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CAPITAL ACCOUNT LIBERALIZATION
AS A SIGNAL

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ABSTRACT

We present a model in which a government's current capital controls policy signals future policies. Controls on capital outflows evolve in response to news on technology, conditional on government attitudes towards taxation of capital. When there is uncertainty over government types, a policy of liberal capital outflows sends a favorable signal that may trigger a capital inflow. This prediction is consistent with the experience of several countries that have liberalized their capital account.

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Controls on international capital flows are a common form of financial regulation. Changes in the extent of these controls are also common. Of 182 countries surveyed by the IMF in 1995, 129 were classified as restricting international capital transactions. At least 50 of them had significantly altered these regulations in the previous 12 months.

Despite the widespread use of capital controls and the frequency with which such restrictions are modified, little work has been done to model the impact of changes in these regulations on capital flows. Perhaps this deficiency reflects the view that the effect of lifting or imposing controls is clear from basic economic theory. Consider, for example, the removal of restrictions on capital outflows. If controls are binding when the liberalization is implemented (so that offshore returns exceed onshore returns), a liberalization should lead to a capital outflow, as funds flow to where returns are highest,¹ while removal of nonbinding controls should have no effect.

Actual experience with lifting controls, however, tells a different story. Many countries that have removed controls on *outflows* have experienced rapid and massive *inflows* of capital.² A popular explanation, motivated by the work of Dooley and Isard (1980), was formalized by Labán and Larraín (1993). Controls that prevent investors from withdrawing capital from a country act like investment irreversibility. Their removal makes investors more willing to invest in a country, as it is easier to get their capital out in the future.

However, the link between capital controls and investment flexibility, though essential to any model of capital controls, provides a partial explanation of capital inflows. This explanation depends crucially on expected persistence of current policies, but, unlike technological constraints, policies may change. In fact, governments that succeed in attracting

foreign investment have a strong incentive to lock the door once the fattened calves have come inside. To make sense of the flexibility argument and motivate the persistence of policies affecting capital mobility, one needs a model that captures the interaction between optimizing, forward-looking investors *and* governments.

Our approach to modeling capital controls and explaining the observed inflows following the adoption of a regime of liberal outflows views capital controls as potential signals of future government behavior. Specifically, we suggest that besides providing greater flexibility for current allocation of capital, a regime of free capital mobility may signal that imposition of controls is less likely to occur in the future and, more generally, that future policies are likely to be more favorable to investment. Our argument rests on the belief that investors have imperfect information on governments' intentions and constraints, and may therefore use the observation of current policies toward investment to infer the course of future policies. This gives governments an incentive to allow free capital mobility so as to provide a favorable signal on future investment policies. If the signal is successful, capital flows in.

A signaling model must make this motive consistent with the ultimate purpose of capital controls, which is often to broaden the domestic tax base. Countries with poorly developed tax systems often rely on revenues from financial repression, enforcing a differential between onshore and offshore returns to capital by regulations aimed at "trapping" capital onshore. In our model, it is precisely those governments that depend most on such a tax base that impose controls, even though such controls may lead to a lower *expected* tax base.

To make the argument convincing, we must show that governments use capital controls as an equilibrium response to information they receive: the choice of an open capital account signals good news about the future, and vice versa. However, if adoption of a regime of free capital mobility is expected to lead to a capital inflow, why would a government that expects bad times not attempt to take advantage of this? (Formally, the question is: Why does a separating equilibrium prevail, rather than a pooling equilibrium in which all governments choose not to impose controls.) To answer this question, we show that some governments choose to impose capital controls, even though they know this is interpreted as an unfavorable signal.

The argument behind this result is simple. Consider a government that raises revenue from several sources, including capital taxation, to finance the provision of public goods. Suppose that revenues (and hence expenditures) have a stochastic component and that government welfare is highly concave in the level of expenditure, so that low expenditure implies very low welfare. A government that anticipates low revenues from other sources is especially sensitive to the possibility of low capital tax collection. It will then impose controls to self-insure against bad states of nature (when capital would flow out), thereby assuring a minimum level of revenues in *all* states of nature. It will impose controls, even though, by doing so, it may forgo higher revenues on average *across all states*.

Our approach has both strengths and limitations. First, in contrast to most previous studies, we model capital controls as a dynamic component of governments' problem rather than as exogenous constraints applying over the whole horizon. Second, unlike the standard symmetric modeling of controls on inflows and outflows, we recognize that real-world

controls are typically asymmetric: stricter either on inflows or--more frequently--on outflows. Greater realism in these respects comes at the cost of simplification elsewhere. For instance, we do not distinguish between restrictions on short-term (or portfolio) and those on long-term (or FDI) flows, nor between restrictions on residents and nonresidents, although one may imagine situations where liberalizing residents' portfolio activity alone may send a favorable signal, thereby indirectly promoting other inflows. Also, we focus solely on policies affecting capital mobility, although we are aware that capital account liberalization is often only one element of broader reform programs. However, by focusing on a single motive for inflows, we can make the clearest case for the signaling role of policies affecting capital mobility. Our model suggests that imperfect information about a government's intentions may provide an incentive to use free capital mobility to enhance the credibility of a broader reform program. It is to a reformist government's advantage to show an early commitment to an open capital account, by exposing itself to risks that less committed governments cannot afford.

The paper is structured as follows. The next section reviews the liberalization experience of a number of countries, pointing to stylized facts that are consistent with our model of capital controls but may be more difficult to explain by alternative models. The model is described in Section 2 and solved in Section 3. Section 4 discusses the results, and Section 5 concludes.

1. Capital controls: Some stylized facts and liberalizations episodes

We begin with a few stylized facts. First, capital controls are much more common

among developing countries than among industrial countries. At the beginning of 1995, for instance, capital controls were used by 126 of 158 developing countries, against only 3 of 24 OECD countries (Greece, Norway, and Turkey).

Second, capital controls are predominantly aimed at restricting capital *outflows*. These controls take a variety of forms, including quantitative restrictions and outright prohibition of outflows, requirements to surrender a portion of the outflow to a low interest rate account, and dual exchange rates. Though these regulations look different, in practice all aim at stemming outflows by making their cost prohibitive.

Third, capital controls appear to play two main roles, either in support of governments' attempt to broaden the tax base for a capital levy, inflation tax, and various forms of "financial repression", or in support of fixed or managed exchange rate policies.

Finally, liberalizations of capital outflows are often accompanied by a sharp increase in net capital inflows, as the experience of some countries that have recently liberalized their capital accounts illustrates. (See Figure 1 for summary data.) The four episodes we review are those of Italy, New Zealand, Uruguay, and Spain.

Italy began to dismantle its system of controls on capital outflows in November 1984. The compulsory zero-interest deposit on portfolio investment abroad was reduced for residents and abolished for mutual funds. The surrender requirement was further reduced in 1985 and 1986 and abolished in 1987, and the crediting of banknotes to capital accounts was liberalized in August 1986. Though the liberalization was completed only in May 1990, its main steps occurred in 1986 and 1987, after which remaining restrictions ceased to be binding (see Bartolini and Bodnar, 1992 and Giavazzi and Giovannini, 1989, for analysis of this episode).

Large inflows were recorded from 1987, and private investors were primarily responsible for them.³

In November 1984, **New Zealand** abolished the exchange and capital controls that had been in place since 1938, as part of a broad policy of financial liberalization. In contrast with the policies followed by Italy and Spain during the 1980s (where the liberalization was part of a policy of greater exchange rate fixity), New Zealand floated its exchange rate soon after the liberalization. The capital liberalization was rapid and focused on the lifting of restrictions on outflows, including the surrender of foreign exchange receipts and limits on holdings of foreign securities and on raising of domestic funds by foreign companies. Interestingly, although the financial market was liberalized in June and July 1984, capital inflows did not surge until year-end, when the capital account was liberalized. In fact, the net inflow recorded in 1984 appears to have occurred wholly in the last two months of the year. Capital inflows surged in 1985, 1986, and 1987, with private investors playing, once again, the principal role.⁴

After nearly two decades of inward-looking policies and financial repression, **Uruguay** began to implement radical reforms in the mid-1970s, including trade and financial deregulation, and--foremost--liberalization of capital flows.⁵ The liberalization of capital flows proceeded at the fastest pace and before other major policy changes: in September 1974, exchange rate controls (primarily on outflows) were eliminated and residents were permitted to hold dollar accounts with domestic banks for the first time, and repatriation of capital and profits connected with FDI was permitted. Large capital inflows were recorded in the four years beginning in 1974. Private investors (mainly from Argentina and the U.S.)

played an essential role also in this episode, a feature we document in Figure 1 by netting official net loans from net capital inflows (assuming negligible official acquisitions of equity and real estate, and negligible foreign investment of the domestic public sector).

After its entry into the EC in 1986, **Spain** liberalized capital flows, as part of a broader plan of fiscal and monetary reform. Both capital outflows and inflows were liberalized.⁶ Evidence from offshore-onshore interest differentials, however, shows that prior to the liberalization, controls on outflows were more stringent than on inflows (Viñals, 1990). In fact, after the liberalization, the positive offshore-onshore interest differential disappeared and then turned negative when temporary controls on inflows were introduced to stem the rapid inflow recorded in 1987. Excluding measures affecting FDI, the main steps in the liberalization included the lifting of restrictions on residents' direct and portfolio investment abroad, on forward exchange operations, and on real estate investment abroad. Although the liberalization was completed only in 1992, net capital inflows (net of FDI) surged immediately after the initial steps of 1986, and continued unabated until the ERM crisis of 1992. Once again, private investors played a primary role in the inflow, as documented in Figure 1, which nets changes in the stock of official loans from total capital flows (excluding FDI; see also Schadler et al., 1993, for a discussion of this episode).

These episodes can be summarized as follows: the liberalizations focussed on removing restrictions on capital outflows; they represented early ingredients of broad reforms that included the lifting of various elements of financial repression; and they were accompanied by a surge in net capital inflows. In the next section we present a model capturing several of these stylized facts.

2. The model

Consistent with the arguments outlined in the introduction, in our model decisions on capital controls are driven by governments' desire to increase the stock of domestic capital. Our main results require government behavior to display two basic features: first, government utility (net of the cost incurred when imposing capital controls) should increase in the stock of domestic capital; second, the willingness to incur the costs of controls should differ across governments in a way (at least, partially) unknown to investors.

Many of the motives for (and costs of) capital controls suggested in the literature could meet these requirements and fit into our framework. For instance, utility from domestic capital could reflect a government's interest in maximizing domestic output, tax base, or official reserves.⁷ Costs of controls could reflect concern with distortionary effects on capital allocation, penalties enforced by other countries for engaging in beggar-thy-neighbor policies (penalties that may include limits on trade credit, exclusion from participation in coordinated policies, etc.), or other economic and political factors that affect the importance governments assign to capital mobility.⁸ Governments may also be concerned with the effects of controls on residents' ability to smooth consumption through capital flows, although the practical relevance of this motive has been questioned.⁹ A different and important argument concerns the use of controls to insulate a country from external shocks. The difficulties associated with the recent large inflows and subsequent outflows in Latin America, which culminated in the Mexican crisis of late 1994, underscore the importance of this motive, whose analysis would require, however, a substantially different model. Although analytical clarity dictates our focus on a single motive for controls, we later discuss how our results may extend beyond

our specific model.

To capture these considerations formally, we present the simplest model we could design to yield our main results.

We consider a two-period model of a small open economy where a single nonstorable, homogeneous good Y_t is produced at time t with onshore capital K_t , using a concave technology $Y_t = \mu_t K_t^\beta$, where μ_t is a stochastic productivity shock and $0 < \beta < 1$. The stock of onshore capital K_t reflects the decisions of competitive, risk-neutral investors. In each period, investors allocate capital either offshore (at a fixed return r) or onshore, to maximize total expected returns, discounted by the factor $\rho = 1/(1+r)$, over the residual horizon.¹⁰ (For simplicity we also set the government's discount factor at ρ .) Absent adjustment costs, the return to physical and financial capital is equalized and we make no distinction between the two. For simplicity, and given the ambiguous evidence in support of capital flows for consumption-smoothing purposes (see Footnote 9), we ignore this motive in our analysis. (Formally, this treatment would follow from the assumption of households' linear utility; see Frenkel and Razin, 1987, for a complete discussion.) We thus focus on investors' capital allocation decisions in response to technology shocks, given endogenous constraints on capital mobility.¹¹

The government taxes capital wealth (for simplicity, only at the end of period two), at a predetermined rate τ , collecting revenues τK_2 .¹² Governments differ by the value they attach to this revenue. This heterogeneity may reflect differences in preferences for expenditures, in willingness to tap revenues other than capital taxation, or in the importance assigned to free capital mobility, differences which cannot be signaled simply by

announcement. We parameterize these differences by a variable $x \in (-\infty, \infty)$, and assume governments to have greater information on x than investors. Although many factors may differentiate governments' willingness to use controls (especially their commitment to non-interventionist policies), for concreteness we treat x simply as revenues (or obligations, when $x < 0$) other than capital taxation, to which the government has access or is willing to use (or service) at the end of period two. At the end of period two, the government transforms the sum $\tau K_2 + x$ into nonmarketed public goods and derives utility $W(\cdot)$ from their supply. This function is increasing, continuous, concave, and satisfies the regularity conditions

$$\lim_{z \rightarrow -\infty} W(z) = -\infty, \quad \lim_{z \rightarrow -\infty} W'(z) = \infty, \quad \text{and} \quad \lim_{z \rightarrow \infty} W'(z) = 0.^{13}$$

Thus, government utility from onshore capital is increasing in $\tau K_t + x$ (so that a potentially larger captive tax base tempts governments to impose controls), but at a decreasing rate (so that a larger x reduces the incentives to trap a given stock of capital). We model asymmetric information by assuming that governments are informed about x at the beginning of period one, whereas investors learn this only at the beginning of period two. We refer to x as a government's *type*; a higher x identifies governments with greater outside resources or greater willingness to tap those resources. Investors have a prior cumulative probability distribution over types, $G(x)$.

We model the direct costs of controls very simply. (Naturally, "reputational" costs are an integral part of our story and are analyzed below.) Similarly to other models in the signaling literature, we interpret the cost of controls simply as the cost to the government of breaking a commitment to free capital mobility:¹⁴ whenever controls are in place, the government pays a cost $\xi > 0$. This approach simplifies the exposition by making the cost of

controls independent of whether or not controls turn out to bind *ex post*.¹⁵

The model's timing is summarized in Table 1. The initial state is summarized by the initial capital stock, K_0 , and $G(x)$. At the beginning of each period, before observing current productivity, the government announces whether capital flows are free or restricted in period t . When controls are imposed, the end-of-period stock of domestic capital, K_t , is constrained to be at least as large as at the beginning of the period, that is, $K_t \geq K_{t-1}$, with $K_0 > 0$.¹⁶ (We use a dummy variable c_t to denote the period t regime, letting $c_t = F$ and $c_t = R$ denote the cases of free and restricted mobility, respectively.) For economy of exposition, we shall often refer to the adoption of a regime of free capital mobility simply as a “liberalization” though, strictly speaking, this term should be reserved to describe a switch from a regime with capital controls to one without controls. In Section 4, we discuss when a “liberalization” in the strict sense may indeed emerge endogenously in our model.

After the government has announced the financial regime, nature reveals current-period productivity μ_t , which may take the values $\{0, \mu\}$. We initially assume μ_t to be serially uncorrelated and write the probabilities of $\mu_t = 0$ and $\mu_t = \mu$ as $1 - \pi$ and π , respectively. We later discuss some implications of the more realistic assumption that μ_t is serially correlated. After μ_t has been revealed, investors choose K_t (in accord with the announced regime) and profits (as well as taxes, in period two) are collected at the end of the period.

3. Solution

Solving the model backward from period two leads us to a unique Perfect Bayesian Equilibrium, a standard equilibrium concept in the signaling literature. (See, for example,

Fudenberg and Tirole, 1991).

A. Period-two equilibrium. After observing μ_2 , investors compare the marginal return from investing offshore (inclusive of principal), $\rho(1+r)$, to that from investing onshore,

$V_2 = \rho(\mu_2 \beta K_2^{\beta-1} + (1-\tau))$ (inclusive of the scrap value of a unit of capital). With free capital mobility, profit maximization equalizes $\rho(1+r)$ and V_2 , yielding the optimal level of onshore investment

$$(1) \quad K_2^*(\mu_2) \equiv \left[\frac{\beta \mu_2}{r + \tau} \right]^{\frac{1}{1-\beta}},$$

which equals zero if $\mu_2=0$. If, instead, capital controls are in place in period two, investors may be unable to attain this solution, since the domestic stock of capital must satisfy the constraint $K_2 \geq K_1$. Then,

$$(2) \quad K_2 \equiv \max \{ K_1, K_2^*(\mu_2) \}.$$

Thus, depending on the inherited stock K_1 , capital controls may or may not bind in period two in the high state $\mu_t = \mu$. However, controls certainly bind (and the corner solution $K_2 = K_1$ prevails) in the low state $\mu_t = 0$, if a positive K_1 is inherited from period one. This possibility, given investors' period-one uncertainty about the risk of controls in period two, plays a crucial role in the period-one equilibrium studied below.

At the beginning of period two, the government decides whether or not to impose controls, given the inherited stock K_1 . The government's problem can be summarized by the function $\psi_2 = \psi_2(K_1, x)$, which defines a type x 's expected utility gain from imposing controls. Types for which $\psi_2 > 0$ impose controls in this period, while the remaining types allow free

capital mobility (with no loss of generality, indifferent types allow free mobility). ψ_2 is defined as

$$(3) \quad \psi_2(K_1, x) \equiv \rho E_2[W(\tau K_2 + x) | K_1, c_2 = R] - \rho \xi - \rho E_2[W(\tau K_2 + x) | K_1, c_2 = F] \\ = \rho \left[\pi [W(\tau K_1 + x) - W(\tau K_2^*(\mu) + x)] I' + (1 - \pi) [W(\tau K_1 + x) - W(x)] - \xi \right],$$

where the indicator function $I' \equiv I(K_1 > K_2^*(\mu))$ equals one when K_1 exceeds the optimal period-two stock in the high productivity state $\mu_2 = \mu$, and zero otherwise.

Under the model's assumptions (in particular, the concavity of $W(\cdot)$), $\psi_2 = \psi_2(K_1, x)$ decreases monotonically in x from ∞ to $-\rho \xi$. Hence, the period-two equilibrium features a low range of types (those for whom $\psi_2 > 0$), who impose capital controls in period two, and a higher range of types with sufficient outside resources that $\psi_2 \leq 0$, who allow free capital mobility. This property is intuitive: capital controls raise expected tax revenues in period two (the tax base is higher with binding controls and unchanged otherwise), thus raising a government's expected utility from public expenditure. The concavity of $W(\cdot)$ implies that this utility gain falls with x , though. For sufficiently large x , the gain from broadening the tax base is outweighed by the cost of controls. Also, ψ_2 rises with the inherited stock of capital K_1 : a higher K_1 provides a potentially larger captive tax base, and hence stronger temptation to impose controls. Based on these properties, we now study the equilibrium prevailing in period one.

B. Period one: signaling equilibrium. In period one, investors also compare the expected returns from onshore and offshore investment. In so doing, however, they must consider the probability that capital controls may be imposed in period two, a probability that reflects their

current beliefs over government types, conditional on the policy chosen by the government at the beginning of period one.

To study this problem, denote the probability that controls may be imposed in period two after having been imposed in period one as $\gamma^R \equiv \gamma^R(K_0, K_1) = \Pr(c_2=R | c_1=R)$ and the probability that controls may be imposed in period two after *not* having been imposed in period one as $\gamma^F \equiv \gamma^F(K_0, K_1) = \Pr(c_2=R | c_1=F)$. (These probabilities depend on both K_0 and K_1 , as these affect the incentives of governments to impose controls in period one and two, respectively.)

Next, the marginal return from investing offshore in period one is $\rho r + \rho^2(1+r)$: in equilibrium, by going offshore in period one, investors earn the risk-free rate in both periods. The expected marginal return from investing onshore in period one, V_1 , is

$$\begin{aligned}
 (4) \quad V_1(K_1, \mu_1, c_1, K_0) &= \rho \beta K_1^{\beta-1} \mu_1 + \rho^2(1+r) [\Pr(c_2=F) + \Pr(c_2=R, \text{not binding})] \\
 &\quad + \rho^2 [1 - \tau + \beta K_1^{\beta-1} E_1[\mu_2 | c_2=R, \text{binding}]] \Pr(c_2=R, \text{binding}) \\
 &= \rho \beta K_1^{\beta-1} \mu_1 + \rho^2(1+r) - \rho^2 \gamma^{c_1} [(r+\tau)(1-\pi(1-I')) - \pi \mu \beta K_1^{\beta-1} I'] ,
 \end{aligned}$$

where $I' = 1$ if $K_1 > K_2^*(\mu)$ and zero otherwise, and γ^{c_1} stands for either γ^F or γ^R , depending on whether $c_1 = F$ or $c_1 = R$.

The term $-\rho^2 \gamma^{c_1} [(r+\tau)(1-\pi(1-I')) - \pi \mu \beta K_1^{\beta-1} I']$ in the last line of (4) captures the “political risk” faced when investing in a country subject to potential capital controls. If the probability of controls in period two, γ^{c_1} , is zero, then the period-one marginal product of onshore capital, $\beta K_1^{\beta-1} \mu_1$, equals the offshore rate r , as both onshore and offshore capital yield $\rho r + \rho^2(1+r)$. In contrast, when the probability of controls in period two is positive,

then the stock K_1 falls in period one, thus raising the period-one onshore return flow (the marginal product of capital) above the offshore rate.

The probabilities γ^R and γ^F are obtained by Bayes' rule from the prior probability that $c_2=R$, conditional on the policy observed in period one. To clarify the updating process, denote by R_1 the set of types imposing controls in period one, and by R_2 the set of types imposing controls in period two. These sets are defined by $R_1 \equiv R_1(K_0) \equiv \{x: \psi_1(K_0, x) > 0\}$ and $R_2 \equiv R_2(K_1) \equiv \{x: \psi_2(K_1, x) > 0\}$, where ψ_2 is defined in (3), and ψ_1 is similarly defined in (7) below. Also, denote by $G(R_1) \equiv \int_{R_1} dG(x)$ the prior probability of $c_1=R$, by $G(R_2) \equiv \int_{R_2} dG(x)$ the prior probability of $c_2=R$, and by $G(R_1 \cap R_2) \equiv \int_{R_1 \cap R_2} dG(x)$ their joint probability. Then, by Bayes' rule,

$$(5) \quad \gamma^R \equiv \Pr(c_2=R | c_1=R) = \Pr(c_2=R) \cdot \frac{\Pr(c_1=R | c_2=R)}{\Pr(c_1=R)} = G(R_2) \cdot \frac{G(R_1 \cap R_2)}{G(R_1) \cdot G(R_2)}.$$

Equation (5) illustrates the effects of the persistence of government policies on the perceived probability of period-two controls. The update factor $\frac{G(R_1 \cap R_2)}{G(R_1) \cdot G(R_2)}$ multiplies the prior $G(R_2)$: should capital controls' decisions be independent across periods, then $G(R_1 \cap R_2) = G(R_1) \cdot G(R_2)$ and the posterior probability of period-two controls, γ^R , would equal its prior, $G(R_2)$. When $G(R_1 \cap R_2) > G(R_1) \cdot G(R_2)$, instead, then capital controls provide an unfavorable signal of future policies, as governments imposing controls in period one are also more likely to do so in period two. In this case, the posterior probability of period-two controls rises above its prior. The intuition behind the upgrade of γ^F , is symmetrical.

Next, note that V_1 is a continuous and decreasing function of K_1 , for both $c_1=F$ and

$c_1=R$, going from infinity for $K_1 \rightarrow 0$, to $-\rho^2\tau$ for $K_1 \rightarrow \infty$.¹⁷ The unconstrained period-one profit-maximizing capital stock, $K_1^* = K_1^*(\mu_1, K_0, c_1)$, is then defined as the unique solution for K_1 of

$$(6) \quad \rho r + \rho^2(1+r) = V_1(K_1, \mu_1, c_1, K_0) .$$

Finally, since the term in square brackets in (4) is positive (offshore returns exceed onshore returns with binding controls), then any rise in γ^{c_1} reduces the return to K_1 , and hence K_1^* itself. This key link underlies our signaling equilibrium: when governments evaluate policy options at the beginning of period one, they know that actions leading to a higher perceived probability of controls in period two will induce a lower desired capital stock in period one.

We can now close the model by examining the problem faced by a government of type x in period one. This problem is summarized by the function $\psi_1 = \psi_1(K_0, x)$ that defines a type x 's expected utility from imposing controls in this period one, as a function of the existing capital stock:

$$(7) \quad \psi_1(K_0, x) = \rho^2 E_1[W(\tau K_2 + x | c_1=R) - W(\tau K_2 + x | c_1=F)] - \rho \xi - \rho^2 \xi I'' ,$$

where expectations are taken over realizations of μ_1 and μ_2 , and the indicator function

$I'' \equiv I(c_2=R)$ equals one when controls are in place in period two and zero otherwise.

The properties of $W(\cdot)$ assure that $\lim_{x \rightarrow -\infty} \psi_1(K_0, x) = \infty$, and $\lim_{x \rightarrow \infty} \psi_1(K_0, x) = -\rho \xi$ for all $K_0 > 0$. Within these extreme values, the behavior of the (continuous) function ψ_1 determines government policies in period one, just as ψ_2 does for period two: types for

which $\psi_1 > 0$ impose controls in period one, while types for which $\psi_1 \leq 0$ do not. While the relative generality of our model does not allow us to characterize the solution for period one as simply as for period two,¹⁸ we can nonetheless characterize government behavior in several important respects and study its implications for capital flows. Proposition 1 summarizes an important property: the adoption of free capital mobility in period one provides a favorable signal, by reducing the posterior probability of controls in period two:

Proposition 1. In equilibrium, $\gamma^F(K_0, K_1^*(\mu, K_0, c_1 = F)) < \gamma^R(K_0, K_1^*(\mu, K_0, c_1 = R))$, for all $K_0 > 0$ and $\mu > 0$: the probability of controls in period two is higher conditional on capital controls than on free capital mobility in period one.

The intuition behind Proposition 1 (whose proof is in Appendix) is simple. Since capital control policies are positively correlated across periods, the observation of free mobility in period one provides a favorable signal of future policies (that is, it reduces the posterior probability of controls in period two). The formal argument behind this correlation is best made by contradiction, by assuming that policies are negatively (or not at all) correlated and noting that in this case low x types would be more inclined to impose controls in period one than high x types. Indeed, if the probability of period-two controls falls upon observing controls in period one, then imposing controls in period one would always raise the end-of-period capital K_1 , and the eventual tax base K_2 : in bad states of nature (where capital controls trap capital above its desired level), and in good states (where the assumed favorable signal provided by capital controls increases the desired stock itself). In this case, however, lower x types would be more inclined to impose controls (just as they do in period two),

since the concavity of their utility function strengthens their taste for a broader tax base. Hence, observing controls in period one would increase, rather than decrease (as assumed), the likelihood of controls in period two.

Based on Proposition 1 and on the solution to investors' problem, Section 4 further discusses the first period's equilibrium and its implications for capital flows.

4. Properties of the equilibrium

A. Who imposes controls? Our model embodies predictions on what type of governments and circumstances are likely to lead to capital controls. These predictions emerge clearly in period two, due to the simple solution available in this case: *ceteris paribus*, governments with fewer outside resources, x , or facing greater temptation to impose controls (in terms of a larger, potentially captive, capital tax base, K_1), are more likely to impose controls. Similar predictions emerge in period one, although the interaction between direct and indirect effects of x and K_0 in the signaling equilibrium blurs the impact of small changes in these two variables. Nonetheless, the effects of x and K_0 eventually dominate: free mobility prevails in period one as $x \rightarrow \infty$ or $K_0 \rightarrow 0$, whereas controls prevail as $x \rightarrow -\infty$ or $K_0 \rightarrow \infty$.

These predictions seem realistic. Although the parameter x could capture any of many factors that affect capital account policies, the interpretation we emphasize--that x represents revenues other than from capital taxation which the government may tap in the future--seems empirically appealing. Both casual evidence (showing more frequent use of capital controls in developing than in industrial countries--see Section 1), and evidence from panel studies (see, for instance, Alesina, Grilli, and Milesi-Ferretti, 1994), indicate that countries are more

likely to impose capital controls when their expected revenues from financial repression are high relative to expected revenues from other sources (here represented by x).¹⁹ Thus, our model's implication that a larger K_0 should provide stronger temptation to impose controls, must be read in a relative sense: developing countries are more likely to use capital controls, not because their stock of taxable capital is high in absolute terms but because it is high relative to other revenue sources they can tap.

B. Capital flows. Several important properties of the model's equilibrium should be noted. First, as long as $K_0 > 0$, a separating equilibrium prevails, whereby governments for which $\psi_1 = \psi_1(K_0, x) > 0$ impose controls at the beginning of period one and all remaining governments allow free capital mobility.²⁰ Figure 2 illustrates the equilibrium in this case, by plotting an illustrative curve ψ_1 (ignore the curve ψ_1^S and the point x^R , for the moment).

We have been unable to rule out the possibility of a nonmonotonic behavior of the curve ψ_1 (although we expect the curve to be decreasing in most plausible cases). In any case, the essence of Proposition 1 is that, even if the ranges of governments choosing $c_1 = R$ and $c_1 = F$ may not be connected, in equilibrium there will be enough probability mass attached to $c_1 = R$ at low values of x to make capital controls in period one an unfavorable signal of x , and hence of future policies. With this caveat, henceforth we shall refer to low x types as being more likely to impose controls in period one.

Next, observe that the profit-maximizing capital stock $K_1^*(\mu, K_0, F)$ in the high state $\mu_1 = \mu$ conditional on free capital mobility lies strictly above its restricted-mobility counterpart, $K_1^*(\mu, K_0, R)$ (the stocks are clearly both equal to zero in the low state $\mu_1 = 0$). This property clearly reflects the separating nature of the equilibrium: the observation of free capital mobility in

period one triggers a discrete upward revision in investors' beliefs over government types, relative to their prior beliefs, and therefore an *ex ante* increase in expected returns to K_1 . Symmetrically when capital controls are imposed in period one. The persistence of policies necessary for this result reflects the fact that low- x governments are more likely than high- x governments to impose controls in both periods.

The wedge $K_1^*(\mu, K_0, F) - K_1^*(\mu, K_0, R)$ affects the response of capital flows to policies. Since $K_1^*(\mu, K_0, F) > K_1^*(\mu, K_0, R)$ and $K_1^*(0, K_0, F) = K_1^*(0, K_0, R) = 0$, for all K_0 , then $E_1[K_1^*(\mu_1, K_0, F)] = \pi K_1^*(\mu, K_0, F) > \pi K_1^*(\mu, K_0, R) = E_1[K_1^*(\mu_1, K_0, R)]$, for all K_0 . Hence, there is always a nontrivial range of initial states K_0 , for which a policy of free capital mobility causes an expected inflow (i.e., $E_1[K_1^*(\mu_1, K_0, F)] > K_0$), even though capital controls would lead to a desired outflow averaged across states ($K_0 > E_1[K_1^*(\mu_1, K_0, R)]$). Intuitively, governments with few outside resources impose controls as their decision is dominated by welfare under the worst scenario ($\mu=0$, in our simple setup), while high x governments are influenced more evenly by the whole distribution of μ_t . Low x governments impose controls because of the large costs associated with possible outflows, notwithstanding the potential benefits of free capital mobility.

The model also predicts the circumstances in which the choice of an open capital account will more likely cause a capital inflow. The likely outcome depends on the strength of the signal provided by that policy. The improvement in investors' beliefs over types, upon observation of $c_1 = F$, is sharper (and hence an inflow is more likely), the lower was the prior likelihood of an open capital account and the greater is the extent of policy persistence across periods. Clearly, for investors to attribute value to these news, they must attach sufficient

importance to future policies: as (4) and (6) indicate, as the discount factor ρ becomes small, the signaling effect of policies vanishes, investment converges to its one-shot outcome, and a removal of binding controls on outflows always causes an outflow.

C. The role of asymmetric information. To clarify the role of asymmetric information in our model, consider the case where investors are informed of x at the beginning of period one. Clearly, there is no scope for signaling in this case: investors already know whether the host government will impose controls or not in period two at each K_1 . Desired period-one capital would then be independent of the regime (i.e., $K_1^*(\mu_1, K_0, R) = K_1^*(\mu_1, K_0, F)$), and a removal of binding controls on outflows would always cause an outflow. Thus, the possibility of an inflow following the removal of binding controls on outflows rests crucially, in our model, on the signaling role of policies.

Asymmetric information equilibria also exhibit “mimicking”: some governments exploit informational asymmetries to pool with higher x types and liberalize capital flows in period one, a policy they would not have adopted with symmetric information. To understand why this is true, consider the highest x (x^R , say, see Figure 2) *just* indifferent between controls and no controls in the asymmetric information case (thus, all types higher than x^R strictly prefer free capital mobility). With asymmetric information, x^R knows that if it imposes controls, investors will pool its type with types in a range with upper bound x^R (and hence reduce their desired investment), when forming their best guess of the host government’s type. Hence, aside from the benefits from trapping the given stock of capital onshore (which are identical with and without asymmetric information), with asymmetric information the type x^R also faces a signaling cost when imposing controls in period one. No such cost arises with

symmetric information: investors already know the host government to be of type x^R . Hence, if x^R is indifferent between controls and no controls under asymmetric information, x^R must strictly prefer controls under symmetric information. Combining this observation with the fact that the symmetric information case features a simple split between governments imposing controls in period one and governments not imposing controls, (see Figure 2, where $\psi_1^S(K_0, x)$ denotes the gains-from-controls function in the symmetric information case), then the types choosing free mobility with symmetric information form a strict subset of those choosing free mobility with asymmetric information.²¹ Thus, in our model, incomplete information about government attitudes toward capital mobility yields a bias toward liberal markets.

D. Extensions. The model of the previous sections is highly stylized, and several extensions could be considered. The main problem in pursuing some of these may be the loss of tractability: signaling models are notoriously hard to solve, and most of the signaling literature has resorted to simplifications such as quadratic loss functions, two-period or two-type models, etc., in order to obtain tractable solutions. In other cases, augmenting the model to endogenize some parameters may not justify the cost of blurring its message. This is likely to be the case, for instance, for more structural models of the motives and costs of capital controls to the extent that these yield reduced forms similar to those that we have simply assumed (whereby governments have an imperfectly known taste for domestic capital, but suffer a cost from imposing controls).

In some respects, our model is less restrictive than it may appear at first sight. The cost of controls ξ , for instance, could be allowed to vary across periods, to differ across

governments, or to be incurred only when controls are binding (e.g., to rise as a function of the gap between onshore and offshore returns). When the cost ξ is viewed as government-specific, the model's prediction that governments with minimal outside resources are more likely to impose controls on capital outflows must be viewed as a *ceteris paribus* prediction: governments less able (or willing) to tap outside revenues are more likely to impose controls than governments facing similar costs of imposing controls, but with easier access to outside revenues.

A positive cost ξ , however, is essential; otherwise the trade-off faced by governments in their policy decision disappears.²² Therefore, in situations where controls are seen as beneficial (for example, to insulate domestic markets from external shocks), other costs of disrupting capital mobility ought to be introduced in the model, for the government to face a meaningful decision problem.

Another simplifying assumption is that the capital stock invested onshore in period one remains intact until period two. When K_t is viewed as physical capital, this assumption is equivalent to that of no capital depreciation;²³ writing the capital controls' constraint as $K_t \geq K_{t-1}$, is also equivalent to assuming controls to be fully effective. Neither of these assumptions is very realistic. However, it is easy to extend the model by rewriting the controls' constraint as $K_t \geq (1-\delta)K_{t-1}$, and equations (2) to (4) with $(1-\delta)K_1$ in place of the stock K_1 inherited from period one. All qualitative results remain unchanged, as long as $\delta < 1$, that is, as long as capital does not depreciate fully from period to period, and controls are at least partially effective. In the degenerate case of $\delta=1$, investors need not be concerned with capital controls: their principal is fully lost (or fully transferrable offshore) in a single period

anyway. In the more realistic case of $0 < \delta < 1$, instead, controls would be effective only in the short run. This is sufficient, however, to make investors afraid that a stock $(1 - \delta)K_1$ may remain trapped onshore earning a low return, leading to a signaling equilibrium of the type studied above.

The payoffs to a more general model may be significant but tractability problems overwhelming, when extending the analysis to a multi-period model. It is clear from Section 3.B that our model has a recursive nature, and that government and investors would face a very similar problem in each period of a repeated game of duration T . However, whereas we could exploit in our solution for period one the semi-closed form solution available for period two, that strategy would only help for period $T-1$ in a multi-period model. Nevertheless, the two-period case has implications for some results one may anticipate for the multi-period case.

First, in our two-period model, while a true “liberalization” (in the sense of a removal of capital controls following their endogenous imposition) can occur in period two, a period-one liberalization would be conditional on inheriting a regime of restricted capital mobility from period zero. Clearly, a multi-period extension could produce richer patterns of liberalizations and re-impositions of controls, particularly when combined with a more general treatment of technology. In this respect, allowing for a continuous distribution for the technology shocks would needlessly complicate the model, but allowing for serially correlated shocks would have interesting implications.²⁴ For instance, the stronger the correlation of the shocks, the more information on future tax revenues the government obtains from current shocks. A high correlation and a high value of μ , would virtually eliminate the need for

controls in response to a positive technology shock: there is no need to insure against bad states of nature if such states can be ruled out a priori; conversely in response to the arrival of bad news on future productivity.

We expect policies to respond to the same incentives in a multi-period model: governments with low outside resources, who expect a narrow tax base in the future (because they expect a series of bad productivity shocks) would initially try to trap capital onshore by imposing controls. Subsequent arrival of good news on future tax revenues, in the form of a large, highly correlated technology shock, would make these governments liberalize capital flows.

Finally, a multi-period model may make the impact of reputational effects on capital flows even more dramatic. As discussed above, there are governments who would impose restrictions if their type were known, but allow free capital mobility under asymmetric information in order to be perceived as more likely to adopt liberal policies in the future. The intuition from our two-period and other signaling models suggest that this reputational effects could be long-lived.

5. Concluding Remarks

We have presented a model in which governments can use policies affecting capital mobility to signal a favorable future fiscal situation. In our model, governments with the most to lose from a capital outflow are more likely to fall prey to the temptation of trapping capital onshore; governments with less to gain from a capital inflow are more likely to withstand such temptation and to allow free capital mobility. Investors recognize these

incentives and the persistence of policies affecting capital flows: governments liberalizing capital flows today are more likely not to impose controls tomorrow, and *vice versa*.

Ironically (but intuitively), governments with less need for a large tax base are more likely to experience a capital inflow. These predictions are consistent with the observed experience of a number of countries that have liberalized their capital accounts. Our model suggests to view those policy shifts as enhancing the credibility of those countries as hosts for foreign investment. A desired inflow upon liberalization, the model suggests, was fully consistent with a desired outflow conditional on a repressed capital account.

While capital controls are motivated in our model by their role in broadening the domestic tax base, the model's insight should extend to related problems. The main alternative would be to explore the role of capital controls to defend an exchange rate target. We expect this motive to lead to similar predictions on the response of investment to capital controls policies. Investors fear being trapped onshore earning a low rate of return and would welcome with an inflow news suggesting lower likelihood of controls in the future. Governments with less to lose from a balance of payment crisis would try to signal their commitment to free capital mobility by exposing themselves to greater chances of a crisis. In so doing, they would differentiate themselves from those governments that cannot afford to take chances, thus validating the signaling content of the liberalization.

Table 1. Time structure of the model

$t=0$: - Inherited stock of capital: K_0 .

$t=1$: - x is revealed to the government.

- Government chooses $c_1 \in \{F, R\}$.
- $\mu_1 \in \{0, \mu\}$ is realized and revealed.
- Public chooses K_1 (with $K_1 \geq K_0$ if $c_1=R$).
- Production takes place, profits are collected.

$t=2$: - x is revealed to the public.

- Government chooses $c_2 \in \{F, R\}$.
- $\mu_2 \in \{0, \mu\}$ is realized and revealed.
- Public chooses K_2 (with $K_2 \geq K_1$ if $c_2=R$).
- Production takes place, profits are collected, taxes are paid and transformed into public goods (together with x).

Appendix

Proof of Proposition 1: The proof is by contradiction. It verifies that under the converse assumption $\psi_1(K_0, x)$ falls with x for all K_0 and x . Write $K_1^F \equiv K_1^*(\mu, K_0, F)$, $K_1^R \equiv K_1^*(\mu, K_0, R)$, and $K_2^* \equiv K_2^*(\mu_2)$. Let $x_2^T(K_1)$ be the unique type x indifferent between controls and no controls at the beginning of period two, given K_1 , and recall that π and $1-\pi$ are the probabilities that $\mu_t = \mu$ and $\mu_t = 0$, respectively, which may depend on $\{\mu_{t-1}, \mu_{t-2}, \dots\}$. We have three cases defined by the relationship between K_0 and μ :

1. low K_0 (or high μ): $K_0 \leq K_1^F \leq K_1^R$.

a. $x \leq x_2^T(K_0)$ (this is the range of x that would impose controls in period two at K_0):

$$(A1) \quad \psi_1(K_0, x) = \pi \rho^2 E_1 \left[W(\tau \cdot \max\{K_1^R, K_2^*\} + x) - W(\tau \cdot \max\{K_1^F, K_2^*\} + x) - \frac{\xi}{\rho} \right] \\ + (1-\pi) \rho^2 E_1 \left[W(\tau \cdot \max\{K_0, K_2^*\} + x) - W(\tau \cdot K_2^* + x) - \frac{\xi}{\rho} - \xi \right]$$

with expectations taken over μ_2 , conditional on μ_1 .

b. $x_2^T(K_0) \leq x \leq x_2^T(K_1^F)$:

$$(A2) \quad \psi_1(K_0, x) = \pi \rho^2 E_1 \left[W(\tau \cdot \max\{K_1^R, K_2^*\} + x) - W(\tau \cdot \max\{K_1^F, K_2^*\} + x) - \frac{\xi}{\rho} \right] \\ + (1-\pi) \rho^2 E_1 \left[W(\tau \cdot K_2^* + x) - W(\tau \cdot K_2^* + x) - \frac{\xi}{\rho} \right]$$

c. $x_2^T(K_1^F) \leq x \leq x_2^T(K_1^R)$:

$$(A3) \quad \psi_1(K_0, x) = \pi \rho^2 E_1 \left[W(\tau \cdot \max\{K_1^R, K_2^*\} + x) - W(\tau \cdot K_2^* + x) - \frac{\xi}{\rho} - \xi \right] \\ + (1-\pi) \rho^2 E_1 \left[W(\tau \cdot K_2^* + x) - W(\tau \cdot K_2^* + x) - \frac{\xi}{\rho} \right]$$

d. $x_2^T(K_1^R) \leq x$:

$$(A4) \quad \psi_1(K_0, x) = \pi \rho^2 E_1 \left[W(\tau \cdot K_2^* + x) - W(\tau \cdot K_2^* + x) - \frac{\xi}{\rho} \right] \\ + (1-\pi) \rho^2 E_1 \left[W(\tau \cdot K_2^* + x) - W(\tau \cdot K_2^* + x) - \frac{\xi}{\rho} \right]$$

2. intermediate K_0 (or intermediate μ): $K_1^F \leq K_0 \leq K_1^R$.

a. $x \leq x_2^T(K_1^F)$: same as (A1).

b. $x_2^T(K_1^F) \leq x \leq x_2^T(K_0)$:

$$(A5) \quad \psi_1(K_0, x) = \pi \rho^2 E_1 \left[W(\tau \cdot \max\{K_1^R, K_2^*\} + x) - W(\tau \cdot K_2^* + x) - \frac{\xi}{\rho} - \xi \right] \\ + (1-\pi) \rho^2 E_1 \left[W(\tau \cdot \max\{K_0, K_2^*\} + x) - W(\tau \cdot K_2^* + x) - \frac{\xi}{\rho} - \xi \right]$$

c. $x_2^T(K_0) \leq x \leq x_2^T(K_1^R)$: same as (A3).

d. $x_2^T(K_1^R) \leq x$: same as (A4).

3. high K_0 (or low μ): $K_1^F \leq K_1^R < K_0$.

a. $x \leq x_2^T(K_1^F)$: same as (A1).

b. $x_2^T(K_1^F) \leq x \leq x_2^T(K_1^R)$: same as (A5).

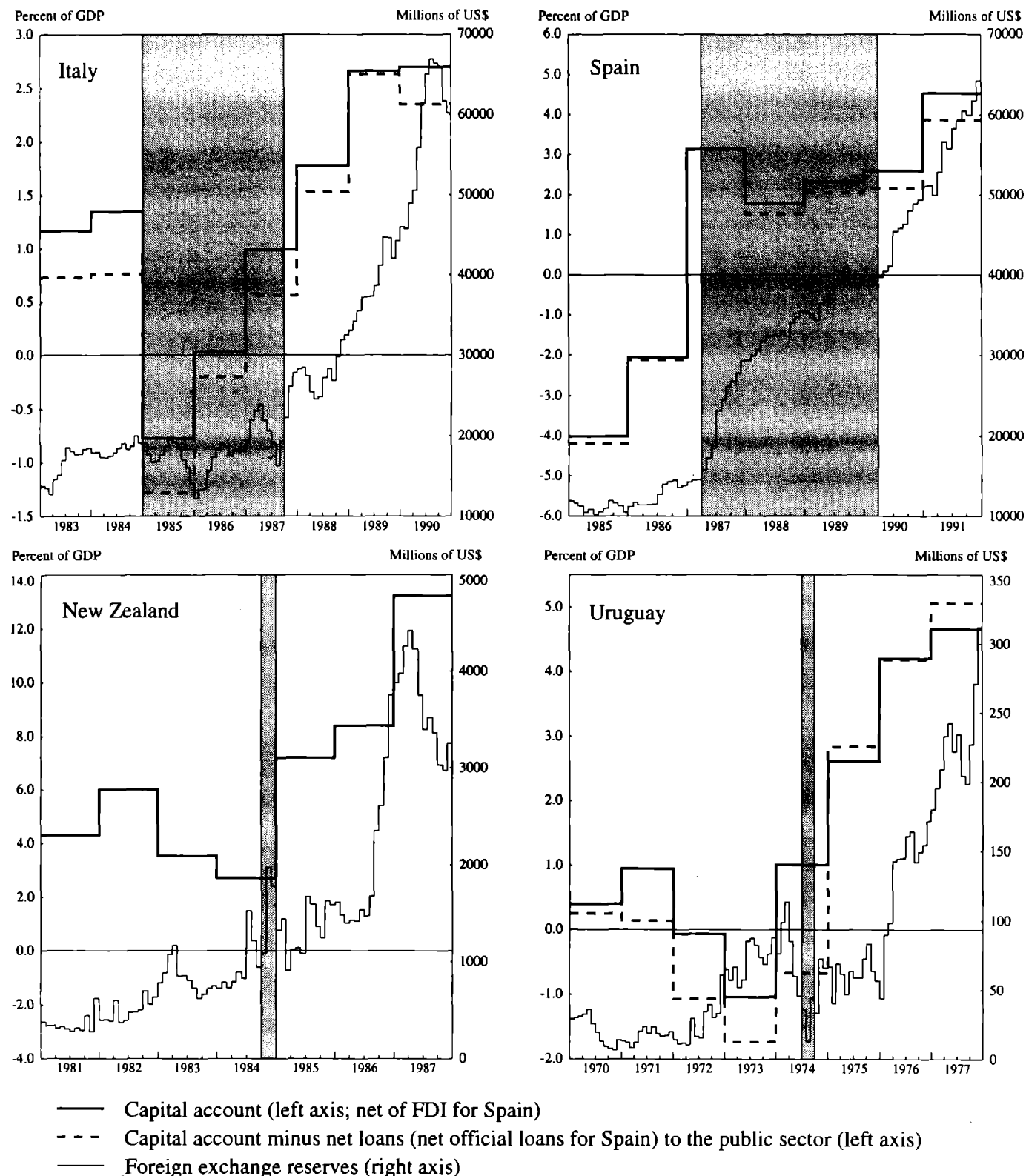
c. $x_2^T(K_1^R) \leq x \leq x_2^T(K_0)$:

$$(A6) \quad \psi_1(K_0, x) = \pi \rho^2 E_1 \left[W(\tau \cdot \max\{K_0, K_2^*\} + x) - W(\tau \cdot K_2^* + x) - \frac{\xi}{\rho} - \xi \right] \\ + (1 - \pi) \rho^2 E_1 \left[W(\tau \cdot \max\{K_0, K_2^*\} + x) - W(\tau \cdot K_2^* + x) - \frac{\xi}{\rho} - \xi \right]$$

d. $x_2^T(K_0) \leq x$: same as (A4).

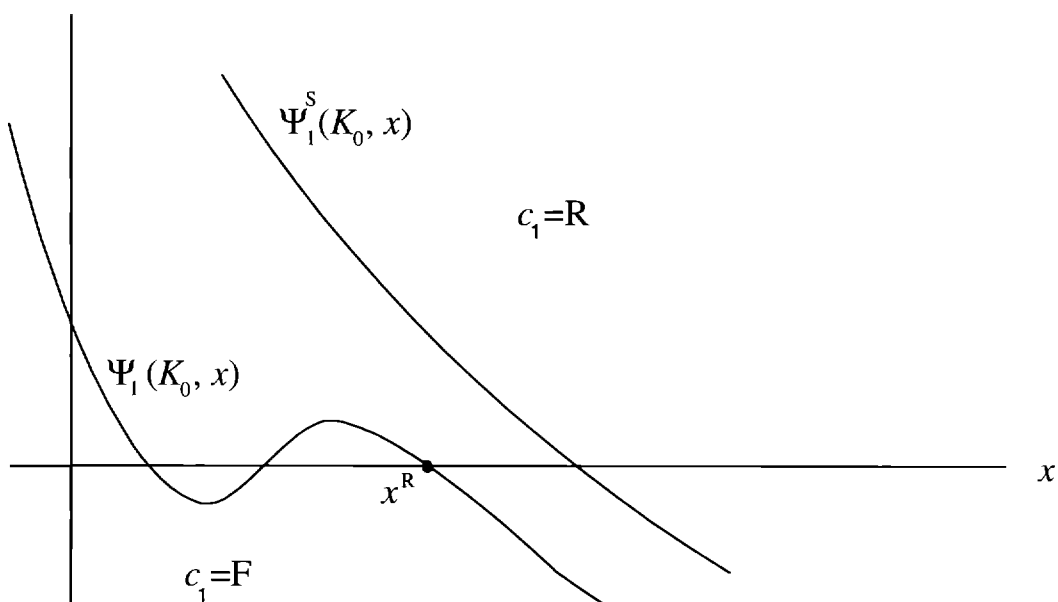
Now, by (4) and (5), if $\gamma^F \geq \gamma^R$, then $K_1^F \leq K_1^R$. Then $E_1[W(\cdot | c_1 = R)] \geq E_1[W(\cdot | c_1 = F)]$ for all ranges of x and for all cases 1 to 3, with strict inequality over ranges with positive probability. Furthermore, the difference between the two sides of the inequality is decreasing in x , due to the concavity of $W(\cdot)$, which implies that sufficiently low x 's impose controls in period one, while higher x 's do not. Since this is also true in period one, then $\gamma^F < \gamma^R$, a contradiction. \square

Figure 1
Capital account and foreign exchange reserves: Italy, Spain, New Zealand and Uruguay



Shaded areas indicate periods of main liberalization measures. Capital flows include errors and omissions. Sources, various issues of: IMF, International Financial Statistics; Banco Central del Uruguay, Indicadores de la Actividad Económico-Financiera; Banca d'Italia, Rapporto Annuale; Banco de España, Boletín Estadístico; The World Bank, World Debt Tables; and data provided by the New Zealand Department of Finance.

Figure 2
Equilibrium Capital Controls Policies in Period One



Endnotes

¹ See, for instance, Obstfeld (1984) and Bacchetta (1992).

² Giavazzi and Spaventa (1990), Williamson (1991), Mathieson and Rojas-Suarez (1993), and Labán and Larraín (1993), among others, review a number of such episodes.

³ As documented in Figure 1, (net) capital flows minus (net) loans to the public sector surged beginning in 1986-87. (Although Italy does not classify capital flows by characteristics of foreign investors, flows from official agencies and other governments should be almost entirely included among foreign loans to the public sector.)

⁴ Although the hands-off approach following the liberalization limits data availability, net flows to the private sector were noted as growing faster and to a higher level, than those to the public sector (see New Zealand, Reserve Bank, January 1986 and July 1986 Bulletins and OECD, 1987). Even flows to the public sector originated wholly at market terms, mainly through sale of Government Stocks and Kiwi Bonds.

⁵ See Banda and Santo (1983), de Melo (1985), and Pérez-Campanero and Leone (1991) for reviews of the Uruguay episode.

⁶ Liberalization of inflows affected mainly FDI in selected sectors; hence, to avoid overstating our case, since the FDI growth may reflect the lifting of these restrictions, Figure 1 reports data net of FDI.

⁷ Alesina, Grilli, and Milesi-Ferretti (1994) list four main motives for capital controls (i. limit volatile capital flows; ii. maintain the domestic tax base; iii. retain domestic savings, and iv. sustain structural reform) and study their determinants across countries and over time. They identify in governments' attempt to collect revenue from financial repression the main

motive for controls. See also Giovannini and de Melo (1993) and Aizenman and Guidotti (1994).

⁸ Alesina and Tabellini (1989), for instance, include the loss of capitalists' electoral support to governments that impose controls among the political costs of capital controls.

⁹ Allowing for consumers' risk aversion, for instance, Lucas (1987) and Mendoza (1991) estimate a loss of utility from inability to smooth consumption through international diversification in the order of .10 percent. Backus, Keohe, and Kydland (1990) report similar results.

¹⁰ See Bartolini and Drazen (1996) for a model (with a different information structure) where government policies respond to changes in external conditions.

¹¹ As suggested by a referee, our model could also be interpreted as a model of international investment in physical capital, where the multi-period horizon reflects the gestation lag necessary for direct investment to become fully productive.

¹² The issues that arise when the government is unable to pre-commit to a fixed tax rate were studied by Fischer (1980). We simplify the model by assuming commitment to a fixed tax rate at time zero.

¹³ Exponential utility would satisfy all these regularity conditions.

¹⁴ See for instance, Rogoff (1987), where the cost of breaking a no-inflation commitment is modeled as independent of the inflation rate itself, and Barro (1986), where a government's cost is zero for zero inflation and prohibitive for positive inflation.

¹⁵ Little is lost with this assumption, since governments' utility is already a function of K_t and x_t , and could be redefined net of other costs that depend on these variables (e.g., as a function

of the gap between offshore and onshore returns). Explicit role for residents' welfare could also be included, by defining government's welfare as utility from public consumption plus consumers' utility from domestic output, produced with onshore capital and a fixed stock of labor.

¹⁶ We focus on controls on capital *outflows*. As it will become clear later, in this model there are no incentives to restrict *inflows*.

¹⁷ To see this, note that $\beta K_1^{\beta-1}$ falls with K_1 from infinity to zero; that γ^c is increasing in K_1 , given K_0 , and for both $c_1=R$ and $c_1=F$ (since $\psi_2(K_1, x)$ rises with K_1 --see Section 3.A); and that the term in square brackets is positive and continuous (including where (1) holds identically with $\mu_2=\mu$ and $K_2=K_1$, and I' switches from zero to one).

¹⁸ In particular, it does not seem possible to rule out, in general, multiple intersections between the function $\psi_1(K_0, x)$ (as this goes from $+\infty$ for $x \rightarrow -\infty$, to $-\rho\xi$ for $x \rightarrow +\infty$) and the horizontal axis.

¹⁹ See also Gordon and Levinsohn (1989) and Giovannini and de Melo (1993), who argue that financial repression in developing countries dominates other forms of taxation that are too costly to organize and administer. Value-added or consumption taxes, for instance, require sophisticated methods of assessment, border controls, and other measures that may simply be beyond the reach of many poor countries.

²⁰ When $K_0=0$, all governments (other than, trivially, the type $x = -\infty$) allow free mobility, a pooling equilibrium prevails in period one, $K_1^*(\mu_1, K_0, F) = K_1^*(\mu_1, K_0, R)$, and signaling plays no role in the ensuing capital flow. We focus here on the case of $K_0 > 0$.

²¹ The argument showing that ψ_1^S is decreasing in x is similar to that for Proposition 1: with symmetric information, there is no role for signaling, and $K_1^*(\mu_1, K_0, R) = K_1^*(\mu_1, K_0, F)$.

Then, controls can only increase K_1 and K_2 ; hence, low x types, who benefit more from a larger tax base, are more inclined to impose controls in all periods.

²² All governments would impose controls in period two and, lacking signaling or direct cost of doing otherwise, also in period one.

²³ When K_t is regarded as a financial claim on returns from physical capital, the same assumption is equivalent to that of no default risk.

²⁴ In our two-period model this extension would only require to specify the transition probabilities for the technology shocks as conditional on previous states, e.g.,

$\pi^\mu \equiv \Pr(\mu_t = \mu \mid \mu_{t-1} = \mu)$, $\pi^0 \equiv \Pr(\mu_t = \mu \mid \mu_{t-1} = 0)$, with $1 - \pi^\mu$ and $1 - \pi^0$ defined accordingly; then, $\pi^\mu > 1/2 > \pi^0$ yields positively correlated shocks. All results would remain qualitatively unchanged.

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