year 3	Average
Model C	100.0%	-12.10%	-12.48%	-8.39%	-10.99%	-14.40%	-13.40%	-8.54%	-12.11%	-6.72%	-10.35%	-8.06%	-8.37%
		(1.66%)	(1.34%)	(1.20%)	(1.33%)	(1.55%)	(1.30%)	(1.16%)	(1.28%)	(1.60%)	(1.32%)	(1.18%)	(1.31%)

Notes: Model A is the spline specification that includes a subset of demographic controls, gun prevalence and gun prevalence squared as additional covariates, time dummies, interactions with region dummies, instrumental variables, and no population weights. Model B is the same as model A, except that it excludes the gun prevalence covariates. Model C is the hybrid specification that includes the full set of demographic controls, no additional covariates, time dummies, interactions with gun prevalence and urban dummies, instrumental variables, and no population weights.

AME is the average marginal effect for all states using their characteristics in 1998-2000. AME-Law and AME-No Law are the average marginal effects for states that introduced shall-issue laws, and those that did not, during the sample period, also using their characteristics in 1998-2000.

Standard errors of the average marginal effects are given in italics and parentheses below the point estimates.

			Model Specification			Log Marginal Likelihood
Formulation of the Laws	Demographics	Additional Covariates	Parameter Heterogeneity	Instrumental Variables	Time Dummies and Region Trends	
Dummy	All	None	None	IV	Time Dummies	-11503.79
Dummy	All	None	None	IV	Region Trends	-11791.37
Dummy	Subset	None	None	IV	Time Dummies	-11526.89
Dummy	Subset	None	None	IV	Region Trends	-11803.91
Dummy	All	None	GP and GP squared	IV	Time Dummies	-11500.68
Dummy	All	None	GP and GP squared	IV	Region Trends	-11797.42
Dummy	Subset	None	GP and GP squared	IV	Time Dummies	-11525.23
Dummy	Subset	None	GP and GP squared	IV	Region Trends	-11813.21
Dummy	All	None	Urban	IV	Time Dummies	-11495.82
Dummy	All	None	Urban	IV	Region Trends	-11767.23
Dummy	Subset	None	Urban	IV	Time Dummies	-11521.18
Dummy	Subset	None	Urban	IV	Region Trends	-11777.99
Dummy	All	None	Region	IV	Time Dummies	-11485.71
Dummy	All	None	Region	IV	Region Trends	-11740.85
Dummy	Subset	None	Region	IV	Time Dummies	-11481.90
Dummy	Subset	None	Region	IV	Region Trends	-11752.87
Dummy	All	None	GP and GP squared and Urban	IV	Time Dummies	-11486.05
Dummy	All	None	GP and GP squared and Urban	IV	Region Trends	-11766.33
Dummy	Subset	None	GP and GP squared and Urban	IV	Time Dummies	-11509.89
Dummy	Subset	None	GP and GP squared and Urban	IV	Region Trends	-11780.47
Dummy	All	None	GP and GP squared and Region	IV	Time Dummies	-11476.38
Dummy	All	None	GP and GP squared and Region	IV	Region Trends	-11725.69
Dummy	Subset	None	GP and GP squared and Region	IV	Time Dummies	-11474.25
Dummy	Subset	None	GP and GP squared and Region	IV	Region Trends	-11741.49
Spline	All	None	None	IV	Time Dummies	-11467.56
Spline	All	None	None	IV	Region Trends	-11669.82
Spline	Subset	None	None	IV	Time Dummies	-11638.87
Spline	Subset	None	None	IV	Region Trends	-11682.50
Spline	All	None	GP and GP squared	IV	Time Dummies	-11485.79
Spline	All	None	GP and GP squared	IV	Region Trends	-11687.53
Spline	Subset	None	GP and GP squared	IV	Time Dummies	-11517.63
Spline	Subset	None	GP and GP squared	IV	Region Trends	-11697.47
Spline	All	None	Urban	IV	Time Dummies	-11480.40
Spline	All	None	Urban	IV	Region Trends	-11668.94
Spline	Subset	None	Urban	IV	Time Dummies	-11516.97
Spline	Subset	None	Urban	IV	Region Trends	-11680.27
Spline	All	None	Region	IV	Time Dummies	-11308.73
Spline	All	None	Region	IV	Region Trends	-11497.79
Spline	Subset	None	Region	IV	Time Dummies	-11292.09
Spline	Subset	None	Region	IV	Region Trends	-11504.26
Spline	All	None	GP and GP squared and Urban	IV	Time Dummies	-11496.10
Spline	All	None	GP and GP squared and Urban	IV	Region Trends	-11689.02
Spline	Subset	None	GP and GP squared and Urban	IV	Time Dummies	-11531.97
Spline	Subset	None	GP and GP squared and Urban	IV	Region Trends	-11696.01
Spline	All	None	GP and GP squared and Region	IV	Time Dummies	-11330.95
Spline	All	None	GP and GP squared and Region	IV	Region Trends	-11513.49
Spline	Subset	None	GP and GP squared and Region	IV	Time Dummies	-11312.01
Spline	Subset	None	GP and GP squared and Region	IV	Region Trends	-11516.61
Hybrid	All	None	None	IV	Time Dummies	-11456.86
Hybrid	All	None	None	IV	Region Trends	-11737.25
Hybrid	Subset	None	None	IV	Time Dummies	-11491.85
Hybrid	Subset	None	None	IV	Region Trends	-11712.56
Hybrid	All	None	GP and GP squared	IV	Time Dummies	-11474.15
Hybrid	All	None	GP and GP squared	IV	Region Trends	-11784.61
Hybrid	Subset	None	GP and GP squared	IV	Time Dummies	-11506.92
Hybrid	Subset	None	GP and GP squared	IV	Region Trends	-11803.04
Hybrid	All	None	Urban	IV	Time Dummies	-11426.21
Hybrid	All	None	Urban	IV	Region Trends	-11727.04
Hybrid	Subset	None	Urban	IV	Time Dummies	-11467.71
Hybrid	Subset	None	Urban	IV	Region Trends	-11721.17
Hybrid	All	None	Region	IV	Time Dummies	-11301.82
Hybrid	All	None	Region	IV	Region Trends	-11609.76
Hybrid	Subset	None	Region	IV	Time Dummies	-11296.53
Hybrid	Subset	None	Region	IV	Region Trends	-11625.41
Hybrid	All	None	GP and GP squared and Urban	IV	Time Dummies	-11445.83
Hybrid	All	None	GP and GP squared and Urban	IV	Region Trends	-11757.38
Hybrid	Subset	None	GP and GP squared and Urban	IV	Time Dummies	-11481.40
Hybrid	Subset	None	GP and GP squared and Urban	IV	Region Trends	-11763.69
Hybrid	All	None	GP and GP squared and Region	IV	Time Dummies	-11306.08
Hybrid	All	None	GP and GP squared and Region	IV	Region Trends	-11638.14
Hybrid	Subset	None	GP and GP squared and Region	IV	Time Dummies	-11299.35
Hybrid	Subset	None	GP and GP squared and Region	IV	Region Trends	-11651.15
Dummy	All	Urban	None	IV	Time Dummies	-11510.51
Dummy	All	Urban	None	IV	Region Trends	-11799.63
Dummy	Subset	Urban	None	IV	Time Dummies	-11537.50
Dummy	Subset	Urban	None	IV	Region Trends	-11814.40
Dummy	All	Urban	GP and GP squared	IV	Time Dummies	-11509.58
Dummy	All	Urban	GP and GP squared	IV	Region Trends	-11807.19
Dummy	Subset	Urban	GP and GP squared	IV	Time Dummies	-11535.24

Formulation of the Laws	Demographics	Additional Covariates	Parameter Heterogeneity	Instrumental Variables	Time Dummies and Region Trends	Log Marginal Likelihood
Dummy	Subset	Urban	GP and GP squared	IV	Region Trends	-11823.92
Dummy	All	Urban	Region	IV	Time Dummies	-11494.44
Dummy	All	Urban	Region	IV	Region Trends	-11750.41
Dummy	Subset	Urban	Region	IV	Time Dummies	-11491.54
Dummy	Subset	Urban	Region	IV	Region Trends	-11763.48
Dummy	All	Urban	GP and GP squared and Region	IV	Time Dummies	-11486.93
Dummy	All	Urban	GP and GP squared and Region	IV	Region Trends	-11737.39
Dummy	Subset	Urban	GP and GP squared and Region	IV	Time Dummies	-11485.35
Dummy	Subset	Urban	GP and GP squared and Region	IV	Region Trends	-11752.80
Spline	All	Urban	None	IV	Time Dummies	-11475.28
Spline	All	Urban	None	IV	Region Trends	-11678.73
Spline	Subset	Urban	None	IV	Time Dummies	-11772.10
Spline	Subset	Urban	None	IV	Region Trends	-11692.96
Spline	All	Urban	GP and GP squared	IV	Time Dummies	-11494.00
Spline	All	Urban	GP and GP squared	IV	Region Trends	-11698.21
Spline	Subset	Urban	GP and GP squared	IV	Time Dummies	-11527.10
Spline	Subset	Urban	GP and GP squared	IV	Region Trends	-11707.46
Spline	All	Urban	Region	IV	Time Dummies	-11320.28
Spline	All	Urban	Region	IV	Region Trends	-11507.10
Spline	Subset	Urban	Region	IV	Time Dummies	-11302.38
Spline	Subset	Urban	Region	IV	Region Trends	-11515.14
Spline	All	Urban	GP and GP squared and Region	IV	Time Dummies	-11339.89
Spline	All	Urban	GP and GP squared and Region	IV	Region Trends	-11523.36
Spline	Subset	Urban	GP and GP squared and Region	IV	Time Dummies	-11321.76
Spline	Subset	Urban	GP and GP squared and Region	IV	Region Trends	-11526.84
Hybrid	All	Urban	None	IV	Time Dummies	-11464.64
Hybrid	All	Urban	None	IV	Region Trends	-11746.01
Hybrid	Subset	Urban	None	IV	Time Dummies	-11502.85
Hybrid	Subset	Urban	None	IV	Region Trends	-11723.03
Hybrid	All	Urban	GP and GP squared	IV	Time Dummies	-11481.92
Hybrid	All	Urban	GP and GP squared	IV	Region Trends	-11795.70
Hybrid	Subset	Urban	GP and GP squared	IV	Time Dummies	-11516.17
Hybrid	Subset	Urban	GP and GP squared	IV	Region Trends	-11813.25
Hybrid	All	Urban	Region	IV	Time Dummies	-11310.26
Hybrid	All	Urban	Region	IV	Region Trends	-11619.58
Hybrid	Subset	Urban	Region	IV	Time Dummies	-11305.23
Hybrid	Subset	Urban	Region	IV	Region Trends	-11635.56
Hybrid	All	Urban	GP and GP squared and Region	IV	Time Dummies	-11317.73
Hybrid	All	Urban	GP and GP squared and Region	IV	Region Trends	-11648.83
Hybrid	Subset	Urban	GP and GP squared and Region	IV	Time Dummies	-11308.07
Hybrid	Subset	Urban	GP and GP squared and Region	IV	Region Trends	-11661.23
Dummy	All	GP and GP squared	None	IV	Time Dummies	-11494.75
Dummy	All	GP and GP squared	None	IV	Region Trends	-11787.53
Dummy	Subset	GP and GP squared	None	IV	Time Dummies	-11515.84
Dummy	Subset	GP and GP squared	None	IV	Region Trends	-11800.52
Dummy	All	GP and GP squared	Urban	IV	Time Dummies	-11486.92
Dummy	All	GP and GP squared	Urban	IV	Region Trends	-11765.60
Dummy	Subset	GP and GP squared	Urban	IV	Time Dummies	-11511.15
Dummy	Subset	GP and GP squared	Urban	IV	Region Trends	-11775.99
Dummy	All	GP and GP squared	Region	IV	Time Dummies	-11480.10
Dummy	All	GP and GP squared	Region	IV	Region Trends	-11740.16
Dummy	Subset	GP and GP squared	Region	IV	Time Dummies	-11474.97
Dummy	Subset	GP and GP squared	Region	IV	Region Trends	-11753.12
Spline	All	GP and GP squared	None	IV	Time Dummies	-11460.07
Spline	All	GP and GP squared	None	IV	Region Trends	-11667.15
Spline	Subset	GP and GP squared	None	IV	Time Dummies	-11687.29
Spline	Subset	GP and GP squared	None	IV	Region Trends	-11680.60
Spline	All	GP and GP squared	Urban	IV	Time Dummies	-11471.71
Spline	All	GP and GP squared	Urban	IV	Region Trends	-11669.19
Spline	Subset	GP and GP squared	Urban	IV	Time Dummies	-11506.87
Spline	Subset	GP and GP squared	Urban	IV	Region Trends	-11678.83
Spline	All	GP and GP squared	Region	IV	Time Dummies	-11306.53
Spline	All	GP and GP squared	Region	IV	Region Trends	-11498.76
Spline	Subset	GP and GP squared	Region	IV	Time Dummies	-11289.88
Spline	Subset	GP and GP squared	Region	IV	Region Trends	-11506.78
Hybrid	All	GP and GP squared	None	IV	Time Dummies	-11448.14
Hybrid	All	GP and GP squared	None	IV	Region Trends	-11733.44
Hybrid	Subset	GP and GP squared	None	IV	Time Dummies	-11481.65
Hybrid	Subset	GP and GP squared	None	IV	Region Trends	-11707.71
Hybrid	All	GP and GP squared	Urban	IV	Time Dummies	-11420.48
Hybrid	All	GP and GP squared	Urban	IV	Region Trends	-11723.79
Hybrid	Subset	GP and GP squared	Urban	IV	Time Dummies	-11459.63
Hybrid	Subset	GP and GP squared	Urban	IV	Region Trends	-11716.55
Hybrid	All	GP and GP squared	Region	IV	Time Dummies	-11300.13
Hybrid	All	GP and GP squared	Region	IV	Region Trends	-11614.41
Hybrid	Subset	GP and GP squared	Region	IV	Time Dummies	-11295.27
Hybrid	Subset	GP and GP squared	Region	non-IV	Region Trends	-11630.81
Dummy	All	None	None	non-IV	Time Dummies	-11534.21
Dummy	All	None	None	non-IV	Region Trends	-11852.26

Formulation of the Laws	Demographics	Additional Covariates	Parameter Heterogeneity	Instrumental Variables	Time Dummies and Region Trends	Log Marginal Likelihood
Dummy	Subset	None	None	non-IV	Time Dummies	-11563.23
Dummy	Subset	None	None	non-IV	Region Trends	-11856.71
Dummy	All	None	GP and GP squared	non-IV	Time Dummies	-11540.50
Dummy	All	None	GP and GP squared	non-IV	Region Trends	-11861.64
Dummy	Subset	None	GP and GP squared	non-IV	Time Dummies	-11568.73
Dummy	Subset	None	GP and GP squared	non-IV	Region Trends	-11866.92
Dummy	All	None	Urban	non-IV	Time Dummies	-11536.97
Dummy	All	None	Urban	non-IV	Region Trends	-11854.56
Dummy	Subset	None	Urban	non-IV	Time Dummies	-11570.33
Dummy	Subset	None	Urban	non-IV	Region Trends	-11855.63
Dummy	All	None	Region	non-IV	Time Dummies	-11473.02
Dummy	All	None	Region	non-IV	Region Trends	-11808.55
Dummy	Subset	None	Region	non-IV	Time Dummies	-11485.39
Dummy	Subset	None	Region	non-IV	Region Trends	-11811.85
Dummy	All	None	GP and GP squared and Urban	non-IV	Time Dummies	-11548.40
Dummy	All	None	GP and GP squared and Urban	non-IV	Region Trends	-11864.98
Dummy	Subset	None	GP and GP squared and Urban	non-IV	Time Dummies	-11575.91
Dummy	Subset	None	GP and GP squared and Urban	non-IV	Region Trends	-11866.26
Dummy	All	None	GP and GP squared and Region	non-IV	Time Dummies	-11484.79
Dummy	All	None	GP and GP squared and Region	non-IV	Region Trends	-11819.20
Dummy	Subset	None	GP and GP squared and Region	non-IV	Time Dummies	-11494.02
Dummy	Subset	None	GP and GP squared and Region	non-IV	Region Trends	-11822.50
Spline	All	None	None	non-IV	Time Dummies	-11493.32
Spline	All	None	None	non-IV	Region Trends	-11832.21
Spline	Subset	None	None	non-IV	Time Dummies	-11523.82
Spline	Subset	None	None	non-IV	Region Trends	-11833.44
Spline	All	None	GP and GP squared	non-IV	Time Dummies	-11516.05
Spline	All	None	GP and GP squared	non-IV	Region Trends	-11864.77
Spline	Subset	None	GP and GP squared	non-IV	Time Dummies	-11545.82
Spline	Subset	None	GP and GP squared	non-IV	Region Trends	-11865.05
Spline	All	None	Urban	non-IV	Time Dummies	-11519.90
Spline	All	None	Urban	non-IV	Region Trends	-11846.22
Spline	Subset	None	Urban	non-IV	Time Dummies	-11551.92
Spline	Subset	None	Urban	non-IV	Region Trends	-11846.27
Spline	All	None	Region	non-IV	Time Dummies	-11371.01
Spline	All	None	Region	non-IV	Region Trends	-11713.76
Spline	Subset	None	Region	non-IV	Time Dummies	-11353.65
Spline	Subset	None	Region	non-IV	Region Trends	-11705.74
Spline	All	None	GP and GP squared and Urban	non-IV	Time Dummies	-11540.79
Spline	All	None	GP and GP squared and Urban	non-IV	Region Trends	-11876.73
Spline	Subset	None	GP and GP squared and Urban	non-IV	Time Dummies	-11572.67
Spline	Subset	None	GP and GP squared and Urban	non-IV	Region Trends	-11877.85
Spline	All	None	GP and GP squared and Region	non-IV	Time Dummies	-11400.00
Spline	All	None	GP and GP squared and Region	non-IV	Region Trends	-11750.84
Spline	Subset	None	GP and GP squared and Region	non-IV	Time Dummies	-11378.92
Spline	Subset	None	GP and GP squared and Region	non-IV	Region Trends	-11741.02
Hybrid	All	None	None	non-IV	Time Dummies	-11497.12
Hybrid	All	None	None	non-IV	Region Trends	-11835.35
Hybrid	Subset	None	None	non-IV	Time Dummies	-11526.23
Hybrid	Subset	None	None	non-IV	Region Trends	-11837.03
Hybrid	All	None	GP and GP squared	non-IV	Time Dummies	-11536.92
Hybrid	All	None	GP and GP squared	non-IV	Region Trends	-11881.65
Hybrid	Subset	None	GP and GP squared	non-IV	Time Dummies	-11564.22
Hybrid	Subset	None	GP and GP squared	non-IV	Region Trends	-11883.49
Hybrid	All	None	Urban	non-IV	Time Dummies	-11522.12
Hybrid	All	None	Urban	non-IV	Region Trends	-11856.54
Hybrid	Subset	None	Urban	non-IV	Time Dummies	-11555.72
Hybrid	Subset	None	Urban	non-IV	Region Trends	-11854.98
Hybrid	All	None	Region	non-IV	Time Dummies	-11386.81
Hybrid	All	None	Region	non-IV	Region Trends	-11721.50
Hybrid	Subset	None	Region	non-IV	Time Dummies	-11368.28
Hybrid	Subset	None	Region	non-IV	Region Trends	-11712.62
Hybrid	All	None	GP and GP squared and Urban	non-IV	Time Dummies	-11565.34
Hybrid	All	None	GP and GP squared and Urban	non-IV	Region Trends	-11900.54
Hybrid	Subset	None	GP and GP squared and Urban	non-IV	Time Dummies	-11593.49
Hybrid	Subset	None	GP and GP squared and Urban	non-IV	Region Trends	-11902.35
Hybrid	All	None	GP and GP squared and Region	non-IV	Time Dummies	-11431.17
Hybrid	All	None	GP and GP squared and Region	non-IV	Region Trends	-11772.40
Hybrid	Subset	None	GP and GP squared and Region	non-IV	Time Dummies	-11410.05
Hybrid	Subset	None	GP and GP squared and Region	non-IV	Region Trends	-11763.22
Dummy	All	Urban	None	non-IV	Time Dummies	-11539.45
Dummy	All	Urban	None	non-IV	Region Trends	-11861.59
Dummy	Subset	Urban	None	non-IV	Time Dummies	-11573.14
Dummy	Subset	Urban	None	non-IV	Region Trends	-11867.19
Dummy	All	Urban	GP and GP squared	non-IV	Time Dummies	-11548.30
Dummy	All	Urban	GP and GP squared	non-IV	Region Trends	-11872.18
Dummy	Subset	Urban	GP and GP squared	non-IV	Time Dummies	-11578.53
Dummy	Subset	Urban	GP and GP squared	non-IV	Region Trends	-11877.16
Dummy	All	Urban	Region	non-IV	Time Dummies	-11483.61

Formulation of the Laws	Demographics	Additional Covariates	Parameter Heterogeneity	Instrumental Variables	Time Dummies and Region Trends	Log Marginal Likelihood
Dummy	All	Urban	Region	non-IV	Region Trends	-11818.72
Dummy	Subset	Urban	Region	non-IV	Time Dummies	-11495.73
Dummy	Subset	Urban	Region	non-IV	Region Trends	-11822.06
Dummy	All	Urban	GP and GP squared and Region	non-IV	Time Dummies	-11492.96
Dummy	All	Urban	GP and GP squared and Region	non-IV	Region Trends	-11829.57
Dummy	Subset	Urban	GP and GP squared and Region	non-IV	Time Dummies	-11504.30
Dummy	Subset	Urban	GP and GP squared and Region	non-IV	Region Trends	-11832.84
Spline	All	Urban	None	non-IV	Time Dummies	-11501.75
Spline	All	Urban	None	non-IV	Region Trends	-11841.71
Spline	Subset	Urban	None	non-IV	Time Dummies	-11533.04
Spline	Subset	Urban	None	non-IV	Region Trends	-11843.55
Spline	All	Urban	GP and GP squared	non-IV	Time Dummies	-11524.13
Spline	All	Urban	GP and GP squared	non-IV	Region Trends	-11872.34
Spline	Subset	Urban	GP and GP squared	non-IV	Time Dummies	-11554.68
Spline	Subset	Urban	GP and GP squared	non-IV	Region Trends	-11875.02
Spline	All	Urban	Region	non-IV	Time Dummies	-11380.93
Spline	All	Urban	Region	non-IV	Region Trends	-11724.89
Spline	Subset	Urban	Region	non-IV	Time Dummies	-11363.11
Spline	Subset	Urban	Region	non-IV	Region Trends	-11715.74
Spline	All	Urban	GP and GP squared and Region	non-IV	Time Dummies	-11408.46
Spline	All	Urban	GP and GP squared and Region	non-IV	Region Trends	-11758.73
Spline	Subset	Urban	GP and GP squared and Region	non-IV	Time Dummies	-11389.32
Spline	Subset	Urban	GP and GP squared and Region	non-IV	Region Trends	-11751.59
Hybrid	All	Urban	None	non-IV	Time Dummies	-11506.52
Hybrid	All	Urban	None	non-IV	Region Trends	-11845.23
Hybrid	Subset	Urban	None	non-IV	Time Dummies	-11536.05
Hybrid	Subset	Urban	None	non-IV	Region Trends	-11847.25
Hybrid	All	Urban	GP and GP squared	non-IV	Time Dummies	-11544.47
Hybrid	All	Urban	GP and GP squared	non-IV	Region Trends	-11890.84
Hybrid	Subset	Urban	GP and GP squared	non-IV	Time Dummies	-11574.82
Hybrid	Subset	Urban	GP and GP squared	non-IV	Region Trends	-11894.17
Hybrid	All	Urban	Region	non-IV	Time Dummies	-11396.20
Hybrid	All	Urban	Region	non-IV	Region Trends	-11731.19
Hybrid	Subset	Urban	Region	non-IV	Time Dummies	-11378.71
Hybrid	Subset	Urban	Region	non-IV	Region Trends	-11722.91
Hybrid	All	Urban	GP and GP squared and Region	non-IV	Time Dummies	-11439.53
Hybrid	All	Urban	GP and GP squared and Region	non-IV	Region Trends	-11781.76
Hybrid	Subset	Urban	GP and GP squared and Region	non-IV	Time Dummies	-11420.86
Hybrid	Subset	Urban	GP and GP squared and Region	non-IV	Region Trends	-11773.37
Dummy	All	GP and GP squared	None	non-IV	Time Dummies	-11524.60
Dummy	All	GP and GP squared	None	non-IV	Region Trends	-11843.52
Dummy	Subset	GP and GP squared	None	non-IV	Time Dummies	-11552.58
Dummy	Subset	GP and GP squared	None	non-IV	Region Trends	-11848.68
Dummy	All	GP and GP squared	Urban	non-IV	Time Dummies	-11529.56
Dummy	All	GP and GP squared	Urban	non-IV	Region Trends	-11845.78
Dummy	Subset	GP and GP squared	Urban	non-IV	Time Dummies	-11559.25
Dummy	Subset	GP and GP squared	Urban	non-IV	Region Trends	-11848.24
Dummy	All	GP and GP squared	Region	non-IV	Time Dummies	-11467.96
Dummy	All	GP and GP squared	Region	non-IV	Region Trends	-11802.26
Dummy	Subset	GP and GP squared	Region	non-IV	Time Dummies	-11478.65
Dummy	Subset	GP and GP squared	Region	non-IV	Region Trends	-11804.76
Spline	All	GP and GP squared	None	non-IV	Time Dummies	-11487.25
Spline	All	GP and GP squared	None	non-IV	Region Trends	-11825.71
Spline	Subset	GP and GP squared	None	non-IV	Time Dummies	-11515.23
Spline	Subset	GP and GP squared	None	non-IV	Region Trends	-11827.35
Spline	All	GP and GP squared	Urban	non-IV	Time Dummies	-11510.37
Spline	All	GP and GP squared	Urban	non-IV	Region Trends	-11838.31
Spline	Subset	GP and GP squared	Urban	non-IV	Time Dummies	-11542.30
Spline	Subset	GP and GP squared	Urban	non-IV	Region Trends	-11839.50
Spline	All	GP and GP squared	Region	non-IV	Time Dummies	-11369.51
Spline	All	GP and GP squared	Region	non-IV	Region Trends	-11712.64
Spline	Subset	GP and GP squared	Region	non-IV	Time Dummies	-11352.01
Spline	Subset	GP and GP squared	Region	non-IV	Region Trends	-11704.26
Hybrid	All	GP and GP squared	None	non-IV	Time Dummies	-11492.54
Hybrid	All	GP and GP squared	None	non-IV	Region Trends	-11827.05
Hybrid	Subset	GP and GP squared	None	non-IV	Time Dummies	-11518.57
Hybrid	Subset	GP and GP squared	None	non-IV	Region Trends	-11829.62
Hybrid	All	GP and GP squared	Urban	non-IV	Time Dummies	-11518.27
Hybrid	All	GP and GP squared	Urban	non-IV	Region Trends	-11846.10
Hybrid	Subset	GP and GP squared	Urban	non-IV	Time Dummies	-11547.99
Hybrid	Subset	GP and GP squared	Urban	non-IV	Region Trends	-11848.10
Hybrid	All	GP and GP squared	Region	non-IV	Time Dummies	-11384.38
Hybrid	All	GP and GP squared	Region	non-IV	Region Trends	-11718.92
Hybrid	Subset	GP and GP squared	Region	non-IV	Time Dummies	-11365.46
Hybrid	Subset	GP and GP squared	Region	non-IV	Region Trends	-11709.37

Note: Each line corresponds to a specific model. Every specification excludes population weights. GP stands for gun prevalence. For a description of the various modeling assumptions see Section 3.

Formulation of the Laws	Demographics	Additional Covariates	Parameter Heterogeneity	Instrumental Variables	Time Dummies and Region Trends	Log Marginal Likelihood
Dummy	All	None	None	IV	Time Dummies	-35.89
Dummy	All	None	None	IV	Region Trends	-401.25
Dummy	Subset	None	None	IV	Time Dummies	-203.37
Dummy	Subset	None	None	IV	Region Trends	-507.66
Dummy	All	None	GP and GP squared	IV	Time Dummies	75.72
Dummy	All	None	GP and GP squared	IV	Region Trends	-348.28
Dummy	Subset	None	GP and GP squared	IV	Time Dummies	-54.28
Dummy	Subset	None	GP and GP squared	IV	Region Trends	-403.52
Dummy	All	None	Urban	IV	Time Dummies	34.46
Dummy	All	None	Urban	IV	Region Trends	-329.57
Dummy	Subset	None	Urban	IV	Time Dummies	-129.63
Dummy	Subset	None	Urban	IV	Region Trends	-415.46
Dummy	All	None	Region	IV	Time Dummies	-33.52
Dummy	All	None	Region	IV	Region Trends	-366.83
Dummy	Subset	None	Region	IV	Time Dummies	-181.19
Dummy	Subset	None	Region	IV	Region Trends	-452.38
Dummy	All	None	GP and GP squared and Urban	IV	Time Dummies	128.12
Dummy	All	None	GP and GP squared and Urban	IV	Region Trends	-272.92
Dummy	Subset	None	GP and GP squared and Urban	IV	Time Dummies	-3.93
Dummy	Subset	None	GP and GP squared and Urban	IV	Region Trends	-322.21
Dummy	All	None	GP and GP squared and Region	IV	Time Dummies	-23.79
Dummy	All	None	GP and GP squared and Region	IV	Region Trends	-350.69
Dummy	Subset	None	GP and GP squared and Region	IV	Time Dummies	-176.16
Dummy	Subset	None	GP and GP squared and Region	IV	Region Trends	-411.64
Spline	All	None	None	IV	Time Dummies	61.86
Spline	All	None	None	IV	Region Trends	-341.69
Spline	Subset	None	None	IV	Time Dummies	-73.75
Spline	Subset	None	None	IV	Region Trends	-419.02
Spline	All	None	GP and GP squared	IV	Time Dummies	70.56
Spline	All	None	GP and GP squared	IV	Region Trends	-353.75
Spline	Subset	None	GP and GP squared	IV	Time Dummies	-51.87
Spline	Subset	None	GP and GP squared	IV	Region Trends	-421.19
Spline	All	None	Urban	IV	Time Dummies	94.30
Spline	All	None	Urban	IV	Region Trends	-288.34
Spline	Subset	None	Urban	IV	Time Dummies	-56.44
Spline	Subset	None	Urban	IV	Region Trends	-368.28
Spline	All	None	Region	IV	Time Dummies	124.36
Spline	All	None	Region	IV	Region Trends	-282.92
Spline	Subset	None	Region	IV	Time Dummies	32.52
Spline	Subset	None	Region	IV	Region Trends	-357.19
Spline	All	None	GP and GP squared and Urban	IV	Time Dummies	96.44
Spline	All	None	GP and GP squared and Urban	IV	Region Trends	-304.18
Spline	Subset	None	GP and GP squared and Urban	IV	Time Dummies	-37.08
Spline	Subset	None	GP and GP squared and Urban	IV	Region Trends	-373.65
Spline	All	None	GP and GP squared and Region	IV	Time Dummies	121.40
Spline	All	None	GP and GP squared and Region	IV	Region Trends	-280.30
Spline	Subset	None	GP and GP squared and Region	IV	Time Dummies	42.81
Spline	Subset	None	GP and GP squared and Region	IV	Region Trends	-339.71
Hybrid	All	None	None	IV	Time Dummies	75.55
Hybrid	All	None	None	IV	Region Trends	-308.19
Hybrid	Subset	None	None	IV	Time Dummies	-48.06
Hybrid	Subset	None	None	IV	Region Trends	-298.96
Hybrid	All	None	GP and GP squared	IV	Time Dummies	192.35
Hybrid	All	None	GP and GP squared	IV	Region Trends	-329.02
Hybrid	Subset	None	GP and GP squared	IV	Time Dummies	102.00
Hybrid	Subset	None	GP and GP squared	IV	Region Trends	-402.21
Hybrid	All	None	Urban	IV	Time Dummies	109.88
Hybrid	All	None	Urban	IV	Region Trends	-235.81
Hybrid	Subset	None	Urban	IV	Time Dummies	-15.15
Hybrid	Subset	None	Urban	IV	Region Trends	-259.76
Hybrid	All	None	Region	IV	Time Dummies	144.73
Hybrid	All	None	Region	IV	Region Trends	-276.74
Hybrid	Subset	None	Region	IV	Time Dummies	44.82
Hybrid	Subset	None	Region	IV	Region Trends	-312.23
Hybrid	All	None	GP and GP squared and Urban	IV	Time Dummies	219.46
Hybrid	All	None	GP and GP squared and Urban	IV	Region Trends	-256.63
Hybrid	Subset	None	GP and GP squared and Urban	IV	Time Dummies	120.05
Hybrid	Subset	None	GP and GP squared and Urban	IV	Region Trends	-330.07
Hybrid	All	None	GP and GP squared and Region	IV	Time Dummies	165.11
Hybrid	All	None	GP and GP squared and Region	IV	Region Trends	-296.92
Hybrid	Subset	None	GP and GP squared and Region	IV	Time Dummies	64.02
Hybrid	Subset	None	GP and GP squared and Region	IV	Region Trends	-352.56
Dummy	All	Urban	None	IV	Time Dummies	-27.86
Dummy	All	Urban	None	IV	Region Trends	-404.12
Dummy	Subset	Urban	None	IV	Time Dummies	-200.30
Dummy	Subset	Urban	None	IV	Region Trends	-513.68
Dummy	All	Urban	GP and GP squared	IV	Time Dummies	81.87
Dummy	All	Urban	GP and GP squared	IV	Region Trends	-348.24
Dummy	Subset	Urban	GP and GP squared	IV	Time Dummies	-50.16

Table A-2: Likelihood - Property Crime

Formulation of the Laws	Demographics	Additional Covariates	Parameter Heterogeneity	Instrumental Variables	Time Dummies and Region Trends	Log Marginal Likelihood
Dummy	Subset	Urban	GP and GP squared	IV	Region Trends	-408.86
Dummy	All	Urban	Region	IV	Time Dummies	-26.18
Dummy	All	Urban	Region	IV	Region Trends	-369.79
Dummy	Subset	Urban	Region	IV	Time Dummies	-180.72
Dummy	Subset	Urban	Region	IV	Region Trends	-457.00
Dummy	All	Urban	GP and GP squared and Region	IV	Time Dummies	-16.39
Dummy	All	Urban	GP and GP squared and Region	IV	Region Trends	-352.49
Dummy	Subset	Urban	GP and GP squared and Region	IV	Time Dummies	-173.64
Dummy	Subset	Urban	GP and GP squared and Region	IV	Region Trends	-416.01
Spline	All	Urban	None	IV	Time Dummies	71.99
Spline	All	Urban	None	IV	Region Trends	-342.70
Spline	Subset	Urban	None	IV	Time Dummies	-72.40
Spline	Subset	Urban	None	IV	Region Trends	-422.93
Spline	All	Urban	GP and GP squared	IV	Time Dummies	79.38
Spline	All	Urban	GP and GP squared	IV	Region Trends	-353.71
Spline	Subset	Urban	GP and GP squared	IV	Time Dummies	-51.04
Spline	Subset	Urban	GP and GP squared	IV	Region Trends	-424.73
Spline	All	Urban	Region	IV	Time Dummies	131.83
Spline	All	Urban	Region	IV	Region Trends	-283.72
Spline	Subset	Urban	Region	IV	Time Dummies	35.03
Spline	Subset	Urban	Region	IV	Region Trends	-360.26
Spline	All	Urban	GP and GP squared and Region	IV	Time Dummies	125.01
Spline	All	Urban	GP and GP squared and Region	IV	Region Trends	-279.08
Spline	Subset	Urban	GP and GP squared and Region	IV	Time Dummies	47.06
Spline	Subset	Urban	GP and GP squared and Region	IV	Region Trends	-343.37
Hybrid	All	Urban	None	IV	Time Dummies	82.01
Hybrid	All	Urban	None	IV	Region Trends	-307.46
Hybrid	Subset	Urban	None	IV	Time Dummies	-45.96
Hybrid	Subset	Urban	None	IV	Region Trends	-300.29
Hybrid	All	Urban	GP and GP squared	IV	Time Dummies	202.42
Hybrid	All	Urban	GP and GP squared	IV	Region Trends	-329.32
Hybrid	Subset	Urban	GP and GP squared	IV	Time Dummies	107.93
Hybrid	Subset	Urban	GP and GP squared	IV	Region Trends	-405.88
Hybrid	All	Urban	Region	IV	Time Dummies	149.41
Hybrid	All	Urban	Region	IV	Region Trends	-274.41
Hybrid	Subset	Urban	Region	IV	Time Dummies	45.55
Hybrid	Subset	Urban	Region	IV	Region Trends	-313.24
Hybrid	All	Urban	GP and GP squared and Region	IV	Time Dummies	171.49
Hybrid	All	Urban	GP and GP squared and Region	IV	Region Trends	-297.20
Hybrid	Subset	Urban	GP and GP squared and Region	IV	Time Dummies	65.17
Hybrid	Subset	Urban	GP and GP squared and Region	IV	Region Trends	-355.51
Dummy	All	GP and GP squared	None	IV	Time Dummies	-19.22
Dummy	All	GP and GP squared	None	IV	Region Trends	-402.47
Dummy	Subset	GP and GP squared	None	IV	Time Dummies	-177.41
Dummy	Subset	GP and GP squared	None	IV	Region Trends	-505.07
Dummy	All	GP and GP squared	Urban	IV	Time Dummies	52.35
Dummy	All	GP and GP squared	Urban	IV	Region Trends	-330.27
Dummy	Subset	GP and GP squared	Urban	IV	Time Dummies	-103.70
Dummy	Subset	GP and GP squared	Urban	IV	Region Trends	-412.32
Dummy	All	GP and GP squared	Region	IV	Time Dummies	-21.58
Dummy	All	GP and GP squared	Region	IV	Region Trends	-367.28
Dummy	Subset	GP and GP squared	Region	IV	Time Dummies	-163.59
Dummy	Subset	GP and GP squared	Region	IV	Region Trends	-446.69
Spline	All	GP and GP squared	None	IV	Time Dummies	72.93
Spline	All	GP and GP squared	None	IV	Region Trends	-344.16
Spline	Subset	GP and GP squared	None	IV	Time Dummies	-58.19
Spline	Subset	GP and GP squared	None	IV	Region Trends	-419.82
Spline	All	GP and GP squared	Urban	IV	Time Dummies	101.49
Spline	All	GP and GP squared	Urban	IV	Region Trends	-292.52
Spline	Subset	GP and GP squared	Urban	IV	Time Dummies	-38.71
Spline	Subset	GP and GP squared	Urban	IV	Region Trends	-367.18
Spline	All	GP and GP squared	Region	IV	Time Dummies	132.86
Spline	All	GP and GP squared	Region	IV	Region Trends	-283.30
Spline	Subset	GP and GP squared	Region	IV	Time Dummies	46.66
Spline	Subset	GP and GP squared	Region	IV	Region Trends	-355.49
Hybrid	All	GP and GP squared	None	IV	Time Dummies	85.66
Hybrid	All	GP and GP squared	None	IV	Region Trends	-307.19
Hybrid	Subset	GP and GP squared	None	IV	Time Dummies	-33.57
Hybrid	Subset	GP and GP squared	None	IV	Region Trends	-293.73
Hybrid	All	GP and GP squared	Urban	IV	Time Dummies	120.53
Hybrid	All	GP and GP squared	Urban	IV	Region Trends	-235.09
Hybrid	Subset	GP and GP squared	Urban	IV	Time Dummies	-1.62
Hybrid	Subset	GP and GP squared	Urban	IV	Region Trends	-256.32
Hybrid	All	GP and GP squared	Region	IV	Time Dummies	147.08
Hybrid	All	GP and GP squared	Region	IV	Region Trends	-281.74
Hybrid	Subset	GP and GP squared	Region	IV	Time Dummies	53.51
Hybrid	Subset	GP and GP squared	Region	IV	Region Trends	-313.68
Dummy	All	None	None	non-IV	Time Dummies	-89.29
Dummy	All	None	None	non-IV	Region Trends	-1160.43

Formulation of the Laws	Demographics	Additional Covariates	Parameter Heterogeneity	Instrumental Variables	Time Dummies and Region Trends	Log Marginal Likelihood
Dummy	Subset	None	None	non-IV	Time Dummies	-274.35
Dummy	Subset	None	None	non-IV	Region Trends	-1313.43
Dummy	All	None	GP and GP squared	non-IV	Time Dummies	-90.77
Dummy	All	None	GP and GP squared	non-IV	Region Trends	-1176.67
Dummy	Subset	None	GP and GP squared	non-IV	Time Dummies	-268.95
Dummy	Subset	None	GP and GP squared	non-IV	Region Trends	-1322.73
Dummy	All	None	Urban	non-IV	Time Dummies	-80.72
Dummy	All	None	Urban	non-IV	Region Trends	-1132.52
Dummy	Subset	None	Urban	non-IV	Time Dummies	-272.38
Dummy	Subset	None	Urban	non-IV	Region Trends	-1278.52
Dummy	All	None	Region	non-IV	Time Dummies	-98.01
Dummy	All	None	Region	non-IV	Region Trends	-1148.21
Dummy	Subset	None	Region	non-IV	Time Dummies	-278.78
Dummy	Subset	None	Region	non-IV	Region Trends	-1288.77
Dummy	All	None	GP and GP squared and Urban	non-IV	Time Dummies	-83.11
Dummy	All	None	GP and GP squared and Urban	non-IV	Region Trends	-1149.60
Dummy	Subset	None	GP and GP squared and Urban	non-IV	Time Dummies	-267.83
Dummy	Subset	None	GP and GP squared and Urban	non-IV	Region Trends	-1289.78
Dummy	All	None	GP and GP squared and Region	non-IV	Time Dummies	-102.61
Dummy	All	None	GP and GP squared and Region	non-IV	Region Trends	-1154.32
Dummy	Subset	None	GP and GP squared and Region	non-IV	Time Dummies	-276.94
Dummy	Subset	None	GP and GP squared and Region	non-IV	Region Trends	-1285.10
Spline	All	None	None	non-IV	Time Dummies	47.08
Spline	All	None	None	non-IV	Region Trends	-1118.89
Spline	Subset	None	None	non-IV	Time Dummies	-93.45
Spline	Subset	None	None	non-IV	Region Trends	-1252.63
Spline	All	None	GP and GP squared	non-IV	Time Dummies	47.06
Spline	All	None	GP and GP squared	non-IV	Region Trends	-1120.39
Spline	Subset	None	GP and GP squared	non-IV	Time Dummies	-81.93
Spline	Subset	None	GP and GP squared	non-IV	Region Trends	-1239.20
Spline	All	None	Urban	non-IV	Time Dummies	54.90
Spline	All	None	Urban	non-IV	Region Trends	-1072.16
Spline	Subset	None	Urban	non-IV	Time Dummies	-93.49
Spline	Subset	None	Urban	non-IV	Region Trends	-1196.45
Spline	All	None	Region	non-IV	Time Dummies	48.82
Spline	All	None	Region	non-IV	Region Trends	-1119.01
Spline	Subset	None	Region	non-IV	Time Dummies	-71.27
Spline	Subset	None	Region	non-IV	Region Trends	-1240.74
Spline	All	None	GP and GP squared and Urban	non-IV	Time Dummies	54.50
Spline	All	None	GP and GP squared and Urban	non-IV	Region Trends	-1076.17
Spline	Subset	None	GP and GP squared and Urban	non-IV	Time Dummies	-82.40
Spline	Subset	None	GP and GP squared and Urban	non-IV	Region Trends	-1186.35
Spline	All	None	GP and GP squared and Region	non-IV	Time Dummies	39.16
Spline	All	None	GP and GP squared and Region	non-IV	Region Trends	-1094.07
Spline	Subset	None	GP and GP squared and Region	non-IV	Time Dummies	-66.03
Spline	Subset	None	GP and GP squared and Region	non-IV	Region Trends	-1197.80
Hybrid	All	None	None	non-IV	Time Dummies	41.47
Hybrid	All	None	None	non-IV	Region Trends	-1123.20
Hybrid	Subset	None	None	non-IV	Time Dummies	-99.02
Hybrid	Subset	None	None	non-IV	Region Trends	-1256.13
Hybrid	All	None	GP and GP squared	non-IV	Time Dummies	28.07
Hybrid	All	None	GP and GP squared	non-IV	Region Trends	-1145.43
Hybrid	Subset	None	GP and GP squared	non-IV	Time Dummies	-96.20
Hybrid	Subset	None	GP and GP squared	non-IV	Region Trends	-1262.58
Hybrid	All	None	Urban	non-IV	Time Dummies	40.13
Hybrid	All	None	Urban	non-IV	Region Trends	-1086.09
Hybrid	Subset	None	Urban	non-IV	Time Dummies	-108.27
Hybrid	Subset	None	Urban	non-IV	Region Trends	-1208.77
Hybrid	All	None	Region	non-IV	Time Dummies	36.57
Hybrid	All	None	Region	non-IV	Region Trends	-1120.51
Hybrid	Subset	None	Region	non-IV	Time Dummies	-80.44
Hybrid	Subset	None	Region	non-IV	Region Trends	-1239.98
Hybrid	All	None	GP and GP squared and Urban	non-IV	Time Dummies	26.06
Hybrid	All	None	GP and GP squared and Urban	non-IV	Region Trends	-1110.81
Hybrid	Subset	None	GP and GP squared and Urban	non-IV	Time Dummies	-107.84
Hybrid	Subset	None	GP and GP squared and Urban	non-IV	Region Trends	-1219.26
Hybrid	All	None	GP and GP squared and Region	non-IV	Time Dummies	12.58
Hybrid	All	None	GP and GP squared and Region	non-IV	Region Trends	-1116.31
Hybrid	Subset	None	GP and GP squared and Region	non-IV	Time Dummies	-87.45
Hybrid	Subset	None	GP and GP squared and Region	non-IV	Region Trends	-1217.60
Dummy	All	Urban	None	non-IV	Time Dummies	-81.35
Dummy	All	Urban	None	non-IV	Region Trends	-1162.52
Dummy	Subset	Urban	None	non-IV	Time Dummies	-272.34
Dummy	Subset	Urban	None	non-IV	Region Trends	-1318.34
Dummy	All	Urban	GP and GP squared	non-IV	Time Dummies	-82.43
Dummy	All	Urban	GP and GP squared	non-IV	Region Trends	-1178.00
Dummy	Subset	Urban	GP and GP squared	non-IV	Time Dummies	-266.06
Dummy	Subset	Urban	GP and GP squared	non-IV	Region Trends	-1327.83
Dummy	All	Urban	Region	non-IV	Time Dummies	-89.39

Table A-2: Likelihood - Property Crime

Formulation of the Laws	Demographics	Additional Covariates	Parameter Heterogeneity	Instrumental Variables	Time Dummies and Region Trends	Log Marginal Likelihood
Dummy	All	Urban	Region	non-IV	Region Trends	-1150.09
Dummy	Subset	Urban	Region	non-IV	Time Dummies	-277.61
Dummy	Subset	Urban	Region	non-IV	Region Trends	-1293.18
Dummy	All	Urban	GP and GP squared and Region	non-IV	Time Dummies	-94.62
Dummy	All	Urban	GP and GP squared and Region	non-IV	Region Trends	-1155.80
Dummy	Subset	Urban	GP and GP squared and Region	non-IV	Time Dummies	-274.08
Dummy	Subset	Urban	GP and GP squared and Region	non-IV	Region Trends	-1289.00
Spline	All	Urban	None	non-IV	Time Dummies	53.53
Spline	All	Urban	None	non-IV	Region Trends	-1118.69
Spline	Subset	Urban	None	non-IV	Time Dummies	-91.69
Spline	Subset	Urban	None	non-IV	Region Trends	-1255.07
Spline	All	Urban	GP and GP squared	non-IV	Time Dummies	54.81
Spline	All	Urban	GP and GP squared	non-IV	Region Trends	-1120.00
Spline	Subset	Urban	GP and GP squared	non-IV	Time Dummies	-80.12
Spline	Subset	Urban	GP and GP squared	non-IV	Region Trends	-1241.73
Spline	All	Urban	Region	non-IV	Time Dummies	52.73
Spline	All	Urban	Region	non-IV	Region Trends	-1116.73
Spline	Subset	Urban	Region	non-IV	Time Dummies	-69.73
Spline	Subset	Urban	Region	non-IV	Region Trends	-1241.95
Spline	All	Urban	GP and GP squared and Region	non-IV	Time Dummies	43.96
Spline	All	Urban	GP and GP squared and Region	non-IV	Region Trends	-1094.42
Spline	Subset	Urban	GP and GP squared and Region	non-IV	Time Dummies	-63.47
Spline	Subset	Urban	GP and GP squared and Region	non-IV	Region Trends	-1199.03
Hybrid	All	Urban	None	non-IV	Time Dummies	47.90
Hybrid	All	Urban	None	non-IV	Region Trends	-1121.95
Hybrid	Subset	Urban	None	non-IV	Time Dummies	-97.26
Hybrid	Subset	Urban	None	non-IV	Region Trends	-1258.60
Hybrid	All	Urban	GP and GP squared	non-IV	Time Dummies	33.85
Hybrid	All	Urban	GP and GP squared	non-IV	Region Trends	-1144.13
Hybrid	Subset	Urban	GP and GP squared	non-IV	Time Dummies	-95.56
Hybrid	Subset	Urban	GP and GP squared	non-IV	Region Trends	-1265.13
Hybrid	All	Urban	Region	non-IV	Time Dummies	40.16
Hybrid	All	Urban	Region	non-IV	Region Trends	-1118.14
Hybrid	Subset	Urban	Region	non-IV	Time Dummies	-79.78
Hybrid	Subset	Urban	Region	non-IV	Region Trends	-1241.35
Hybrid	All	Urban	GP and GP squared and Region	non-IV	Time Dummies	18.53
Hybrid	All	Urban	GP and GP squared and Region	non-IV	Region Trends	-1115.81
Hybrid	Subset	Urban	GP and GP squared and Region	non-IV	Time Dummies	-85.47
Hybrid	Subset	Urban	GP and GP squared and Region	non-IV	Region Trends	-1218.69
Dummy	All	GP and GP squared	None	non-IV	Time Dummies	-75.29
Dummy	All	GP and GP squared	None	non-IV	Region Trends	-1170.70
Dummy	Subset	GP and GP squared	None	non-IV	Time Dummies	-253.62
Dummy	Subset	GP and GP squared	None	non-IV	Region Trends	-1322.17
Dummy	All	GP and GP squared	Urban	non-IV	Time Dummies	-68.67
Dummy	All	GP and GP squared	Urban	non-IV	Region Trends	-1143.28
Dummy	Subset	GP and GP squared	Urban	non-IV	Time Dummies	-252.33
Dummy	Subset	GP and GP squared	Urban	non-IV	Region Trends	-1287.35
Dummy	All	GP and GP squared	Region	non-IV	Time Dummies	-86.23
Dummy	All	GP and GP squared	Region	non-IV	Region Trends	-1158.94
Dummy	Subset	GP and GP squared	Region	non-IV	Time Dummies	-262.18
Dummy	Subset	GP and GP squared	Region	non-IV	Region Trends	-1296.98
Spline	All	GP and GP squared	None	non-IV	Time Dummies	58.68
Spline	All	GP and GP squared	None	non-IV	Region Trends	-1127.71
Spline	Subset	GP and GP squared	None	non-IV	Time Dummies	-77.94
Spline	Subset	GP and GP squared	None	non-IV	Region Trends	-1261.50
Spline	All	GP and GP squared	Urban	non-IV	Time Dummies	66.50
Spline	All	GP and GP squared	Urban	non-IV	Region Trends	-1082.93
Spline	Subset	GP and GP squared	Urban	non-IV	Time Dummies	-75.32
Spline	Subset	GP and GP squared	Urban	non-IV	Region Trends	-1205.44
Spline	All	GP and GP squared	Region	non-IV	Time Dummies	57.79
Spline	All	GP and GP squared	Region	non-IV	Region Trends	-1127.81
Spline	Subset	GP and GP squared	Region	non-IV	Time Dummies	-57.39
Spline	Subset	GP and GP squared	Region	non-IV	Region Trends	-1248.23
Hybrid	All	GP and GP squared	None	non-IV	Time Dummies	51.12
Hybrid	All	GP and GP squared	None	non-IV	Region Trends	-1133.48
Hybrid	Subset	GP and GP squared	None	non-IV	Time Dummies	-81.55
Hybrid	Subset	GP and GP squared	None	non-IV	Region Trends	-1265.44
Hybrid	All	GP and GP squared	Urban	non-IV	Time Dummies	51.45
Hybrid	All	GP and GP squared	Urban	non-IV	Region Trends	-1096.50
Hybrid	Subset	GP and GP squared	Urban	non-IV	Time Dummies	-90.89
Hybrid	Subset	GP and GP squared	Urban	non-IV	Region Trends	-1217.93
Hybrid	All	GP and GP squared	Region	non-IV	Time Dummies	44.72
Hybrid	All	GP and GP squared	Region	non-IV	Region Trends	-1132.61
Hybrid	Subset	GP and GP squared	Region	non-IV	Time Dummies	-67.06
Hybrid	Subset	GP and GP squared	Region	non-IV	Region Trends	-1248.89

Note: Each line corresponds to a specific model. Every specification excludes population weights. GP stands for gun prevalence. For a description of the various modeling assumptions see Section 3.